



New features in LS-DYNA R9.0.1

- Release R9.0.1 published in August 2016
- This presentation about major changes since R8.1
- Comprehensive list of enhancements and corrections in <http://www.dynasupport.com/news/ls-dyna-r9.0.1-r9.109912-released>

LS-DYNA versions

■ Version numbering scheme

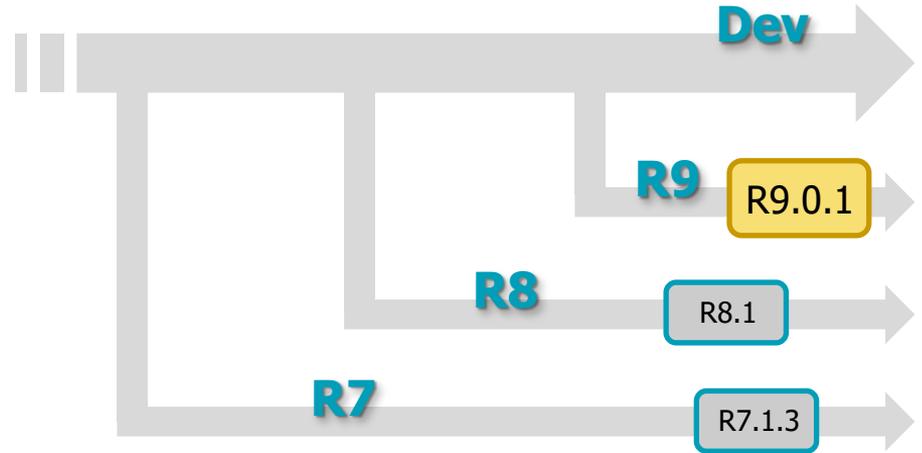
- Major branches called R6, R7, R8, R9, ...
- Official releases such as R6.1.2, R7.1.3

■ Robust production version

- Release R7.1.3 from May 2016
- Recommended for daily use in crash and occupant simulation

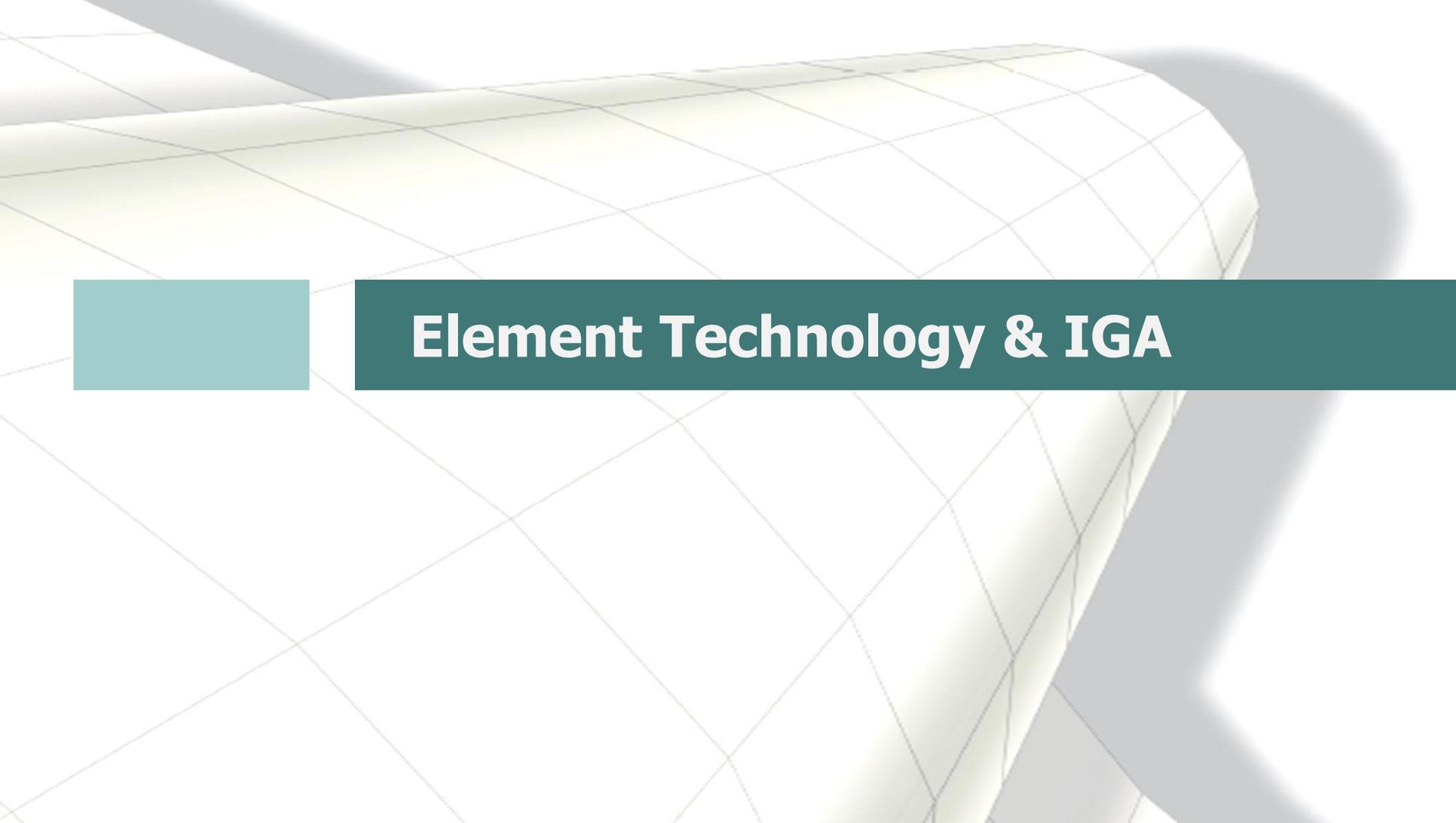
■ Latest official versions

- Release R8.1 from February 2016: Webinar slides on www.dynamore.de
- Release R9.0.1 from August 2016: New features shown in this presentation



Overview

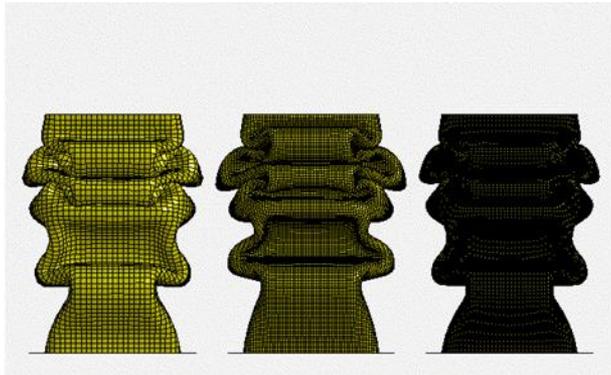
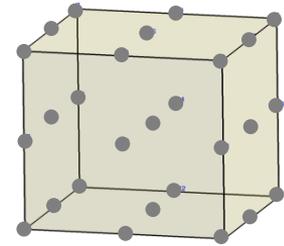
- Element Technology & IGA
- Contact
- Material models
- Forming applications
- Airbags
- Implicit analyses
- Frequency Domain
- MPP
- Miscellaneous
- Meshfree methods
- ALE / S-ALE
- Electromagnetics
- CFD & FSI
- CESE
- Bug fixes
- Conclusion



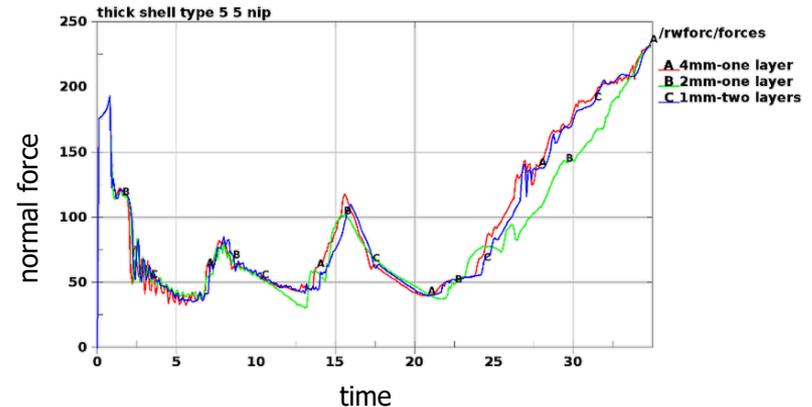
Element Technology & IGA

27-node solid element

- New element formulation ELFORM = 24 on *SECTION_SOLID
 - Accurate for large deformation, severe distortion
 - Selective reduced integration to alleviate volumetric locking
 - Supports *ELEMENT_SOLID_H8TOH27
 - Excellent behavior in bending with 1 element over plate thickness!



coarse-mesh
accuracy

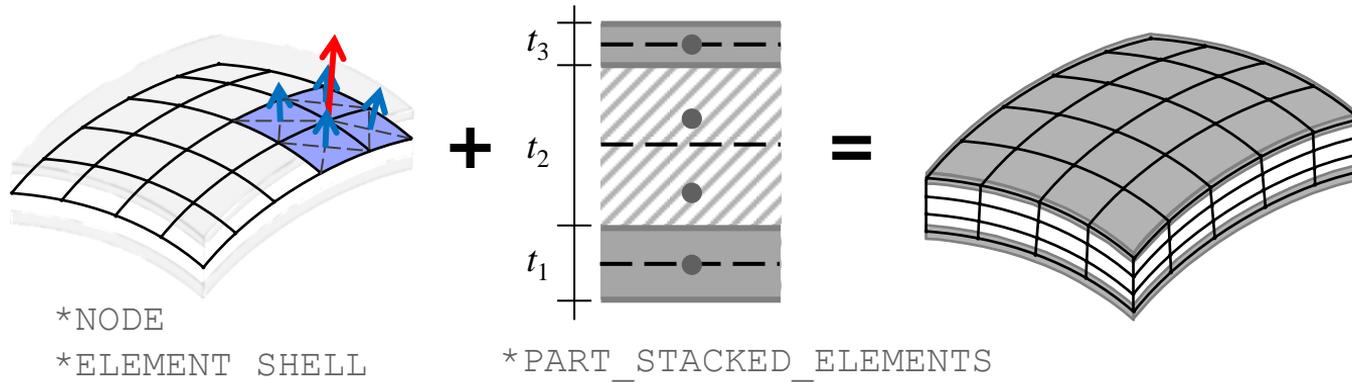


Stacked elements

■ New keyword `*PART_STACKED_ELEMENTS`

- Layered shell and/or solid element model for shell-like structures
- Application examples: sandwich plate systems, composite laminates, ...
- Definition of surface geometry and layup sequence
- Automatic mesh generation by extrusion

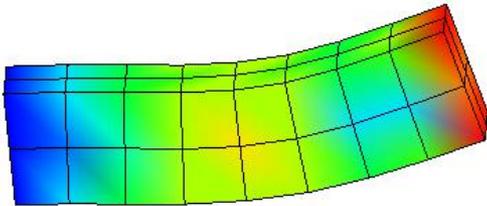
picture credit:
Wikipedia



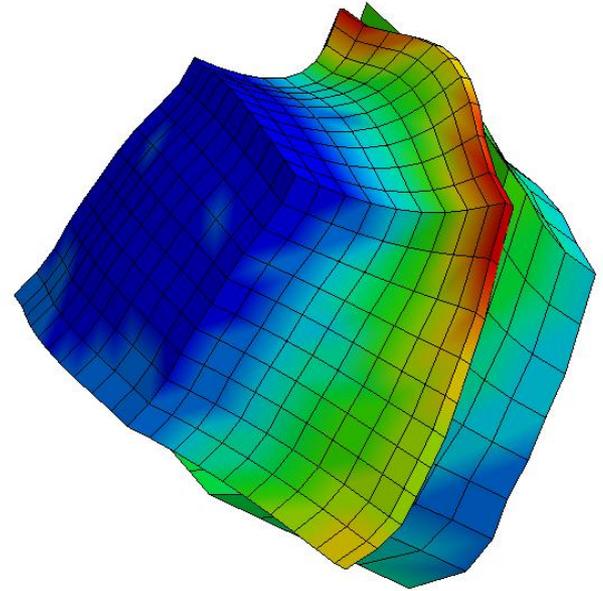
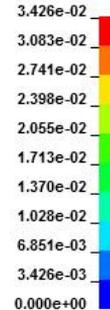
IGA for solids

- New keyword `*ELEMENT_SOLID_NURBS_PATCH`
 - Enable isogeometric analysis for solid elements
 - Supports explicit and implicit analysis, contact and eigenvalue analysis, etc.
 - To be used with `ELFORM=201` on `*SECTION_SOLID`

LS-DYNA eigenvalues at time 1.00000E-0
Freq = 0.11493
Contours of Resultant Displacement
min=0, at node# 100001
max=0.034257, at node# 100223



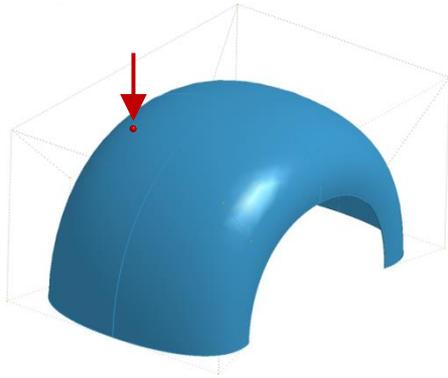
Fringe Levels



two bodies impact:
effective stress distribution

IGA boundary conditions

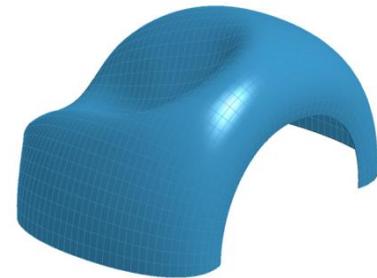
- New keyword `*CONSTRAINED_NODE_TO_NURBS_PATCH`
 - Add additional massless nodes (`*NODE`) to the surface of a NURBS patch (desired position)
 - Possibility to apply force and displacement boundary conditions at arbitrary position



Quadratic NURBS
(2x2 Elements)

