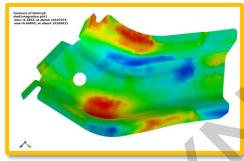


WORKSHOP ENVYO®: MAPPING AND DATA MANAGEMENT ALONG THE SIMULATION PROCESS CHAIN

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AGENDA

- "Historical" Overview
- Workflow
- Mapping Capabilities
- Example
- Future Plans
- Questions & Answers



"Historical" Overview

- In 2011, with the start of the government funded research project T-Pult, first implementations were made to enhance the existing tool DYNAmat with mapping capabilities for BEAM -> SHELL mapping as well as to consider CT-scan data.
- Further inhancements led to the consideration of fiber orientations gained from draping simulations with *MAT_249 (*MAT_REINFORCED_THERMOPPLASTIC) on shell meshes with the ORIENTATION -> SHELL capability.
- Several material models for draping simulations (*MAT_034, *MAT_234 & *MAT_235) were considered for orientation mapping within the government funded research project SWIM-RTM.
- In 2013, the mapping capabilities were removed from the Fortran based DYNAmat – tool and transferred to an independet C++ program.



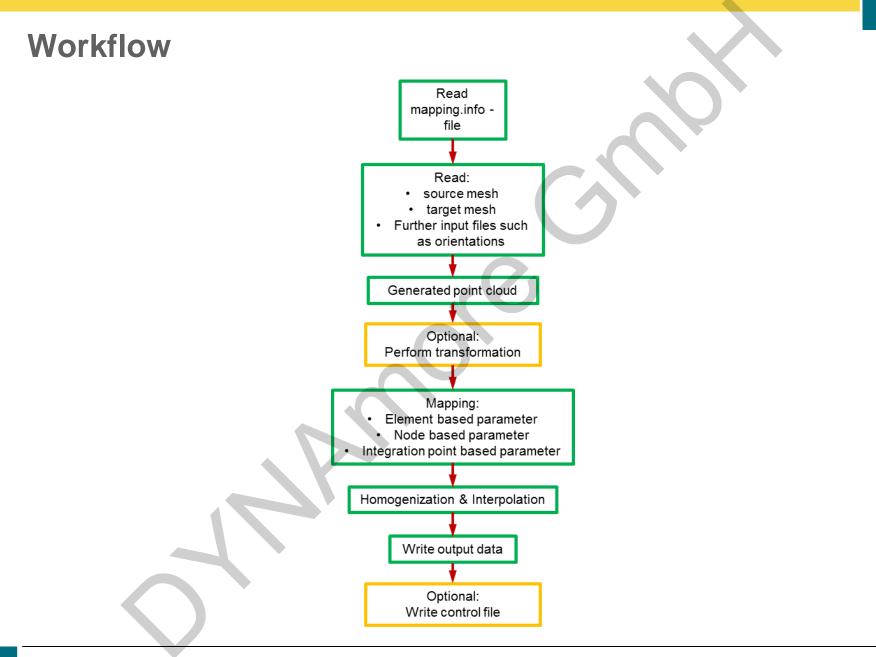
"Historical" Overview

- several names existed "Fibermap" and "DYNAmap" were the most common ones.
- with the start of the government funded research project ARNEA2036 in 2014, further software tools such as PAM-Crash, PAM-RTM, FiberSim can be considered within the mapping.
- a link to the HDF5 binary data format has been implemented.
- in 2015, a lot of work went into the consideration of fiber orientations as well as resinuous areas which can be identified with multi-layer draping simulations.
- enhancements were made towards the homogenization of stiffness parameters for *MAT_157 for short fiber reinforced composites.

"Historical" Overview

- in 2016, the consideration of eff. plastic strain resulting from a forming simulation for damage estimation in the GISSMO *MAT_ADD_EROSION failure and damage model has bee implemented.
- results from forming simulations using shell meshes can be used to generate solid meshes for springback analysis and thickness post-processing.
- a tool to generate vector files for the post-processing of various spring back analysis as been implemented.
- the mapping tool is officially named Envyo[®] is introduced to the public at the 14th German LS-DYNA User's Meeting in Bamberg, Germany.