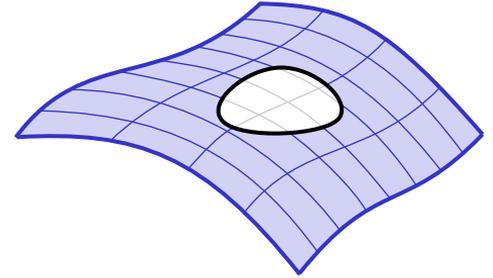


Deformation
Quadratic NURBS
(10x10 Elements)



Deformation
Quadratic NURBS
(40x40 Elements)

IGA: Trimmed NURBS

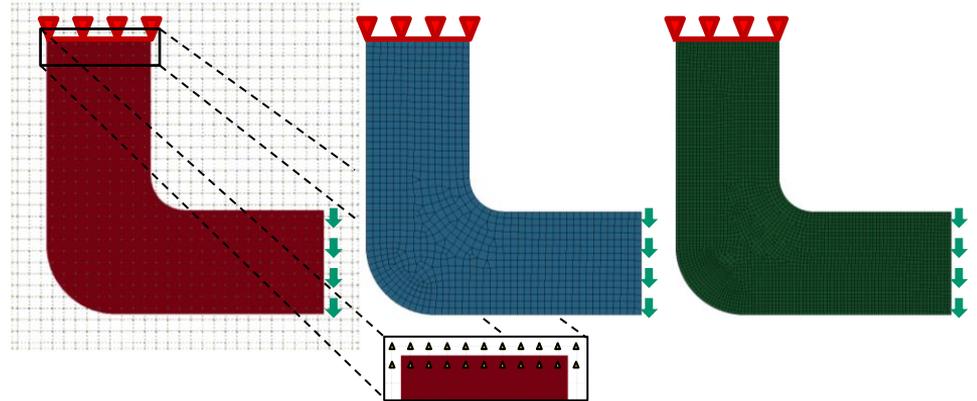


■ Add trimmed NURBS capability

- For surfaces that contain holes or have arbitrary shapes
- Define NL trimming loops to specify a trimmed NURBS patch
- Use *DEFINE_CURVE (DATTYP=6) to define trimming edges in the parametric space
- Boundary conditions via new keyword *CONSTRAINED_NODE_TO_NURBS_PATCH (CNTNP)

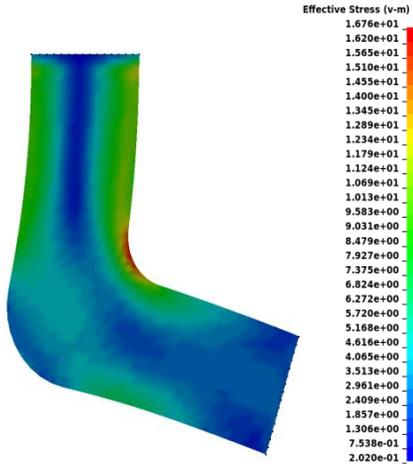
■ Example: L-Shape

- Dirichlet-BC's (kinematic):
 1. via SPC on „closest“ Control Points
 2. via CNTNP (con=111111, SF varying)
- Neumann-BC's (load):
via CNTNP (con=0)
+ *LOAD_NODE_SET

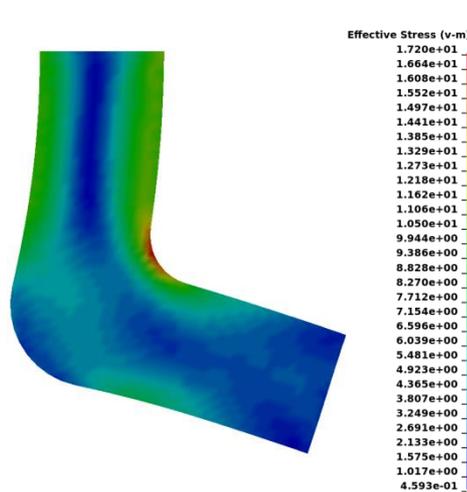


IGA: Trimmed NURBS

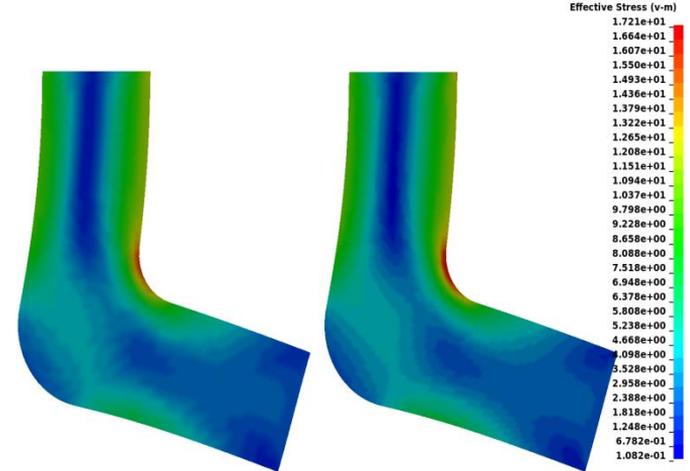
■ L-Shape results: Deformation and von Mises stresses



Trimmed NURBS (quadratic)
30x30 elements
mesh size: 0.33 mm
SPC on CPs



Trimmed NURBS (quadratic)
30x30 elements
mesh size: 0.33 mm
SPC on "massless" nodes via CNTNP

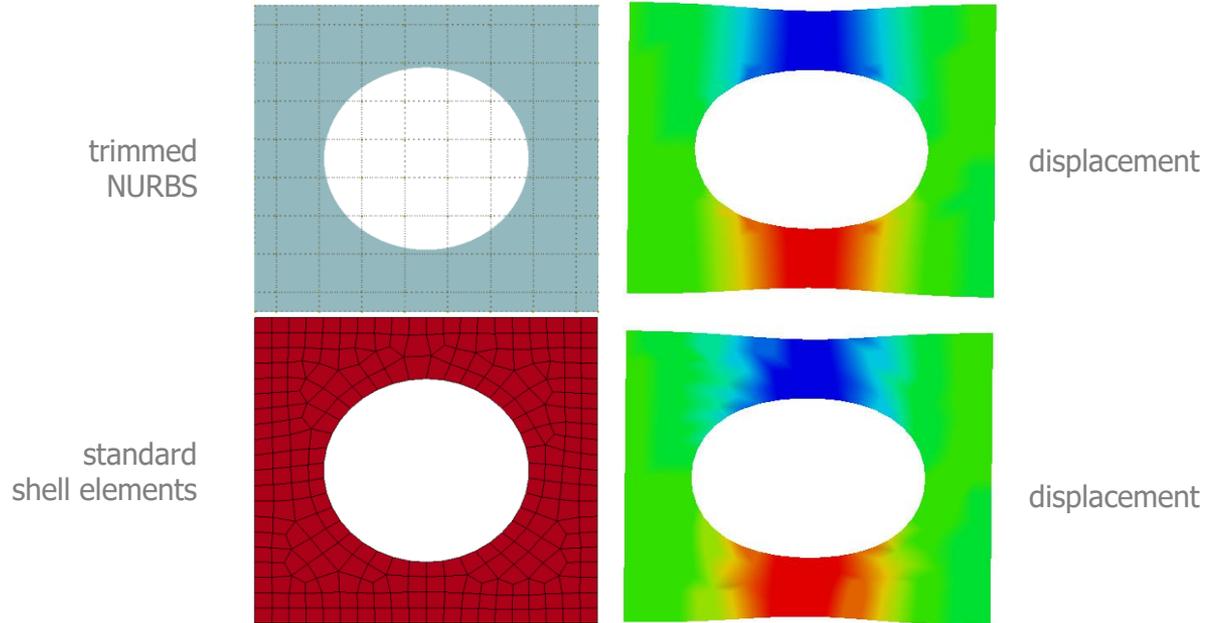


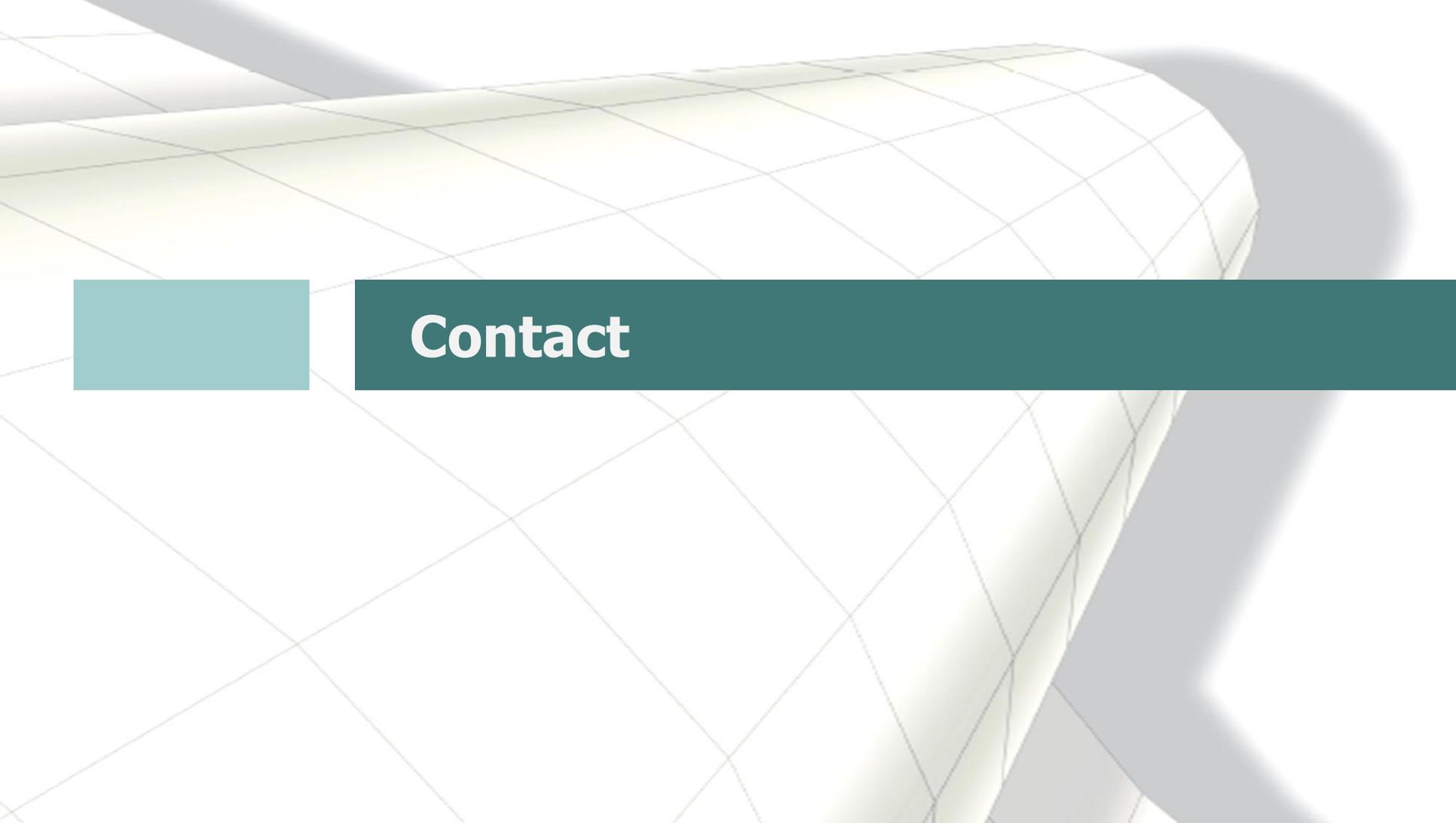
Standard FE
mesh size: 0.2 mm

Standard FE
mesh size: 0.1 mm

IGA: Trimmed NURBS

- Another example: plate with hole

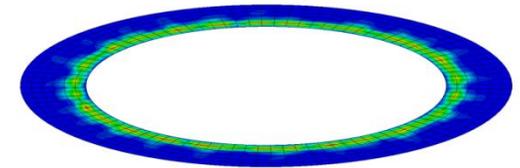
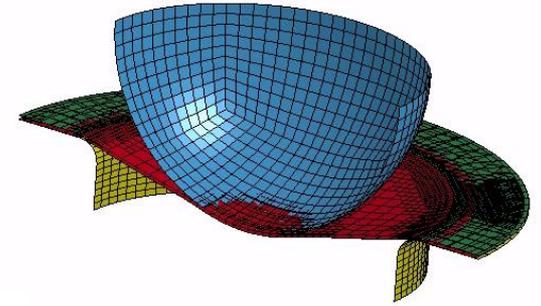
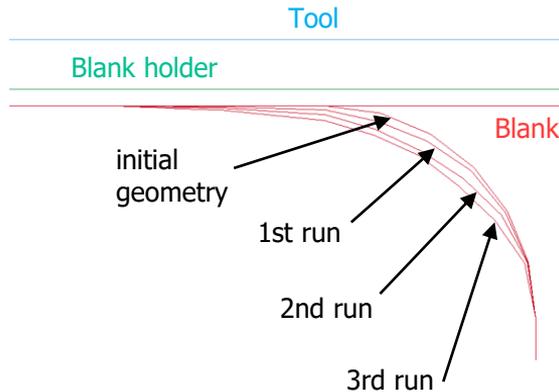
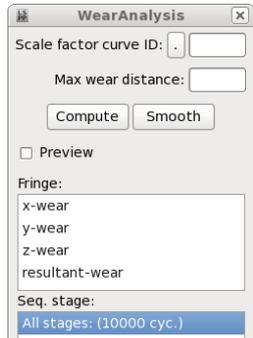




Contact

Wear processes

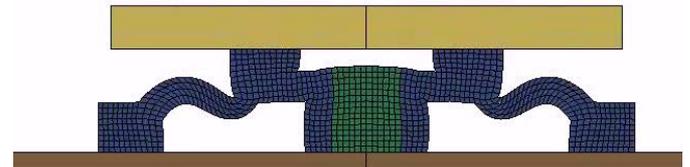
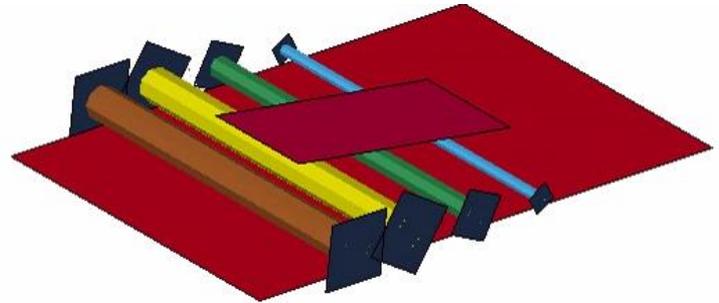
- New keyword `*CONTACT_ADD_WEAR`
 - Simulating wear is of interest for improving tool design
 - Archard and User wear laws
 - Post process wear in LS-PrePost
 - Modify geometry in LS-PrePost based on wear, using `*INITIAL_CONTACT_WEAR`



wrinkling tendency influences wear on binder

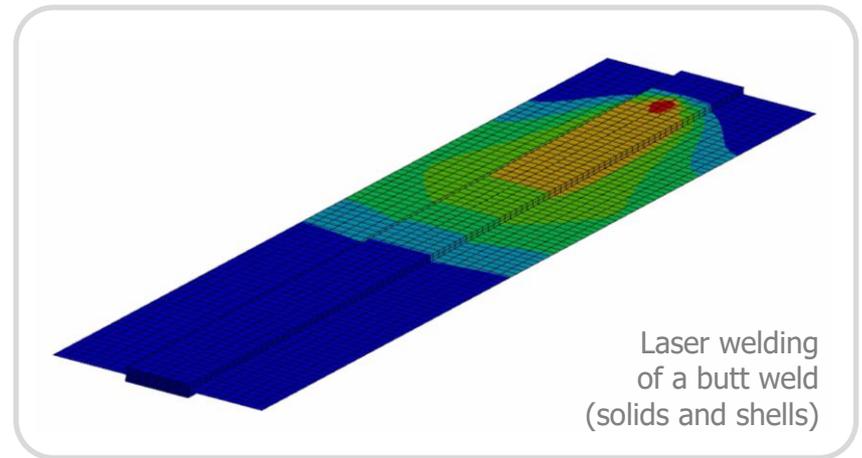
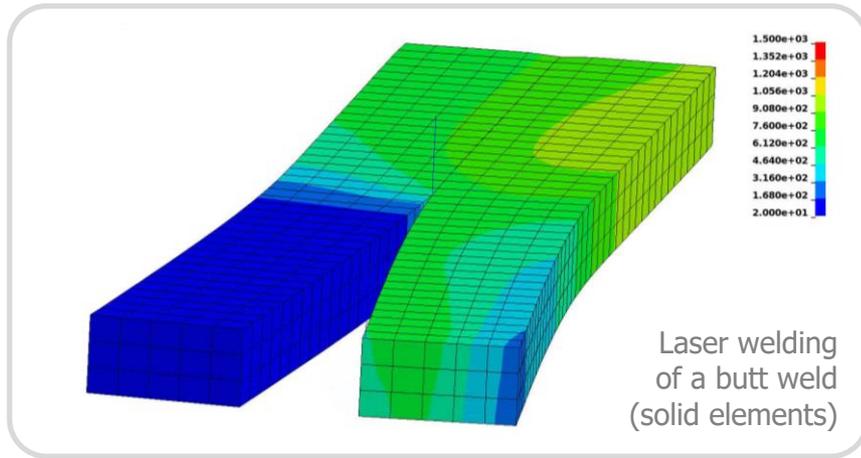
Mortar contact

- Several enhancements and improvements
 - Forming mortar contact now runs with deformable solid tools and honors ADPENE
 - Support rotational degrees of freedom when contact with beam elements
 - Maximum allowable penetration takes master thickness into account
 - Account for sharp edges in solid elements
 - When solid elements are involved, default stiffness is increased by a factor of 10
 - The OPTT parameter on *PART_CONTACT for the contact thickness of beams is now supported



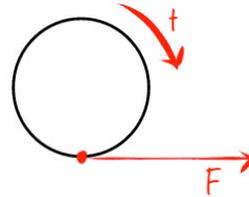
Tied contact for welding

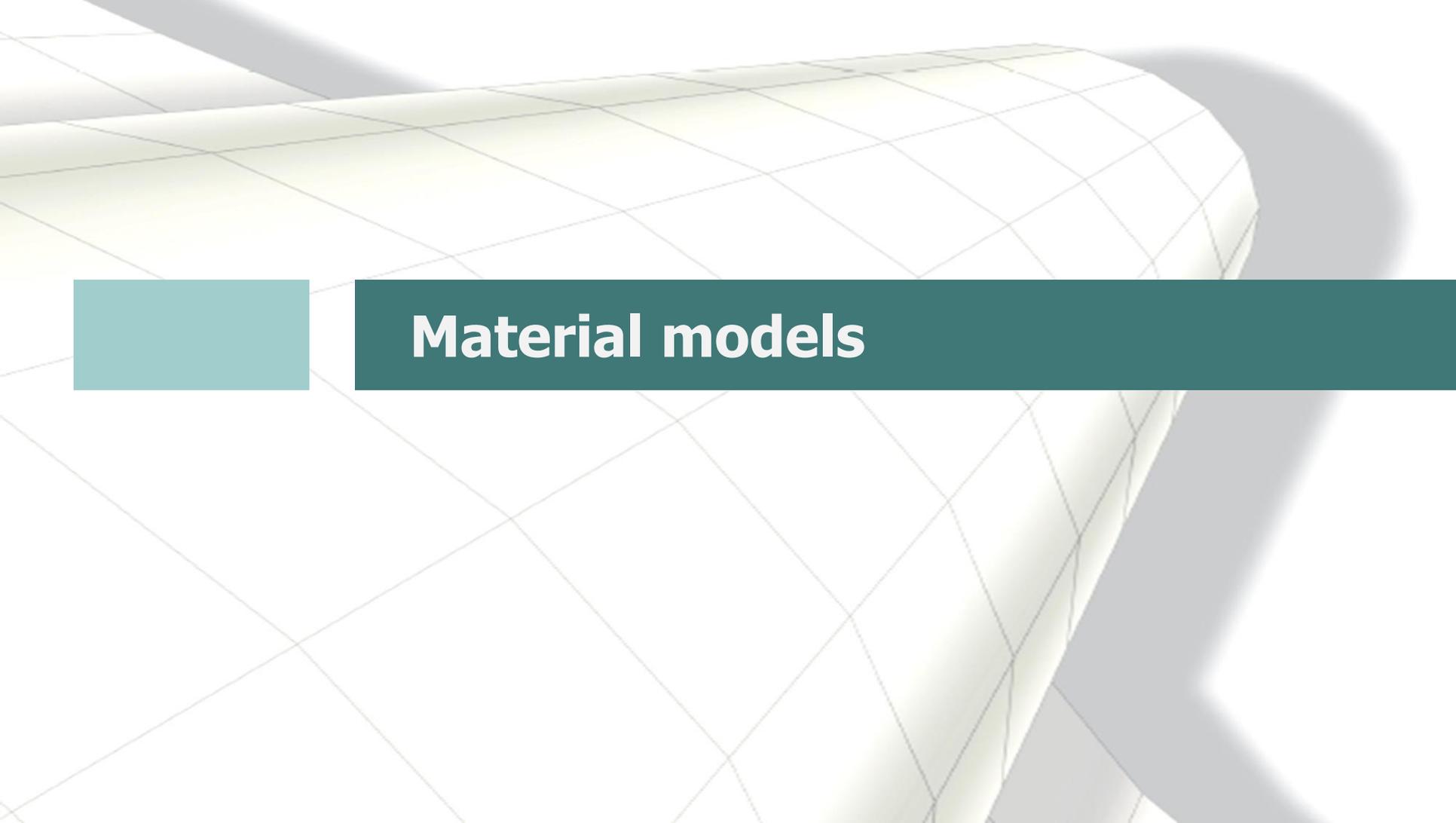
- New keyword `*CONTACT_AUTOMATIC_SURFACE_TO_SURFACE_TIED_WELD_THERMAL`
 - As regions of the surfaces are heated to the welding temperature and come into contact, the nodes are tied. (Below welding temperature: standard sliding contact behavior)
 - Heat transfer in welded contact zones differs as compared to unwelded regions



More contact enhancements

- Change “interface pressure” report in **intfor** file from $\text{abs}(\text{force}/\text{area})$ to $-\text{force}/\text{area}$ for correct representation of tied interfaces in tension
- Add support for ***DEFINE_REGION** to define an active contact region for MPP contacts
- Add **frictional work calculation for beams** in ***CONTACT_AUTOMATIC_GENERAL**
- Add new option FTORQ for **torque introduced by friction** (beams in ***CONTACT_AUTOMATIC_GENERAL**)
- Added support to SOFT=2 contact for **SRNDE** parameter (non-extended shell edges)
- *SENSOR can now be used to control ***CONTACT_GUIDED_CABLE**
- Add ***CONTACT_TIED_SHELL_EDGE_TO_SOLID** to transmit shell or beam moments into solids using force pairs





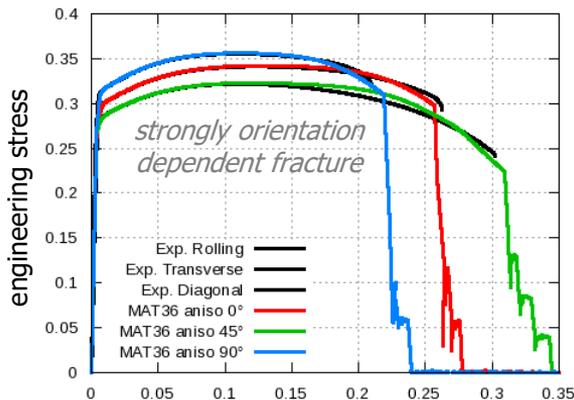
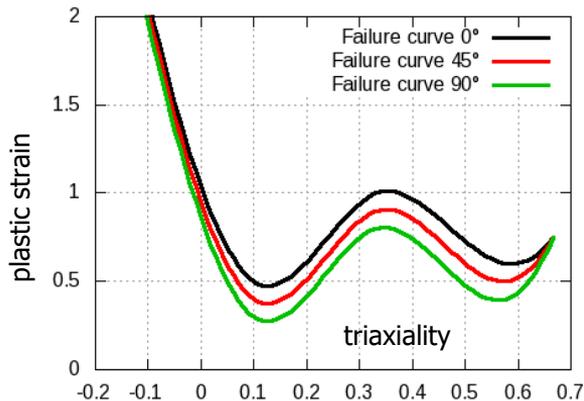
Material models

Generalized damage model

■ New keyword *MAT_ADD_GENERALIZED_DAMAGE (MAGD)

- General damage model as add-on for other material models
- Intention: non-isotropic damage as in aluminum extrusions, ...
- Up to 3 history variables as damage driving quantities
- Very flexible due to input via *DEFINE_FUNCTIONS

$$\begin{bmatrix} \sigma_{11} \\ \sigma_{22} \\ 0 \\ \sigma_{12} \\ \sigma_{23} \\ \sigma_{31} \end{bmatrix} = \begin{bmatrix} D_{11} & D_{12} & 0 & D_{14} & 0 & 0 \\ D_{21} & D_{22} & 0 & D_{24} & 0 & 0 \\ 0 & 0 & D_{33} & 0 & 0 & 0 \\ D_{41} & D_{42} & 0 & D_{44} & 0 & 0 \\ 0 & 0 & 0 & 0 & D_{55} & 0 \\ 0 & 0 & 0 & 0 & 0 & D_{66} \end{bmatrix} \begin{bmatrix} \tilde{\sigma}_{11} \\ \tilde{\sigma}_{22} \\ 0 \\ \tilde{\sigma}_{12} \\ \tilde{\sigma}_{23} \\ \tilde{\sigma}_{31} \end{bmatrix}$$

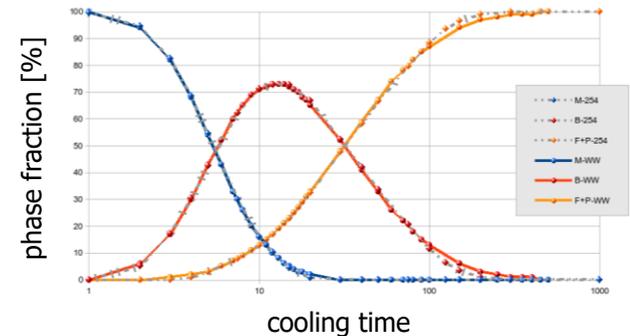
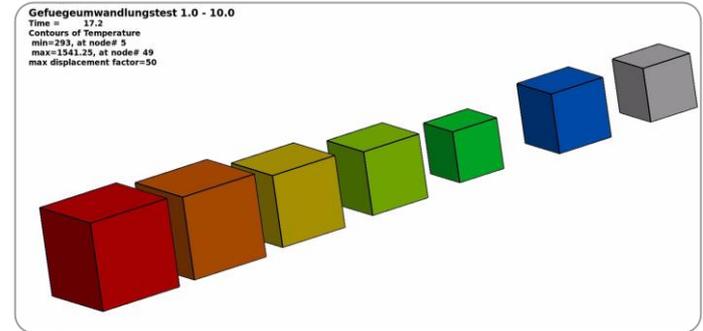