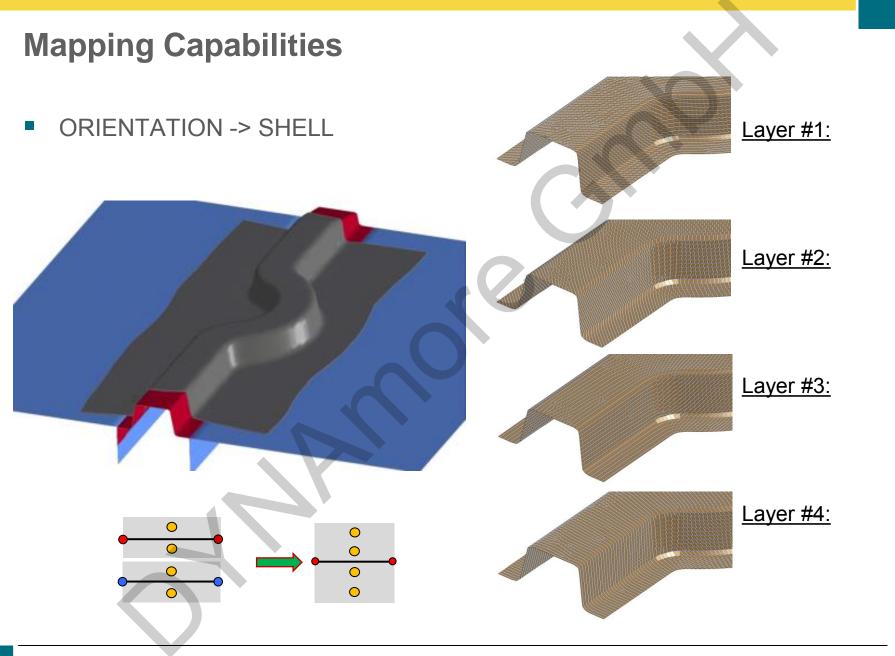


- ORIENTATION -> SHELL
- ORIENTATION -> ALE_MESH
- SHELL -> STACKED_SHELL
- SOLID -> SOLID
- STACKED_SHELL -> SOLID
- BEAM -> ALE_MESH
- SHELL -> SOLID
- SHELL -> THICK_SHELL
- STACKED_SHELL -> STACKED_THICK_SHELL
- SHELL -> SHELL
- SHELL -> SOLID (GENERATION)
- MOLDFLOW -> SHELL
- MOLDFLOW -> SOLID
- MOLDFLOW -> SHELL (with

plasticity curve interpolation)

- Moldflow visualization
- CT-Scan -> SHELL
- CT-Scan Visualization
- CT-Scan -> Through Thickness
 Curves
- MOLDFLOW -> Through Thickness Curves
- MOLDFLOW3D -> Through Thickness Curves
- HDF5-Input
- Springback Analysis



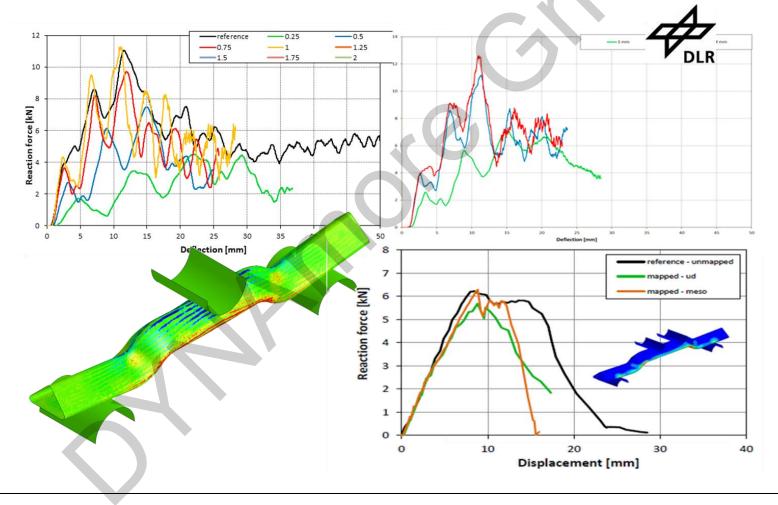




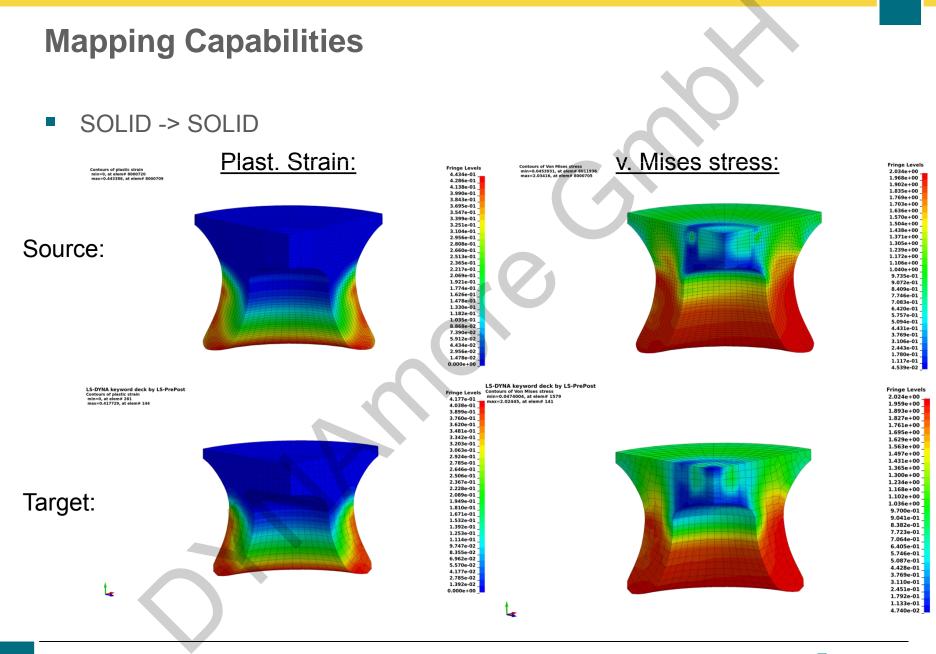




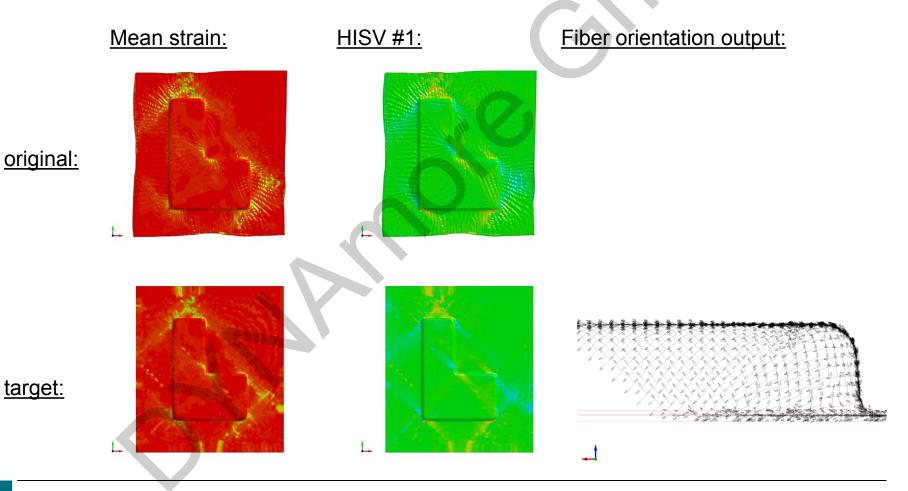
SHELL -> STACKED_SHELL

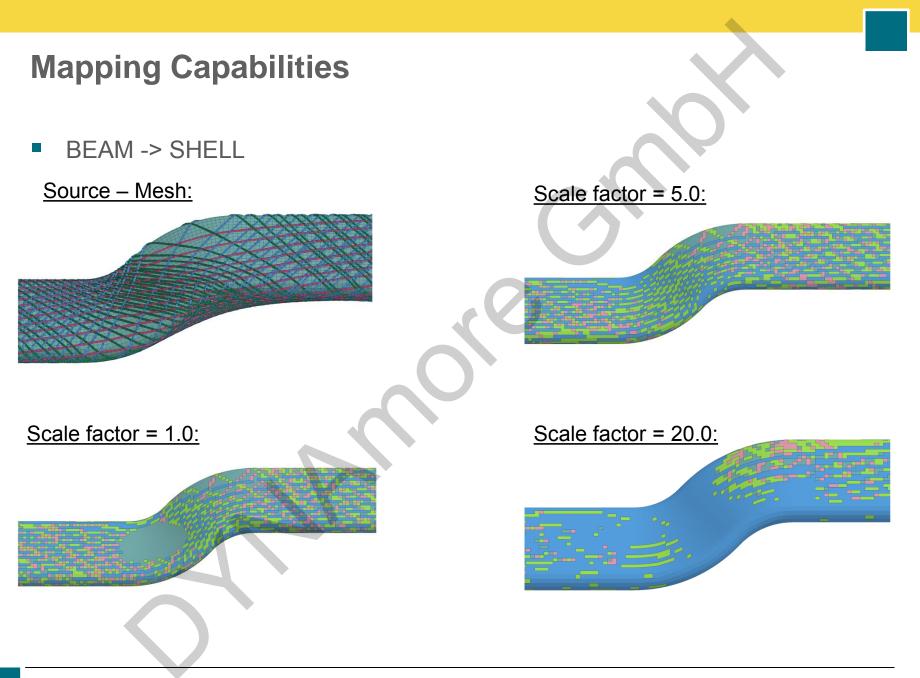






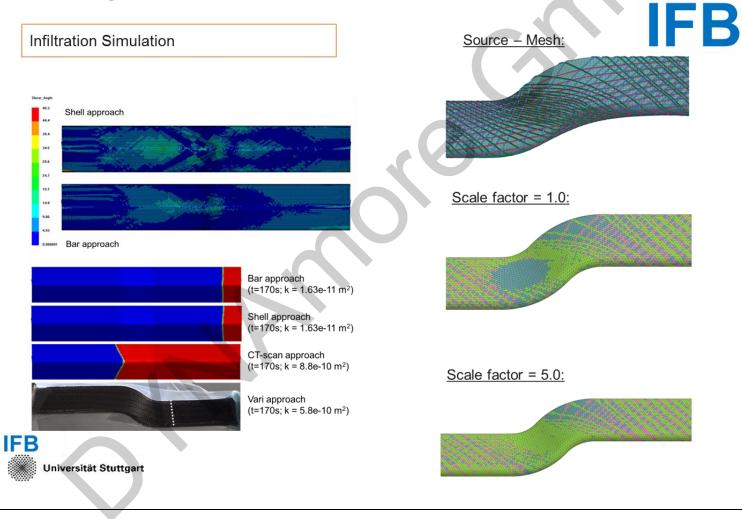
STACKED_SHELL -> SOLID







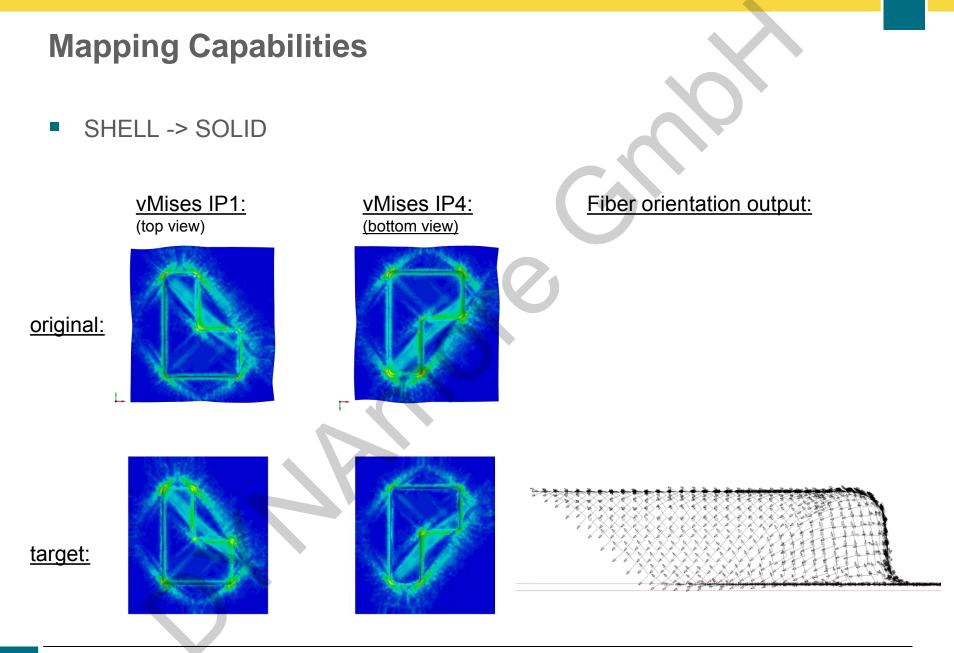