... and many other possible application areas

General phase change material

■ New material model *MAT_GENERALIZED_PHASE_CHANGE or *MAT_254

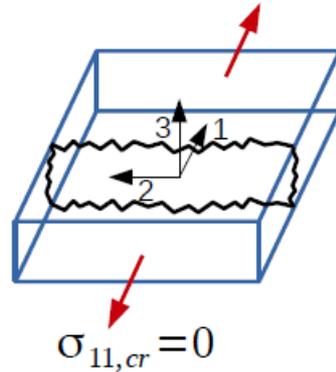
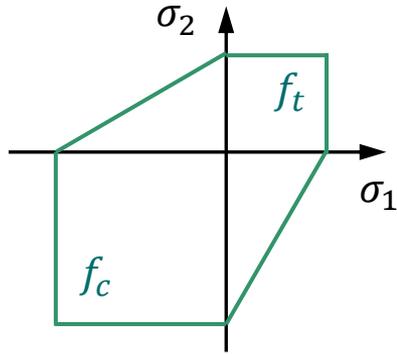
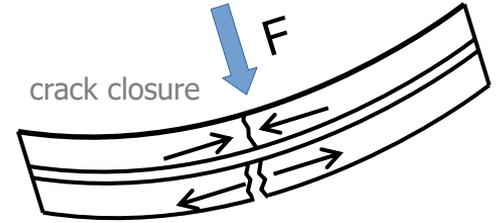
- Very general material implemented to capture micro-structure evolution in welding and heat treatment
- Up to 24 individual phases
- For any of the possible phase transformation user can choose from a list of generic phase change mechanisms (e.g. Leblond, JMAK, Koistinen-Marburger, Kirkaldy, ...)
- Parameters for transformation law directly given in tables
- Additional features
 - Transformation induced strains
 - Transformation induced plasticity (TRIP)
 - Temperature and strain rate dependent plasticity
- Ongoing development



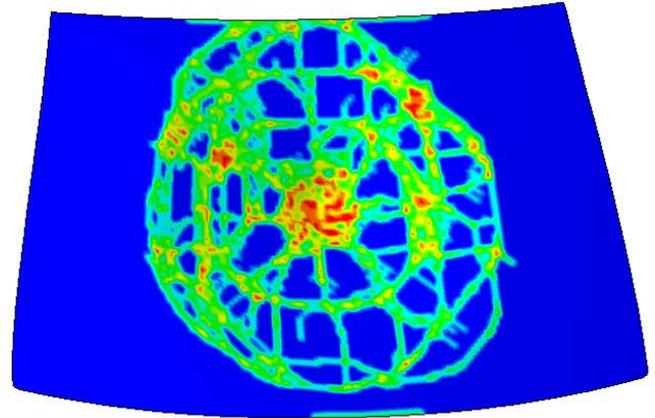
Glass model

■ New material *MAT_GLASS (*MAT_280)

- Material model for fracture of (laminated) safety glass
- Brittle smeared fixed crack model for shell elements (plane stress)
- Failure criteria: Rankine, Mohr-Coulomb, or Drucker-Prager
- Incorporates up to 2 cracks, simultaneous failure over thickness, crack closure effect (no element deletion)

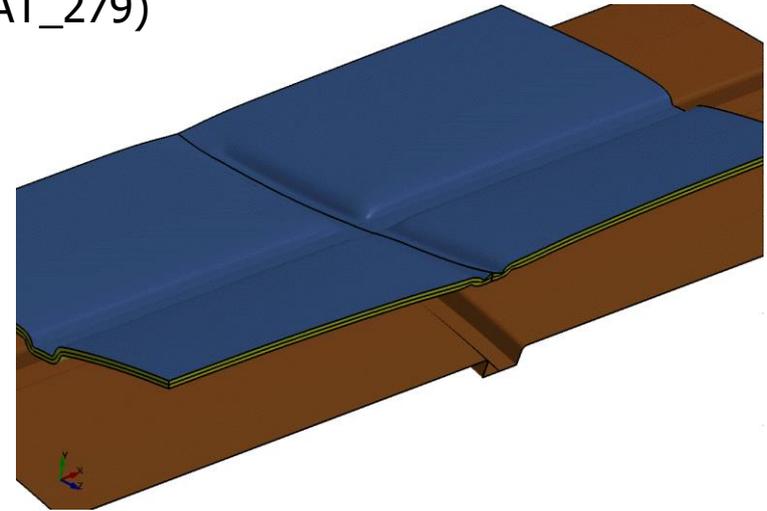
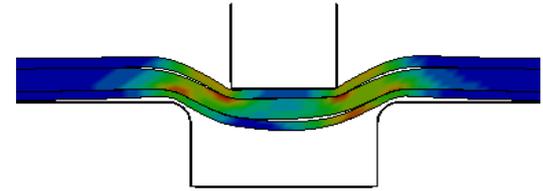
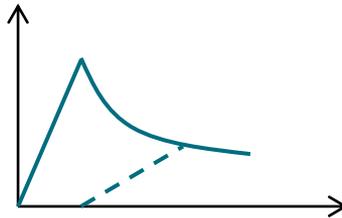


windshield
head impact



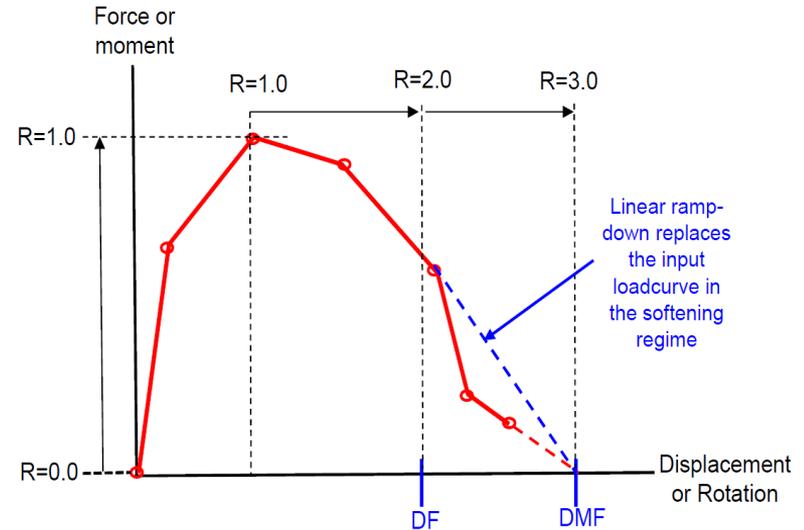
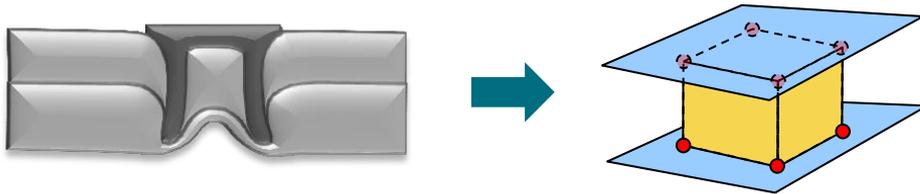
Paperboard modeling

- *MAT_PAPER or *MAT_274 already available in R7.1.3
 - Orthotropic elastoplastic model for shell and solid elements
 - For creasing simulation with delamination of individual plies
- New cohesive model *MAT_COHESIVE_PAPER (*MAT_279)
 - For modeling delamination in conjunction with *MAT_PAPER and shells
 - In-plane and out-of-plane models uncoupled
 - Normal compression nonlinearly elastic
 - Normal tension and tangential traction given by elastoplastic traction-separation law:



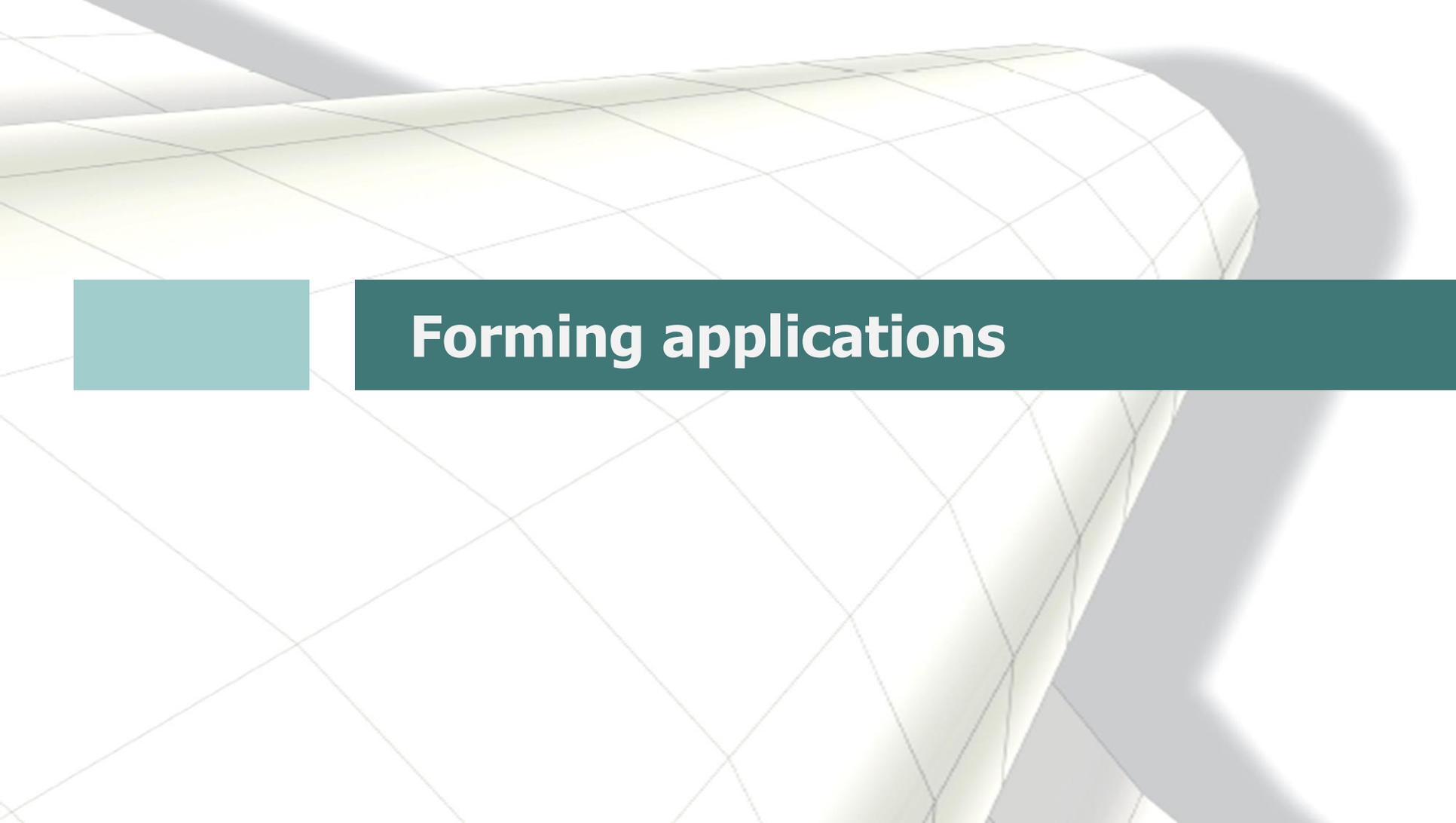
Material model for self-piercing rivets

- Keyword is *MAT_SPR_JLR or *MAT_211
 - Already available since R7, now stable and extensively documented in User's Manual of R9
 - SPR discretized as hexahedron ELFORM=1 but uses separate unique element formulation
 - Covers several special features suitable for SPR (head-tail distinction, axial-shear-bending, non-linear force-displacement, softening, ...)
 - Comprehensive output capabilities



More material enhancements

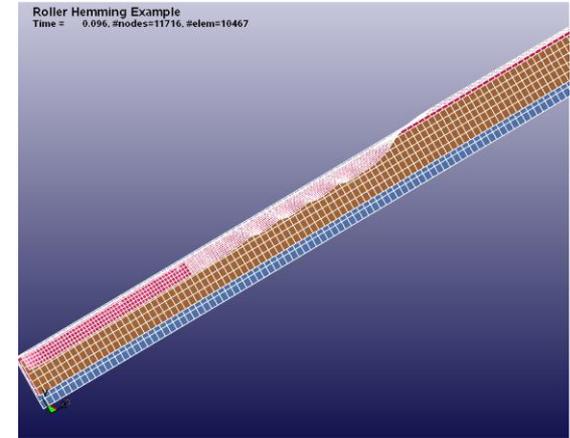
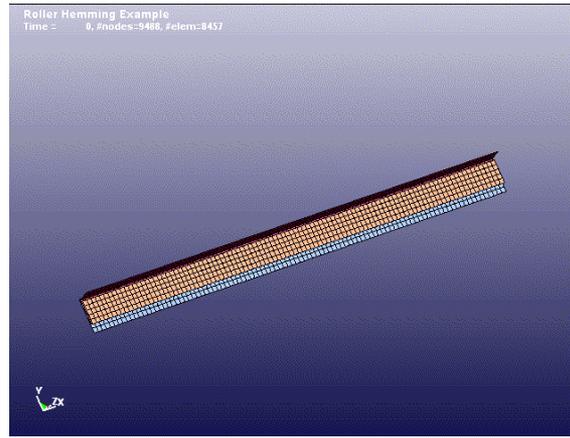
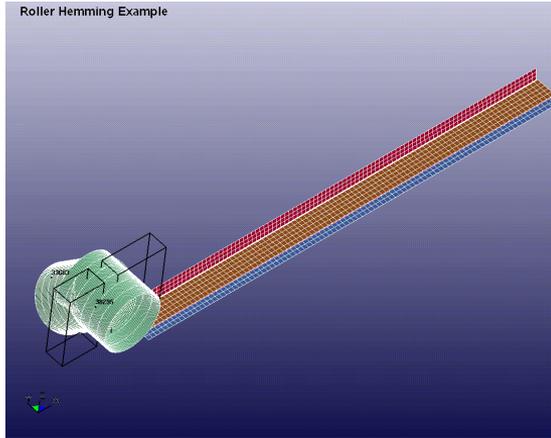
- New keyword ***DEFINE_MATERIAL_HISTORIES** for organizing history outputs
- Modified ***MAT_FABRIC** FORM=24 so that Poisson's effects occur in tension only
- Add thick shell support for the **STOCHASTIC** option of materials 10, 15, 24, 81, and 98
- Added support for ***MAT_BRITTLE_DAMAGE** for solid element types 3, 4, 15, 18, and 23
- Add implicit iteration abort flag "reject" to **user-defined materials**
- Several improvements for **DIEM**: efficiency, new options, output, ...
- Rate dependent plasticity and strengths for ***MAT_261** and ***MAT_262**
- Add possibility to use ***DEFINE_FUNCTION** for ***MAT_SPOTWELD**, OPT=-1/0
- Improve performance of **GISSMO** and ***MAT_187**
- Add **implicit** capability for materials 120, 121, 157, 181 (2D), 254, 274, 275