BEAM -> SHELL



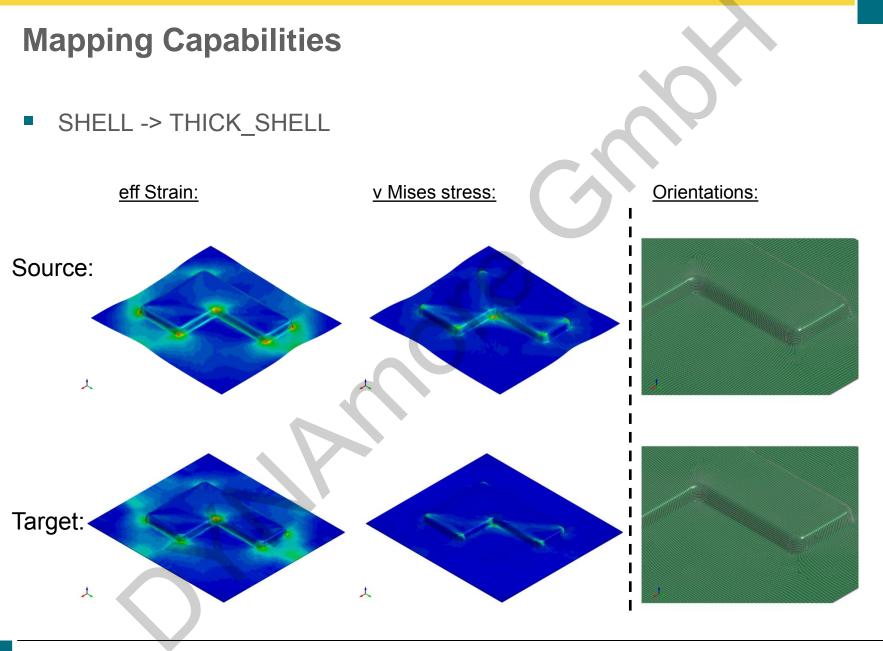


BEAM -> ALE_MESH

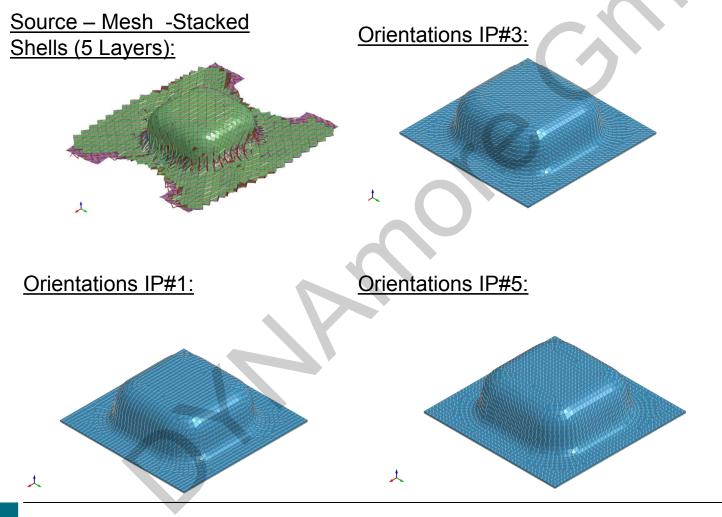




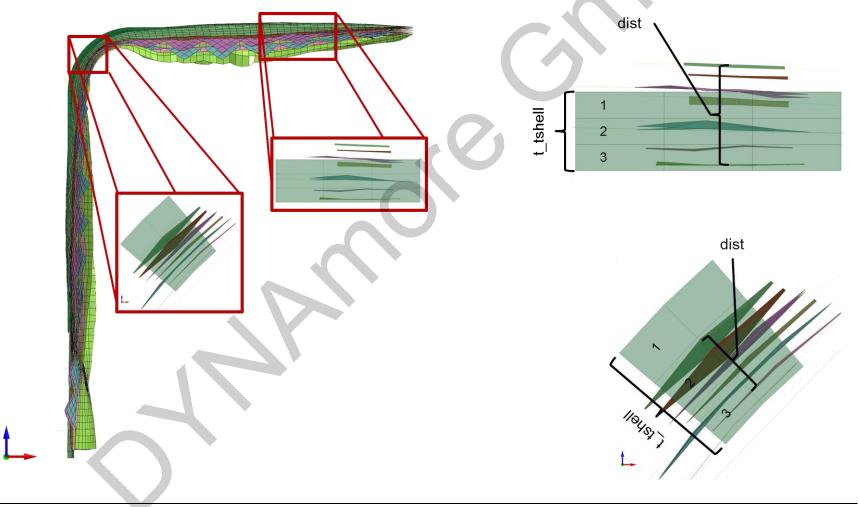




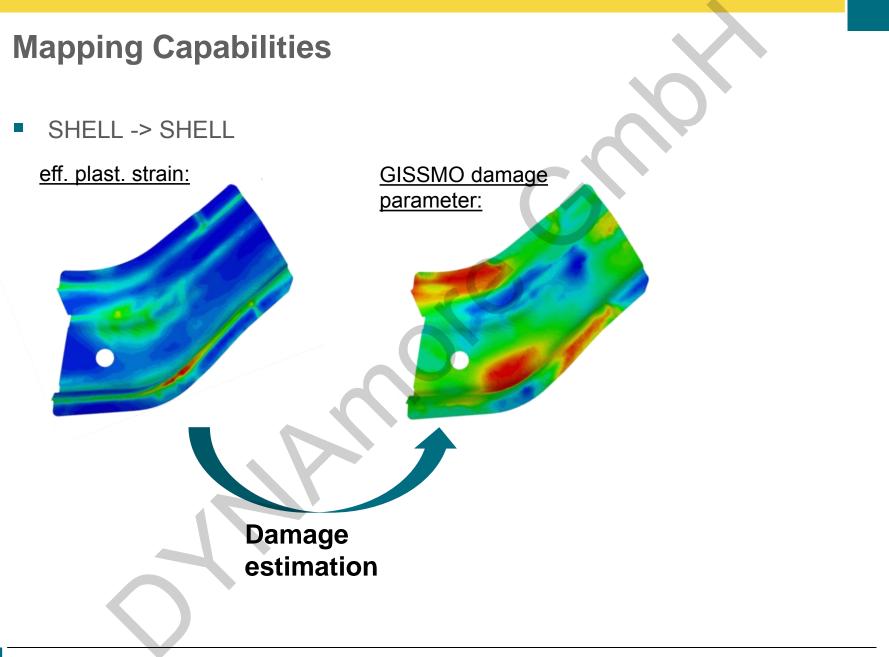
STACKED_SHELL -> STACKED_THICK_SHELL

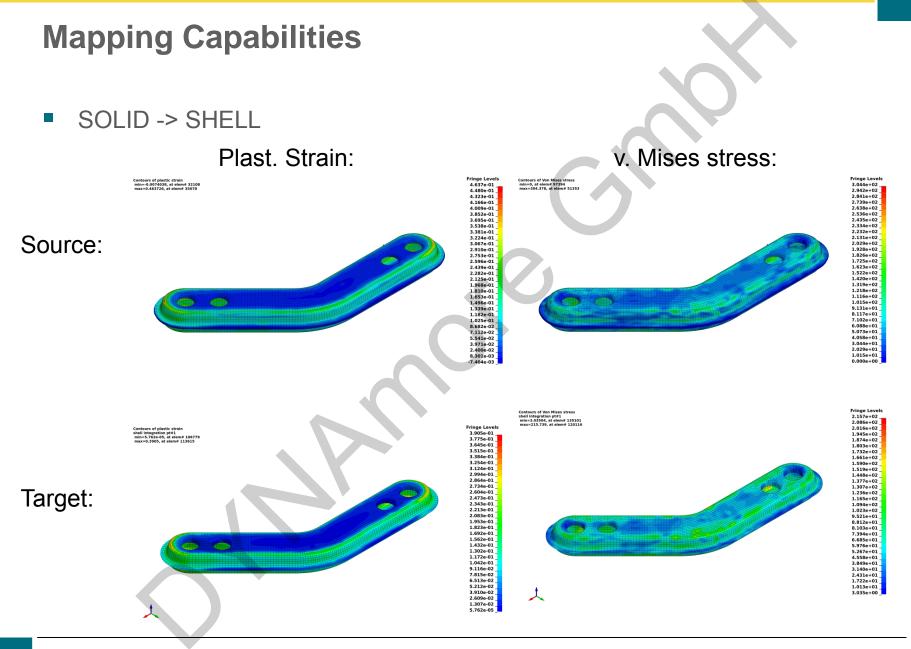


STACKED_SHELL -> STACKED_THICK_SHELL







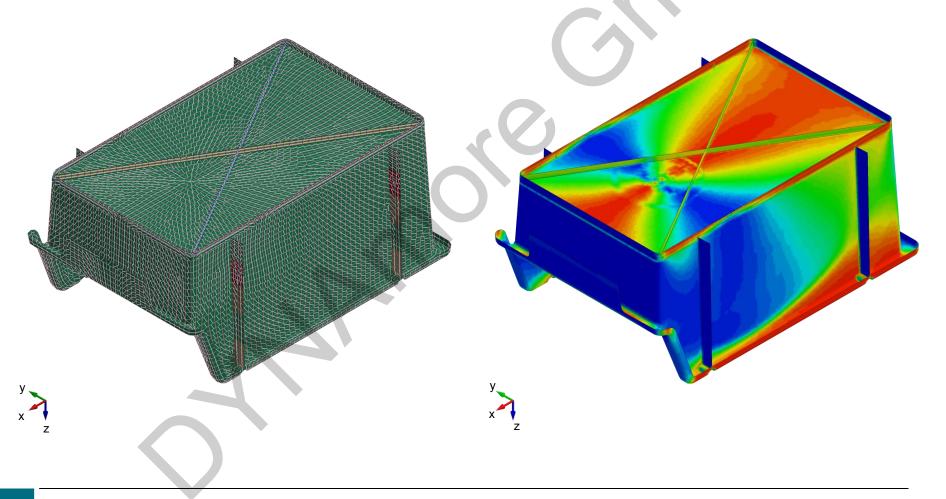


SHELL -> SOLID (GENERATION)



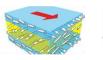


MOLDFLOW -> SHELL

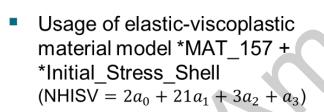




- MOLDFLOW -> SHELL (with plasticity curve interpolation)
 - Mapping (Moldflow/Moldex -> Shell) and homogenization for SFRP – components