Forming applications

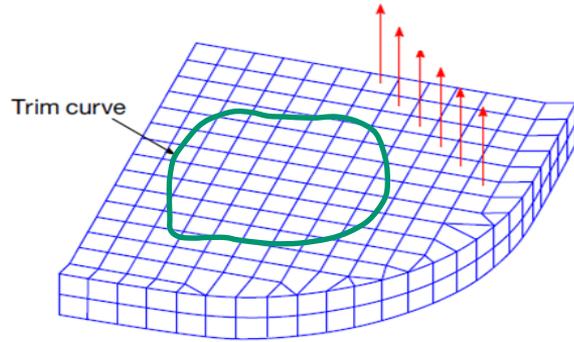
Enhanced adaptive box

- Mesh fission and fusion in a user defined region changing over time
 - Moving box to control mesh refinement and coarsening
 - New option in *DEFINE_BOX_ADAPTIVE
 - Useful in roller hemming and incremental forming

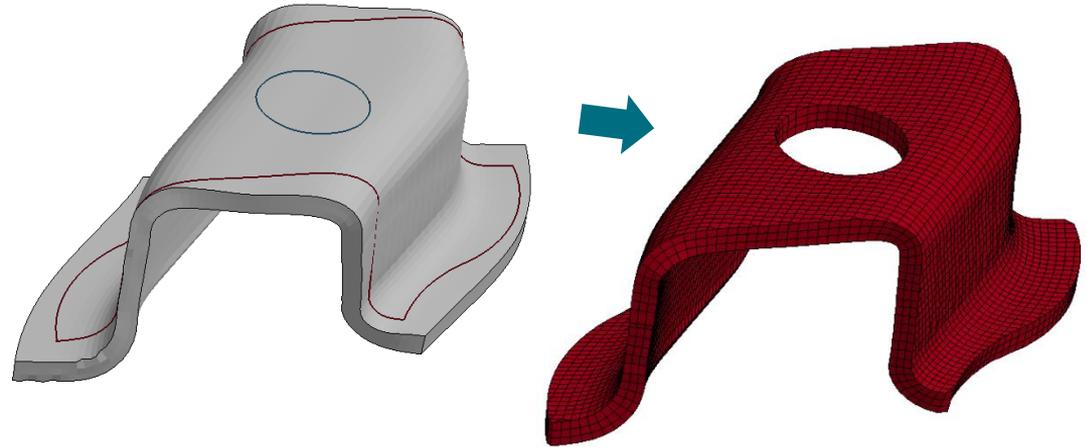


Trimming extensions

- NEW: 2D and 3D trimming of solids (and laminates)
 - Inputs to trim solid elements are the same as for trimming of shell elements
 - *INCLUDE_TRIM has to be used (new efficient method to include mesh for trimming)
 - Additional input to indicate solid normals: TDIR on *DEFINE_CURVE_TRIM_3D

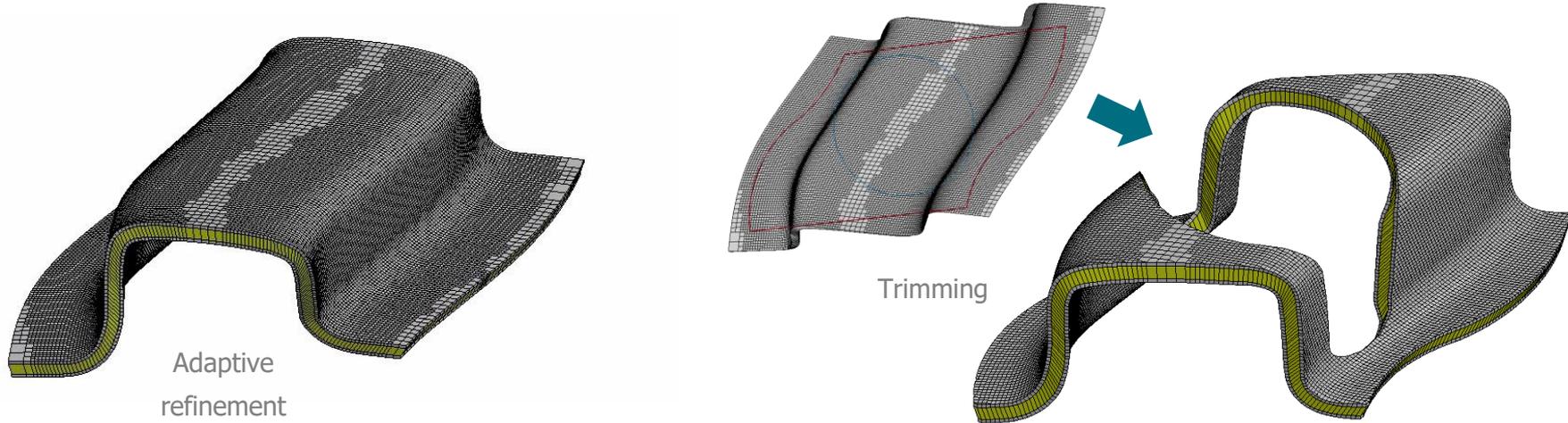


TDIR = 1: trim curve near top surface
TDIR = -1: trim curve near bottom surface



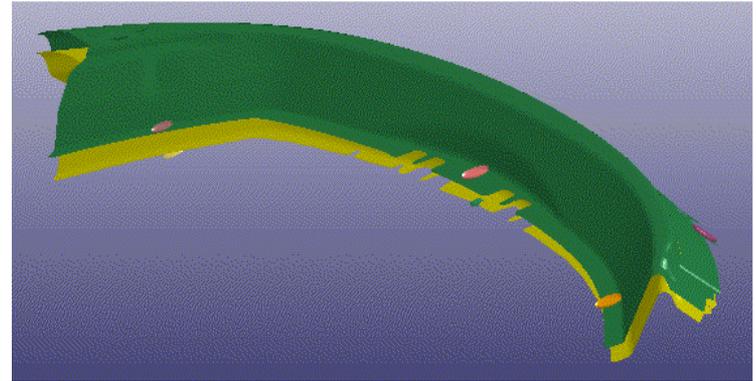
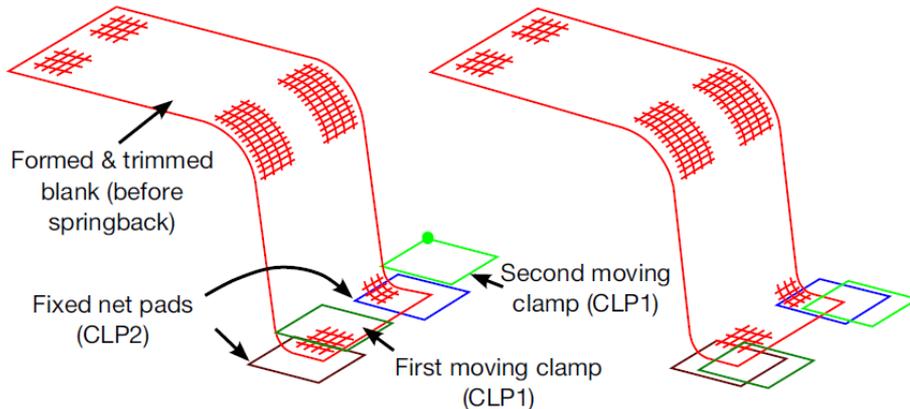
Sandwich sheets

- New features to treat shell-solid-shell models in metalforming
 - For sandwich structures such as metal sheets with polymer core layer
 - Option IFSAND on *CONTROL_ADAPTIVE for adaptive refinement
 - Trimming via *DEFINE_CURVE_TRIM_3D now supports solid elements and sandwiches



Clamping simulation

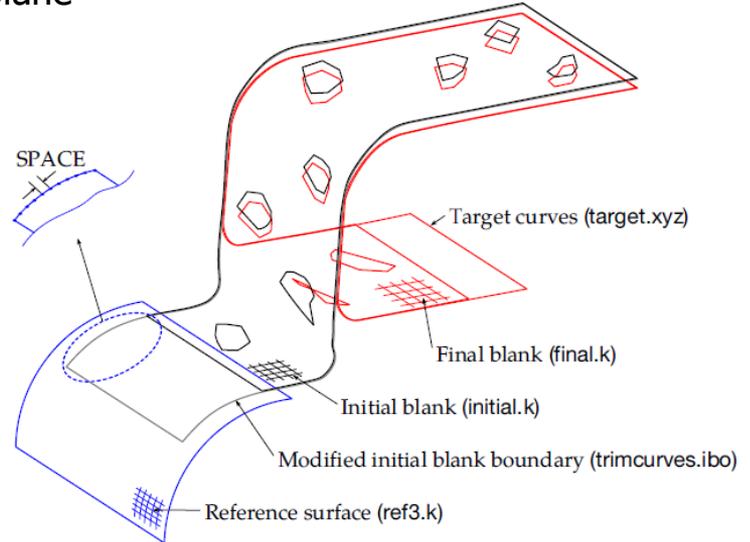
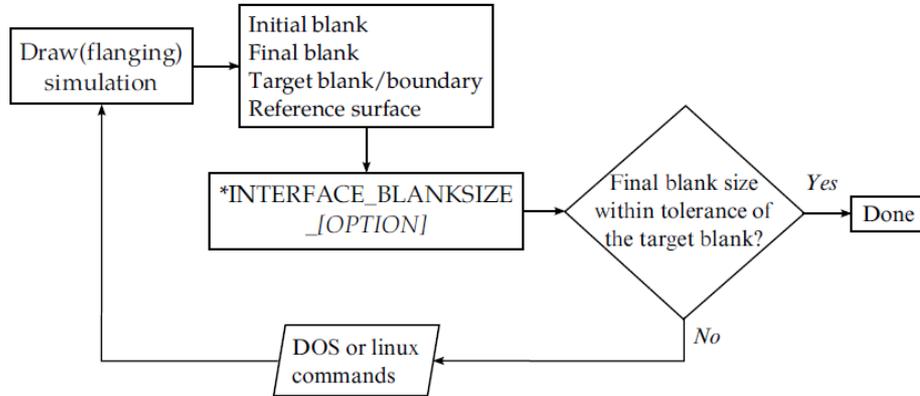
- New keywords `*DEFINE_FORMING_CLAMP` and `*DEFINE_FORMING_CONTACT`
 - Macros serving as placeholders for the combination of cards needed to model a clamping process
 - Eliminate the need to use auto-position cards between the formed panel and clamps
 - Prescribed motions are automatically (internally) assigned to the clamps
 - Simplifies the contact definition between the panel and the clamps



Blank size development

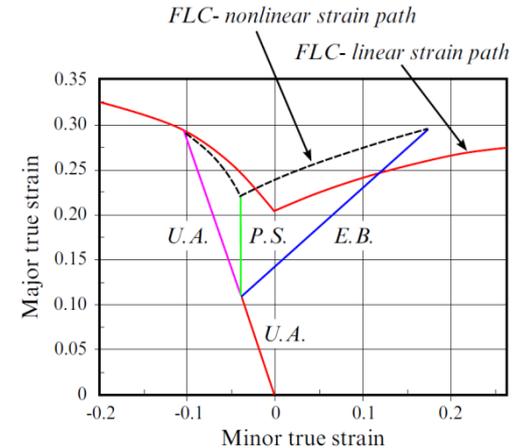
■ New features for *INTERFACE_BLANKSIZE_DEVELOPMENT_...

- SCALE_FACTOR allows user to include or exclude a target curve in the calculation of the initial curve. It also allows user to scale up or down in size of a target curve involved in the calculation.
- SYMMETRIC_PLANE allows user to define a symmetric plane
- and others...



More enhancements for forming

- Add a new keyword `*CONTROL_FORMING_BESTFIT`
 - This rigidly moves two parts so that they maximally coincide
- Improvements to springback compensations
 - e.g. output of new trimming curve format
- Improvements to `*CONTROL_FORMING_AUTOCHECK`
 - e.g. output rigid tool mesh in offset position
- Improvements to `*CONTROL_FORMING_UNFLANGING`
 - e.g. allow non-smooth flange edge
- Add formability index to `*MAT_036`, `*MAT_037`, `*MAT_226`
- Add a new material model `*MAT_260` (2 forms)
 - `*MAT_260A`: "Stoughton non-associated flow"
 - `*MAT_260B`: "Mohr non-associated flow"

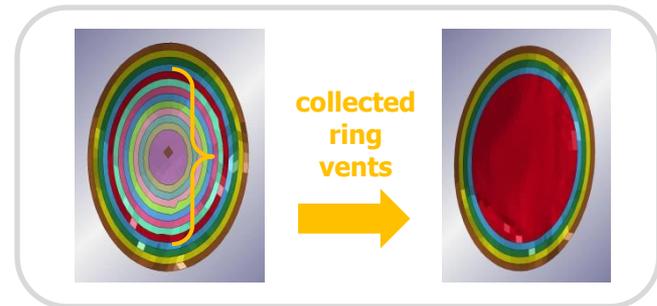
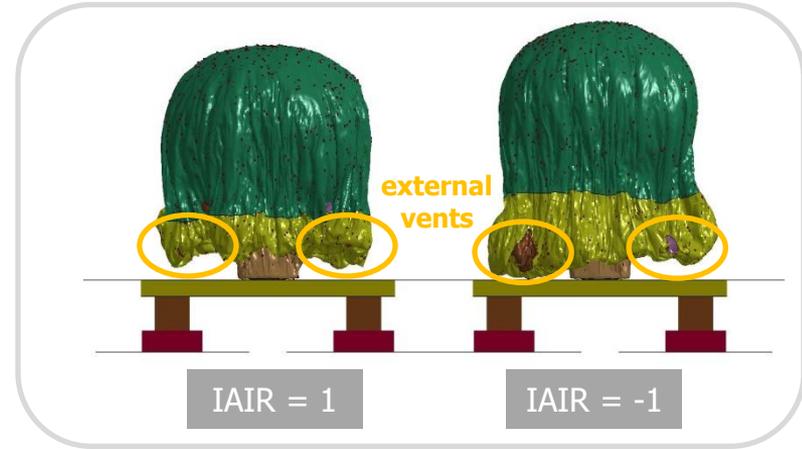