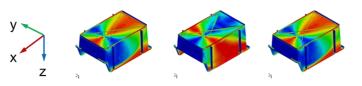






CAR	D 1	eid	nplane	nthick	nhisv	ntensor	large	nthint	nthhsv
CAR	D 2	t	sigxx	sigyy	sigzz	sigxy	sigyz	sigzx	eps
CAR	D 3	hisv1=q ₁	hisv2=q ₂	#3=C ₁₁	#4=C ₁₂	#5=C ₁₃	#6=C ₁₄	#7=C ₁₅	#8=C ₁₆
CAR	D 4	#9=C ₂₂	#10=C ₂₃	#11=C ₂₄	#12=C ₂₅	#13=C ₂₆	#14=C ₃₃	#15=C ₃₄	#16=C ₃₅
CAR	D 5	#17=C ₃₆	#18=C ₄₄	#19=C ₄₅	#20=C ₄₆	#21=C ₅₅	#22=C ₅₆	#23=C ₆₆	

Flag	Description	Variables	# 2	
a_0	Material directions	<i>q</i> ₁ , <i>q</i> ₂		
a_1	Anisotropic stiffness	Cij	21	
a_2	Anisotropic constants	r_{00}, r_{45}, r_{90}	3	
a_3	Stress-strain Curve	LCSS	1	



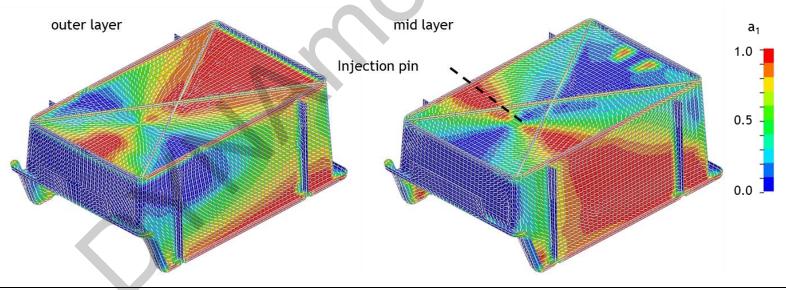


MOLDFLOW -> SHELL (with plasticity curve interpolation)

Orientation tensor 2nd order a: Mapped from process simulation as

- eigenvectors q_i (main fiber directions)
- eigenvalues a_i (orientation probability)