Airbags

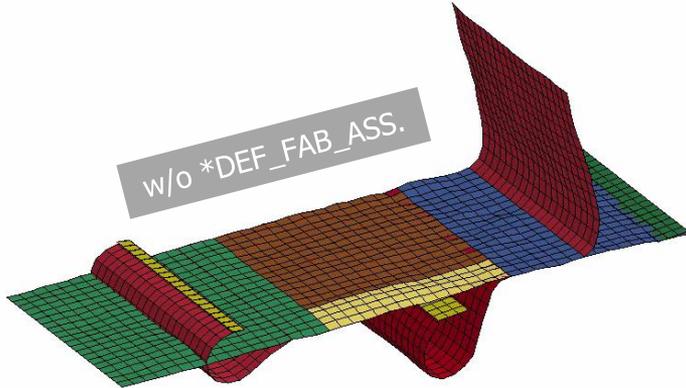
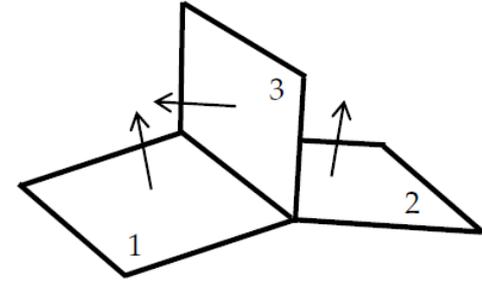
CPM for Airbag Modeling

- Several enhancements and improvements
 - New option IAIR=-1 allows external vents to draw in outside air (if $p_{\text{bag}} < p_{\text{atm}}$)
 - Treat heat convection when chamber is defined
 - Allow IAIR=4 to gradually switch to IAIR=2 to avoid instability
 - Allow using shell to define inflator orifice
 - New feature to collect all ring vents into a single vent in order to correctly treat enhanced venting option
 - Support vent/fabric blockage for CPM and ALE coupled analysis
 - New option in `*CONTROL_CPM` to allow user defined smoothing of impact forces

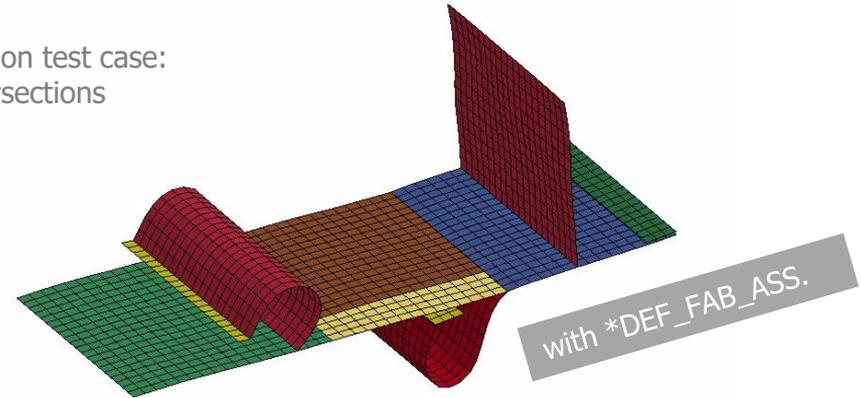


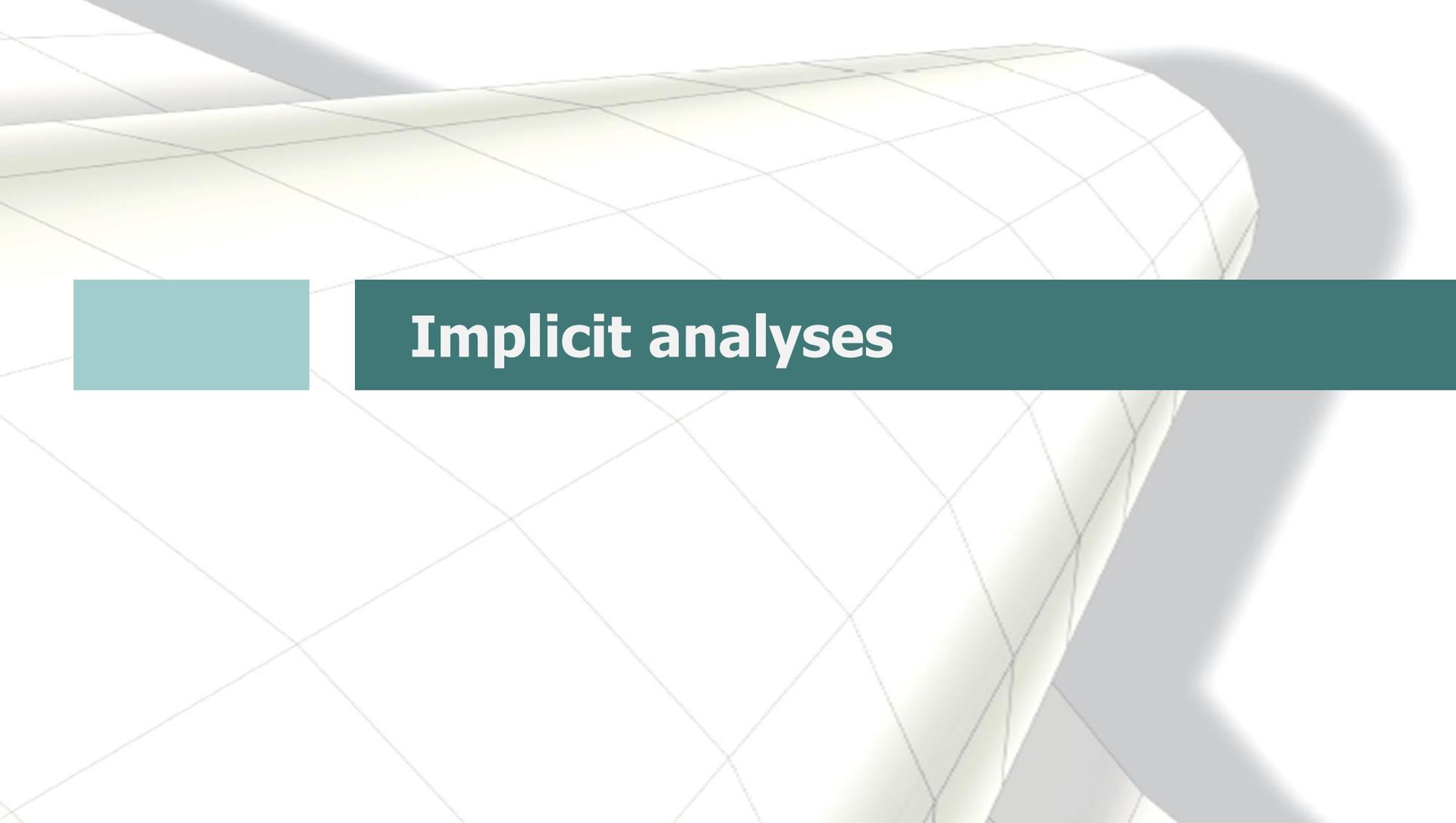
Fabric assemblies

- Proper treatment of bending of t-intersecting fabrics
 - New keyword `*DEFINE_FABRIC_ASSEMBLIES`
 - List of part sets to treat fabric bending between parts
 - Works with `*MAT_FABRIC`'s optional coating feature (ECOAT, SCOAT, TCOAT)



numerical verification test case:
various t-intersections

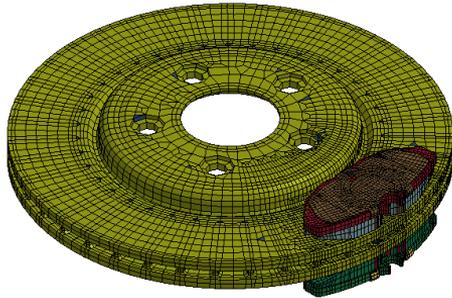




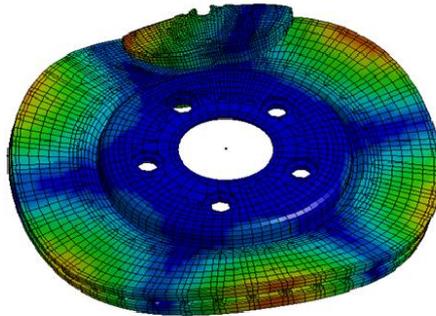
Implicit analyses

Brake squeal analysis

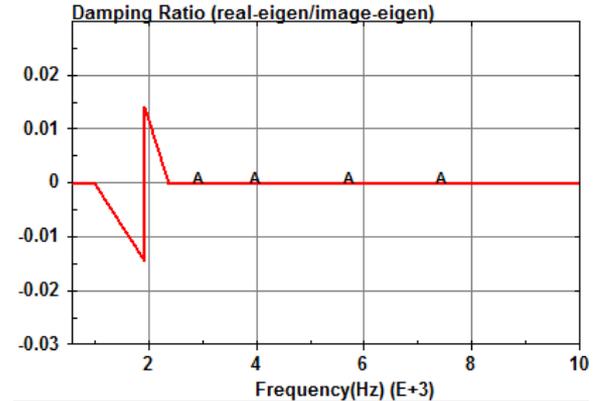
- Rotor dynamics application with `*CONTROL_IMPLICIT_ROTATIONAL_DYNAMICS`
 - Brake squeal noise as a result of friction-induced vibration
 - Intermittent eigenvalue analysis:
combination of transient analysis and complex eigenvalue analysis (instability detection)
 - Pad-Disk contact (MORTAR) introduces non-symmetry to the stiffness matrix:
`LCPACK=3` on `*CONTROL_IMPLICIT_SOLVER`



Disk brake model

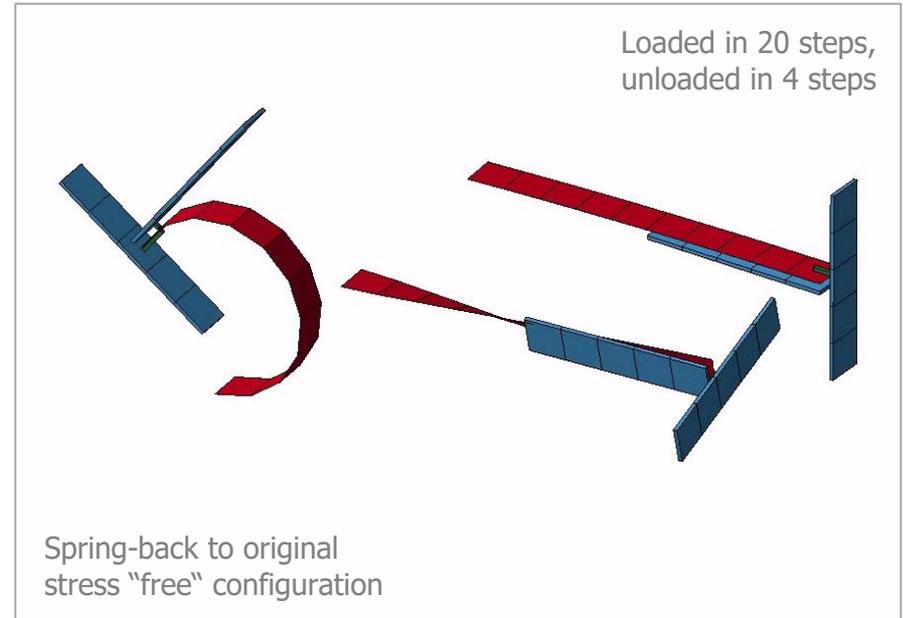


Resultant displacements at 2000 Hz



Implicit accuracy

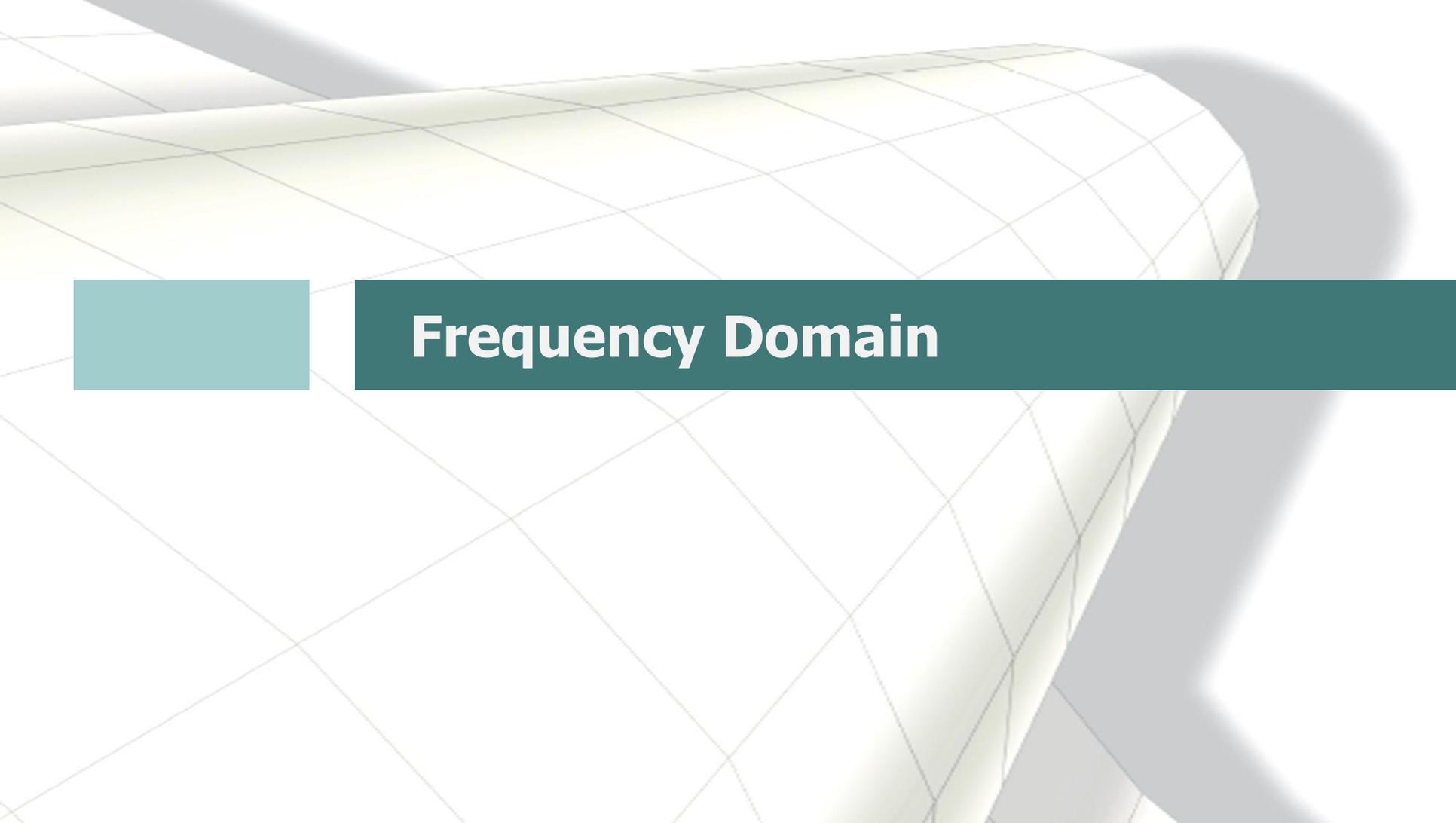
- Implicit accuracy option IACC=1 on *CONTROL_ACCURACY
 - Larger implicit steps demand for stronger objectivity and higher accuracy
 - Higher accuracy in selected material models
 - Fully iterative plasticity
 - Tightened tolerances
 - Strong objectivity and consistency in selected tied contacts →
 - Physical (only ties to DOFs that are "real") bending/torsion whenever applicable
 - Finite rotation
 - Strong objectivity and increased accuracy in selected elements
 - Finite rotation support for hypoelasticity