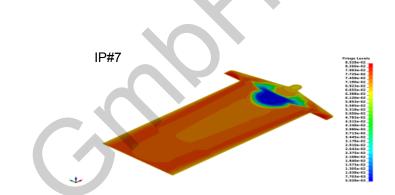


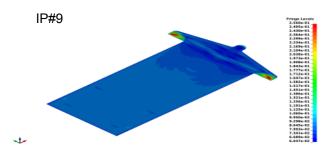


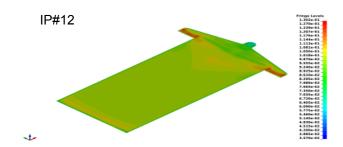
 a_2q_2

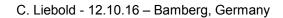
 a_1q_1

Moldflow visualization

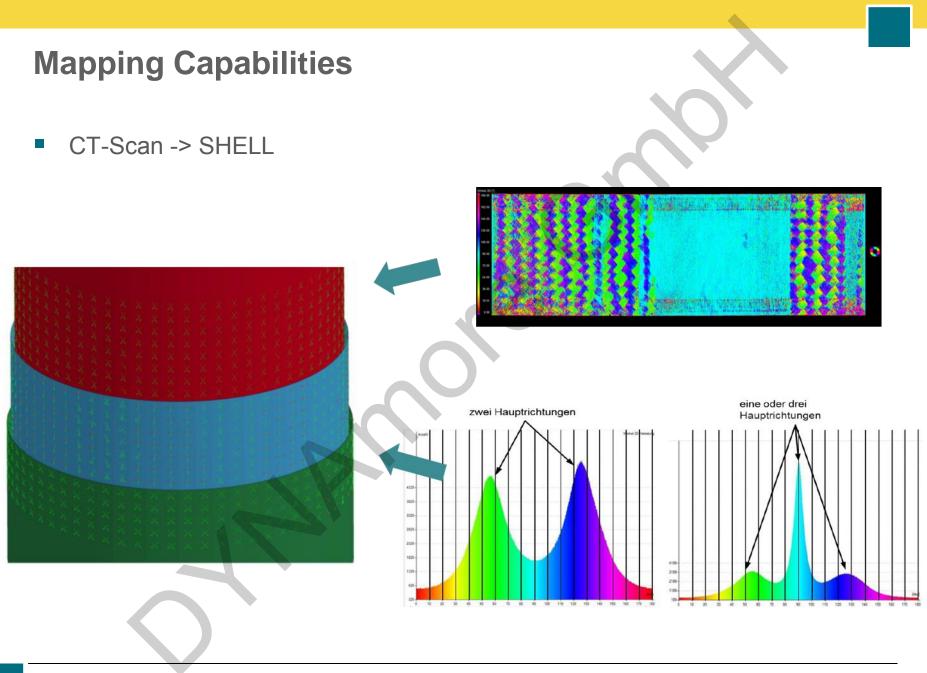








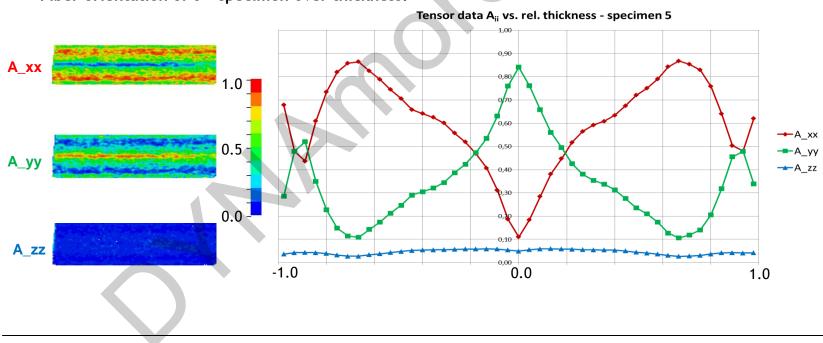
MORE

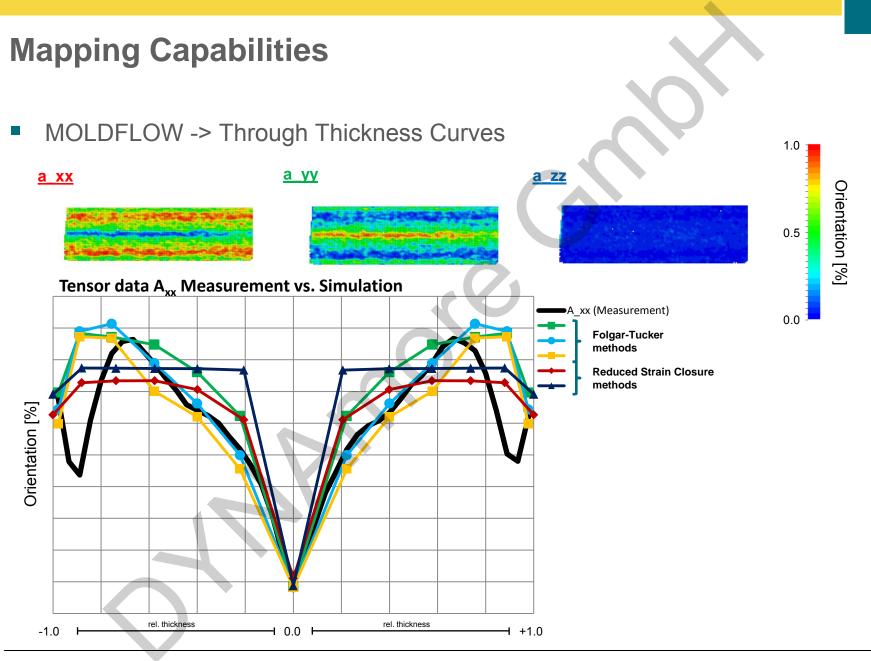




CT-Scan Visualization

- CT-Scan -> Through Thickness Curves
- Fiber orientation of 0°- specimen over thickness:

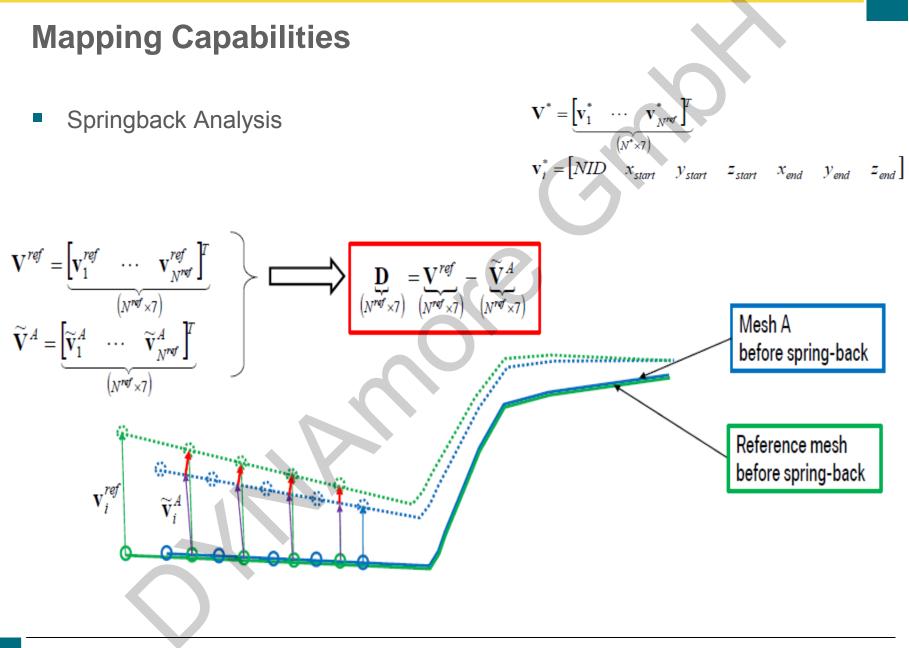






- HDF5-Input
 - A platform independent, HDF5 data storage container is defined within the ARENA2036 project, allowing to access and track simulation results from other partners within a defined project.
 - This is available for different FE solvers an will be extended as needed

7	HDFView 2
<u>File</u> <u>Window</u> <u>T</u> ools <u>H</u> elp	
Recent Files /home/cl/Projekte/FuE_ARENA2036/00_Process_Chain_HDF5/00_new	.structur/Projekt_Tunnelbruecke.h5
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🕈 📹 000_ProcessStatus	Table M
status_overview	
► C10_PreliminaryDesign	
← C1 020_Optimization	Description
🗢 🗀 030_ProcessSimulation	Description 0 PRE1_Draping_FiberSim_20150907_122153
🕈 🚍 040_Mapping	1 OPT1_Layup_Nastran_20150907_122159
← C MAP1_Map2RTM	2 PR01_Braiding_esi-pc_20150907_122204 3 MAP1_Map2RTM_esi-pc_esi-rtm_20150907_122210
🕈 📹 MAP2_Map2Structural	4 MAP2_Map2Structural_lesi-pc_lsdyna_20150907_122213
esi-pc_lsdyna	
e 🗑 20150907_122213	
OUD_SOURCE: Generisches_Bauteil_Flechtsim_V3_RESULT_1.pc	
← 🎱 001_TARGET: Target-Flechtkern.k	
🗢 🇀 010_RESULT: Orientations_mapped_from_SHELL.key	
← 🎦 999-MappingCommand: mapping_info_Map2Structural.in	