More enhancements for Implicit

- Nonlinear implicit solver 12 is made default aiming for improved robustness
- Reduce symbolic processing time and cost of numerical factorization in MPP
 - Done by reuse of matrix reordering and prediction of non tied contacts
- Apply improvements to Metis memory requirements used in MPP
- Add coupling of prescribed motion constraints for Modal Dynamics by using constraint modes
- Several enhancements for matrix dumping (MTXDMP)
- Enhancements for implicit-explicit switching
 - e.g. time step adjustments, intermittent eigenvalue analysis, ...
- Add support for *CONSTRAINED_LINEAR for 2D problems
- Bathe composite time integration implemented for increased stability and conservation of energy/momentum, see ALPHA on *CONTROL_IMPLICIT_DYNAMICS

4	5	6	7	8
TDYBIR	TDYDTH	TDYBUR	IRATE	ALPHA
F	F	F	I	F
0.0	10 ²⁸	10 ²⁸	0	0

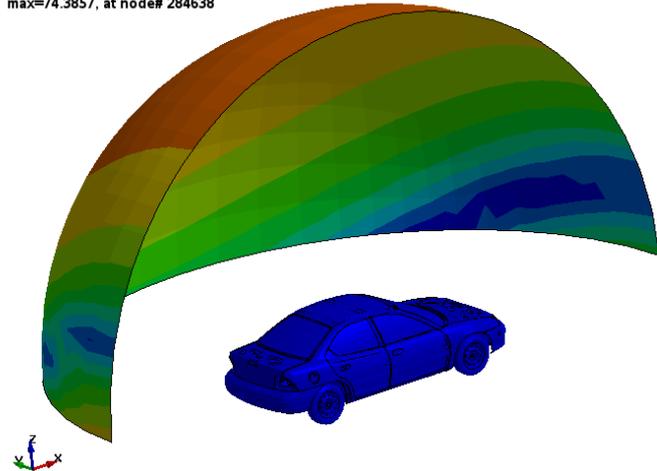


Frequency Domain

Acoustic fringe plot

- New keyword *FREQUENCY_DOMAIN_ACOUSTIC_FRINGE_PLOT
 - Define field points for acoustic pressure computation and use D3ACS binary database to visualize the pressure distribution
 - Either for existing structure components ... (PART, PART_SET, NODE_SET)
 - ... or for automatically generated geometries (plate, sphere)
 - Results comprise real part, imaginary part, and absolute value of acoustic pressure as well as sound pressure level (dB)
 - Supported by LS-Prepost 4.2 and above

Freq = 10
Contours of Sound pressure level (dB)
min=0, at node# 2297002
max=74.3857, at node# 284638

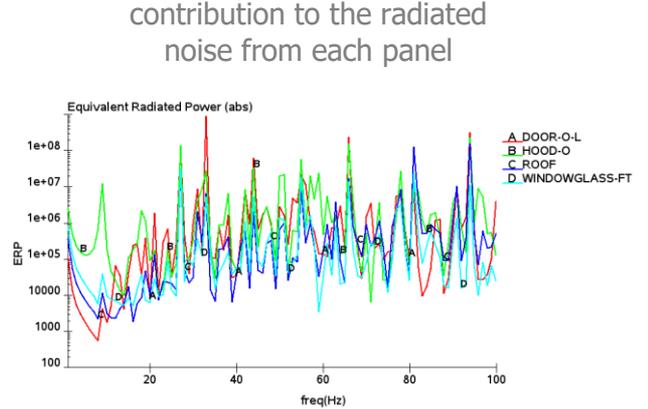
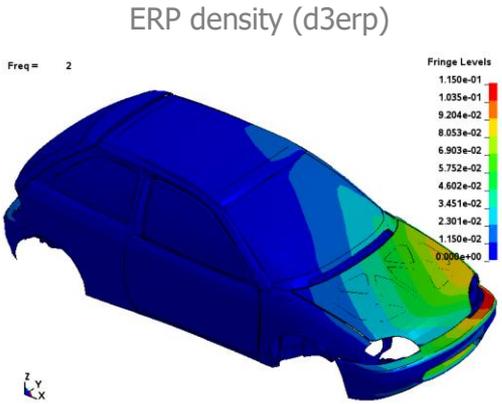
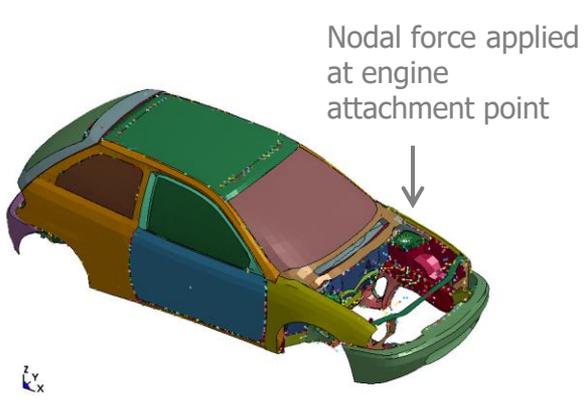


Fringe Levels

7.439e+01	Red
7.177e+01	Orange
6.915e+01	Yellow
6.654e+01	Light Green
6.392e+01	Green
6.130e+01	Dark Green
5.869e+01	Teal
5.607e+01	Cyan
5.345e+01	Blue
5.083e+01	Dark Blue
4.822e+01	Very Dark Blue

Equivalent Radiated Power (ERP) calculation

- New option `_ERP` for `*FREQUENCY_DOMAIN_SSD`
 - Fast and simplified way to characterize acoustic behavior of vibrating structures
 - Gives user a good look at how panels contribute to total noise radiation (valuable tool in early phase of product development)
 - Results are saved in binary plot database `d3erp`, and ASCII xyplot files `ERP_abs` and `ERP_dB`



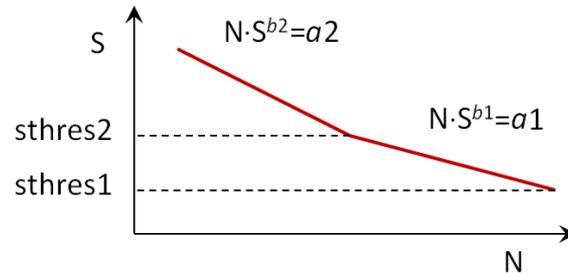
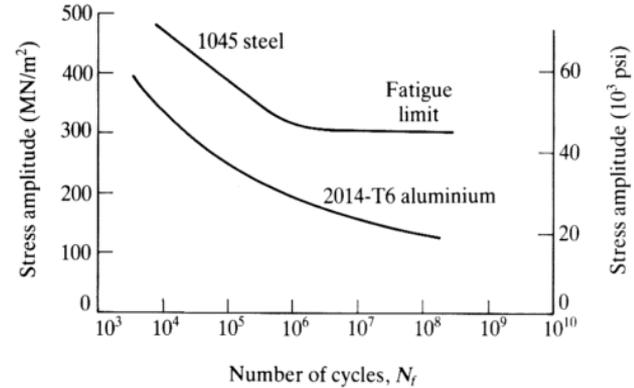
S-N fatigue curves

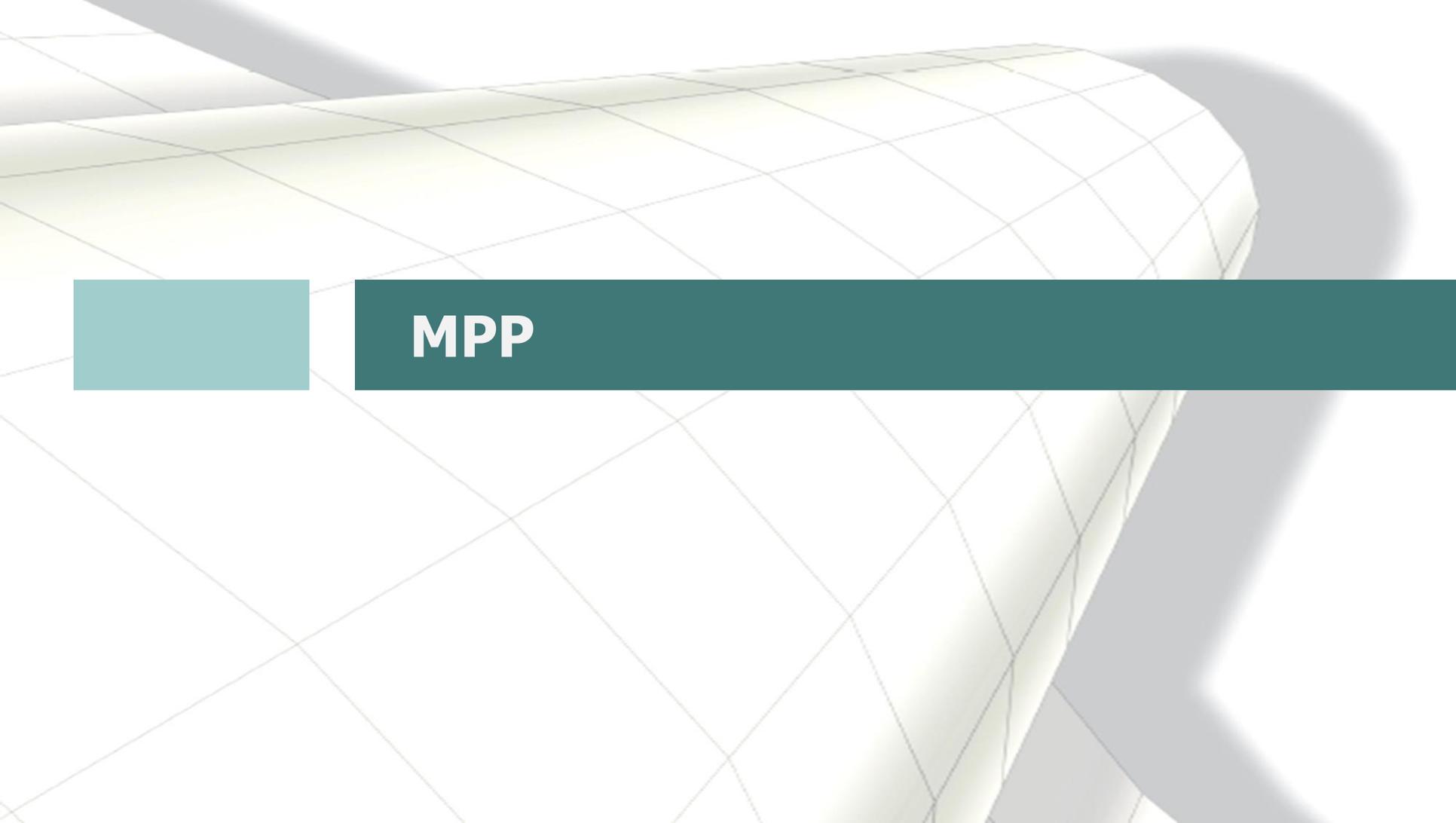
■ New options for *MAT_ADD_FATIGUE

- Implemented multi slope SN curves to be used in random vibration fatigue (*F_D_RANDOM_VIBRATION_FATIGUE) and SSD fatigue (*F_D_SSD_FATIGUE)
- Modular use with other material models
- Either with *DEFINE_CURVE
- Or typical equations:

$$N S^b = a$$

$$\log(S) = a - b \log(N)$$





MPP

MPP related enhancements

- Output two csv files for user to check MPP performance:
 - load_profile.csv: general load balance
 - cont_profile.csv: contact load balance
- The following decomposition related keywords now have a _LOCAL option:
 - *CONTROL_MPP_DECOMPOSITION_PARTS_DISTRIBUTE_LOCAL
 - *CONTROL_MPP_DECOMPOSITION_PARTSET_DISTRIBUTE_LOCAL
 - *CONTROL_MPP_DECOMPOSITION_ARRANGE_PARTS_LOCAL
 - *CONTROL_MPP_DECOMPOSITION_CONTACT_DISTRIBUTE_LOCAL
- memory2=... option on *KEYWORD line
- Allow user to control decomp/distribution of multiple airbags using *CONTROL_MPP_DECOMPOSITION_ARRANGE_PARTS