Example

\$#
\$# Main mapping definition
\$#
FIBERMAP=MOLDFLOW-SHELL(PLASTICITY_CURVE-GEN)
\$#
\$# Activate transformation
\$#
TRANSFORMATION=NO
SourceUnitSystem=kg-m-s
TargetUnitSystem=kg-mm-ms
\$#
\$# In- and output meshes
\$#
SourceFile=MOLDFLOW_SOURCE.key
TargetFile=TARGET_LS-DYNA.key
MappingResult=FILE_FOR_STRUCTURAL_ANALYSIS.key
OrientationFile=MOLDFLOW-ORIENTATIONS.xml
SectionFile=SECTION_CARDS.key



Example

\$#-----Target – Properties \$#-----NumberOfTARLayers=5 NumberOfTARInPlaneIPs=4 MapStress=YES TargetThickness=2.5 MapMainDir=NO \$#-----\$# Mapping-Options \$#-----ALGORITHM=ClosestPoint SORT=BUCKET TargetMaterialModel=157 HomogenizationMethod=Mori-Tanaka ClosureApproximation=hybrid E11F= E22F= RHOF= PRBAF= PRCBF=

G12F= EM= RHOM= PRM= AspectRatio= FiberVolumeFraction= InclusionShape=Spheroidal



Example

\$#
\$# Define Curve Input
\$#
NumberOfCurveFiles=3
CurveFileName#1=0deg_curves.inc
\$#
\$# Strain Rate Info
\$#
NumberOfDirections=3
Direction#1=0
NumberOfStrainRates=4
StrainRate#1=
StrainRate#1Direction#1=995
StrainRate#1Direction#2=45995
StrainRate#1Direction#3=90995

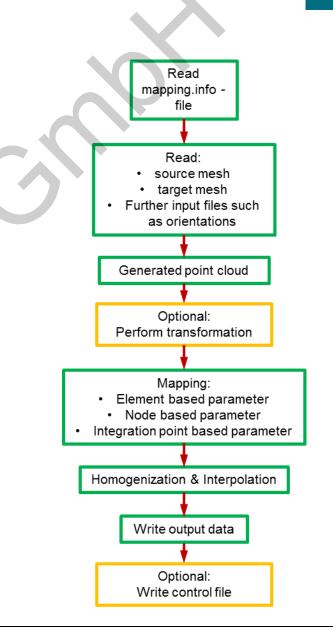
StrainRate#4Direction#3=90998

\$#-----

\$# END-OF-FILE \$#-----

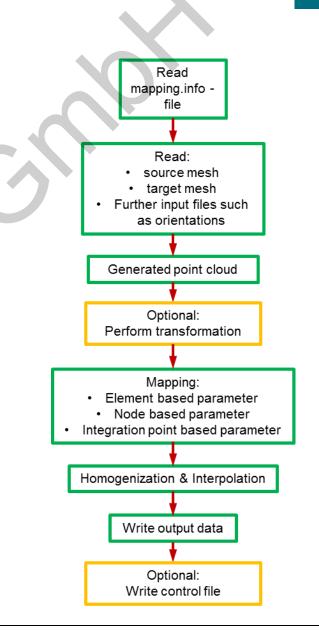


- GUI implementation
- A return mapping has to be performed in order to quantify and "postprocess" the loss of information during the mapping process (by now, only visual quality check).
- Possible evaluation criteria:
 - Overlap of mapped areas
 - Average offset btw. meshes
 - Comparison btw. element normals
 - "jumps" within the mapped parameter
 - Difference btw. transfered energies
 - Offsets btw. corresponding elements
- Output can be local (element or nodewise) or global

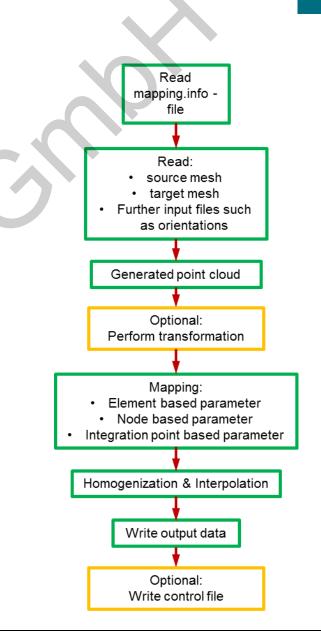


Tensor interpolation methods:

- Several approaches exist:
 - Euclidean interpolation
 - Riemannian interpolation
 - Log-Euclidean method
 - Geodesic-loxodrome approach
 - Approaches using partial differential equations
- Target: properly transfer shape and orientation
- Tensor characteristics are descirbed by eigenvalues, eigenvectors
- The usage of tensor invariants is proposed for tensor interpolation



- Scalar value interpolation methods:
 - Several approaches exist:
 - Inverse distance weighted methods (Shepard's method)
 - Rectangle based blending methods
 - Triangle based blending methods
 - Finite element based methods
 - Foley's methods
 - Global basis function type methods
 - Modified maud methods



- Envyo[®] will be available on Windows and Linux platforms
- first test versions will be available by the end of this year
- after a successful testing period it is thought to distribute Envyo[®] commercially. Details will follow in due time.

Remark:

 the quality and the capability of the program are highly dependent on its usage. Feedback is very appreciated.



Questions & Answers