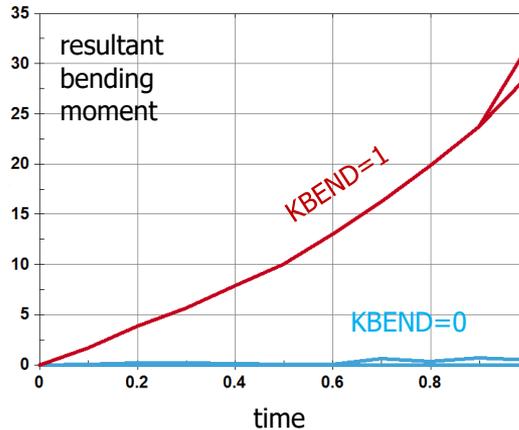
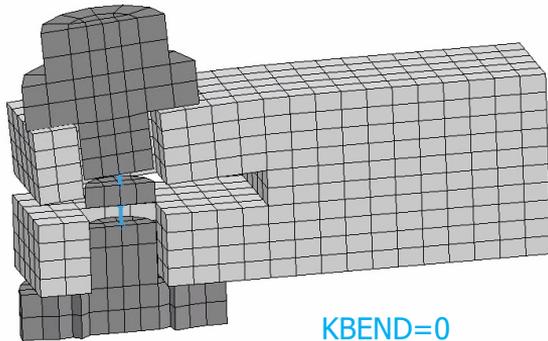
Miscellaneous

Bending stiffness of pre-stressed bolts

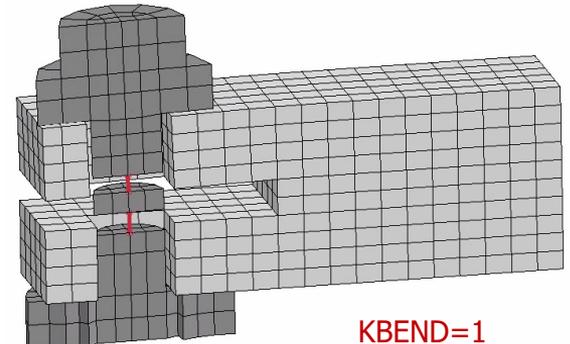
■ New option KBEND on *INITIAL_AXIAL_FORCE

- With KBEND=1, bending stiffness is retained in beam elements that have prescribed axial force
- Uses appropriate modification at each integration point such that the resultant axial force is correct, but the stress gradient remains unchanged
- Recommended in general

Time = 0.00094266

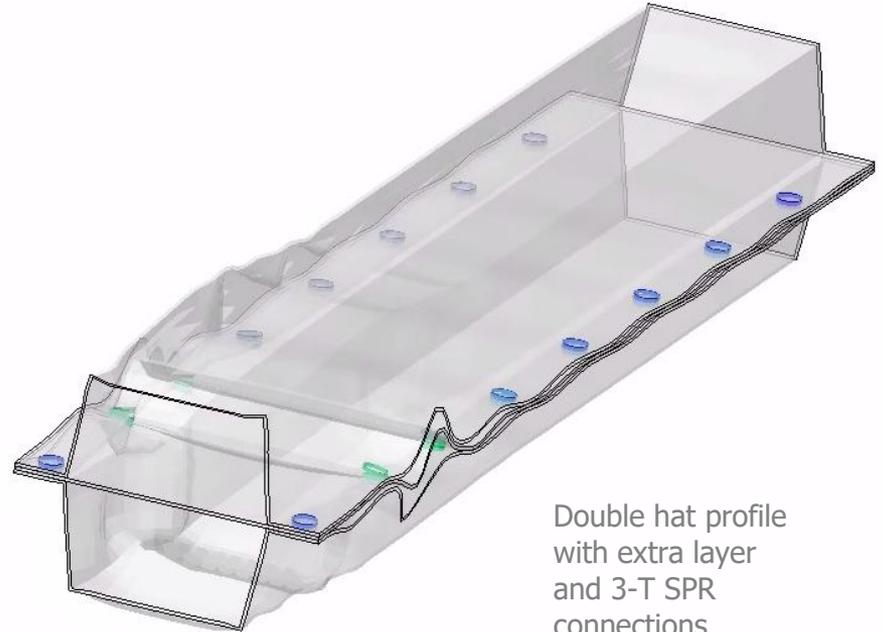
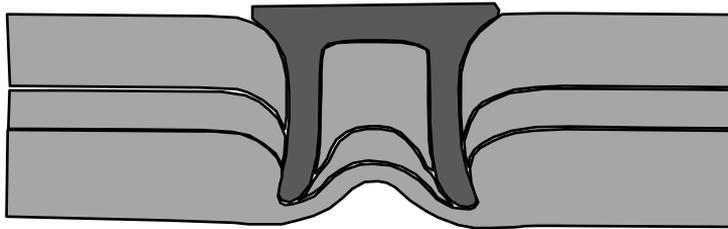


Time = 0.00094266



Multi-sheet SPR

- New option for *CONSTRAINED_SPR2
 - Multi-sheet connection for self-piercing rivets
 - Before: only 2 parts (master and slave)
 - Now: up to 4 additional "extra parts"
 - Question about interdependence of connections and reproduction of experimental results remains open

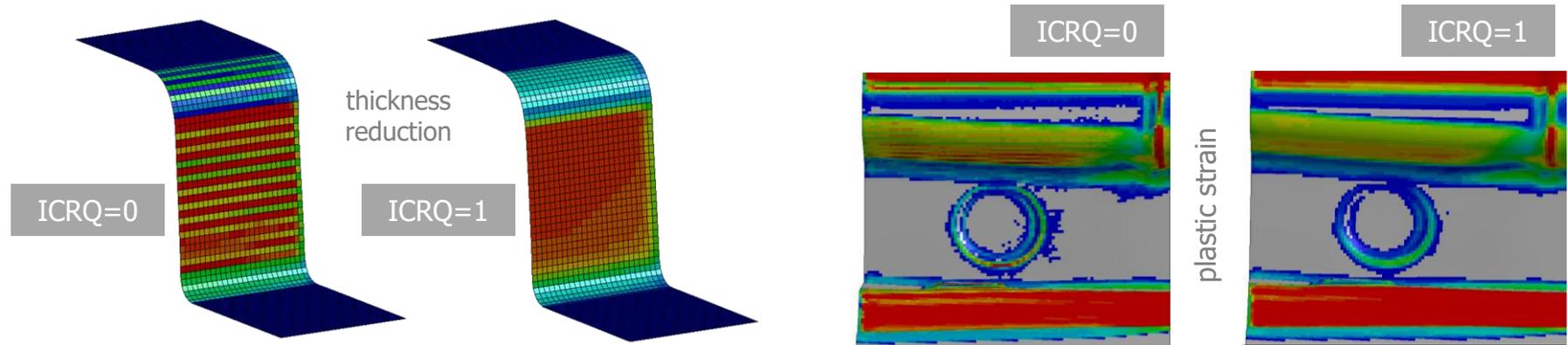


Double hat profile
with extra layer
and 3-T SPR
connections

Continuous result quantities

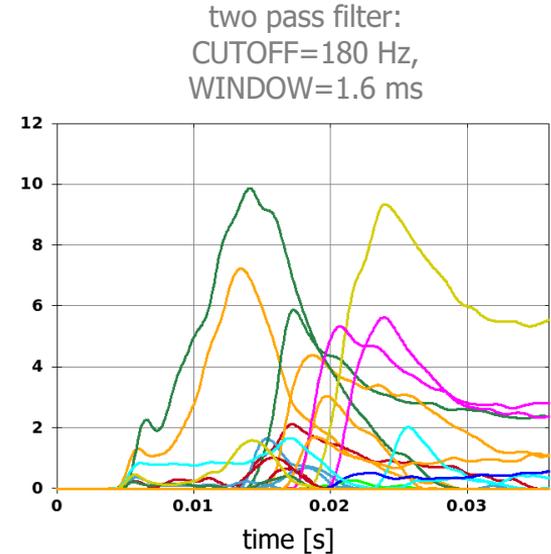
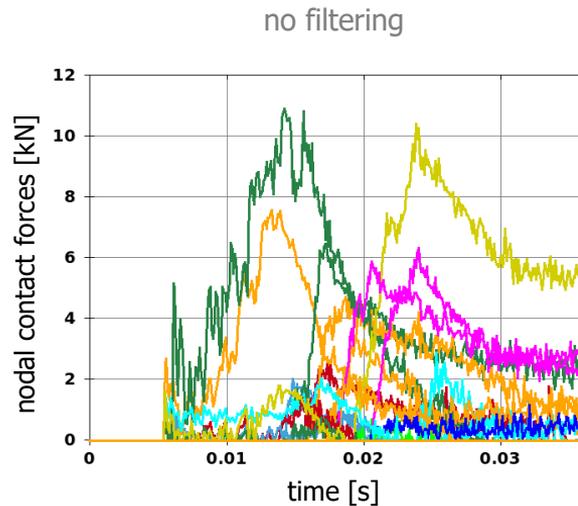
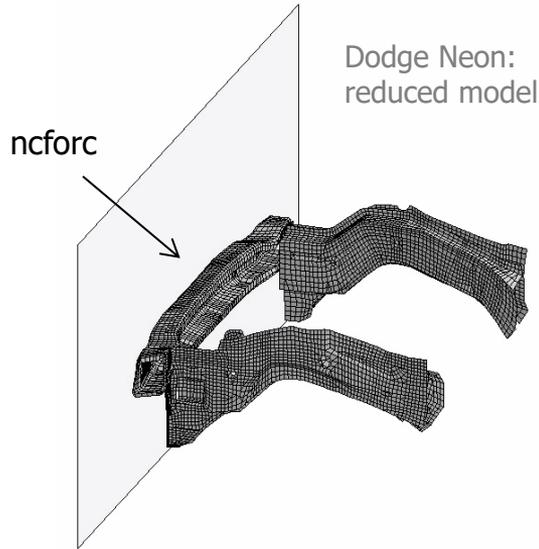
■ New option ICRQ on *CONTROL_SHELL

- Continuous treatment of thickness and plastic strain across element edges for shell element formulations 2, 4, and 16 with max. 9 integration points through the thickness
- Similar to MAT_NONLOCAL, but only direct neighbors are used for node-based smoothing
- Reduces alternating weak localizations sometimes observed in metal forming applications when shell elements get stretch-bended over small radii



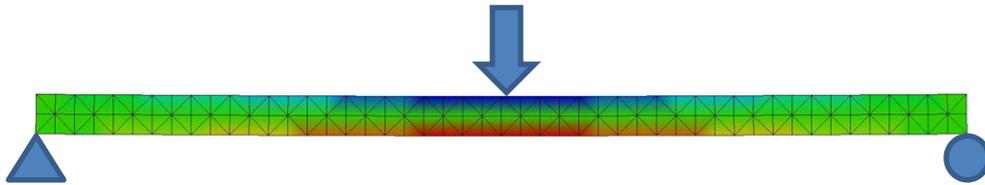
Results filtering

- New options for *DATABASE_BINARY_D3PLOT and *DATABASE_NCFORC
 - Single pass or double pass Butterworth filtering to smooth the output
 - Input parameters are time interval between filter sampling, frequency cut-off, window width



Stress result recovery

- New keyword *DATABASE_RECOVER_NODE
 - Recovers stresses at nodal points by using Zienkiewicz-Zhu's Superconvergent Patch Recovery
 - Available for solid and thin shell elements
 - "x/y/z-Acceleration" in LS-Prepost will be replaced by selected stress measures
 - Generally improves quality of results (accuracy)



Single span beam with concentrated load

Maximum axial stress results

analytical: 6.0

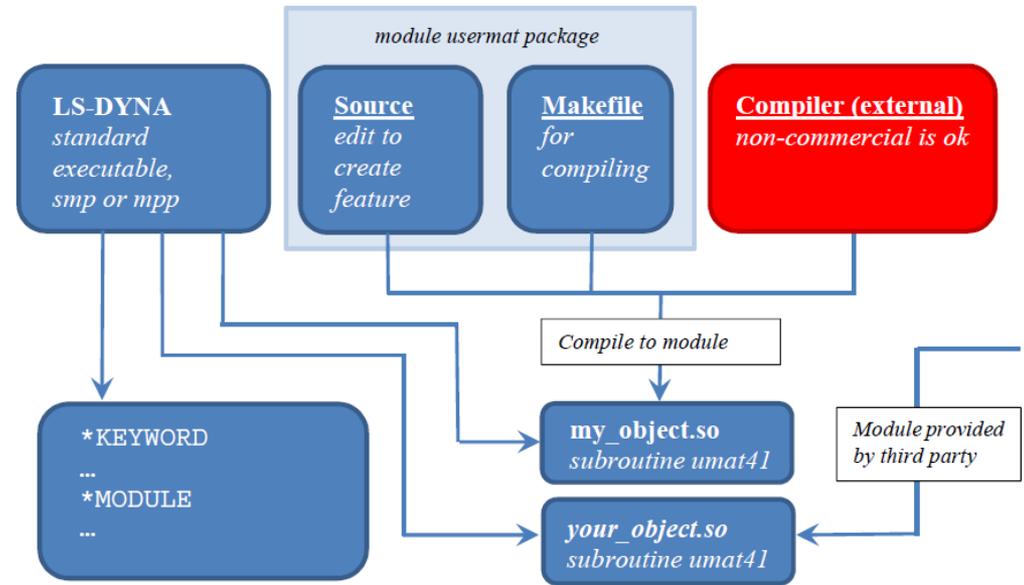
element-based: 5.19 (error = 13.5 %)

recovered node based: 5.96 (error = 0.7 %)

Module Concept for User Defined Features (UDF)

■ Shared object approach and new keyword *MODULE

- To facilitate working with UDFs in that the content of the usermat package is reduced, replaced by *MODULE
- To enhance flexibility when incorporating features delivered as shared objects by third parties
- *MODULE_PATH: specify multiple paths (directories)
- *MODULE_LOAD: load dynamic library (file name)
- *MODULE_USE: define rules for mapping user subroutines to the model



Miscellaneous

- Add ability to specify unique values **LCINT** for each curve
- Add new input check for **quality of rediscretized curves**
- Add new option ***INTERFACE_SPRINGBACK_EXCLUDE** to exclude selected portions from the generated dynain file
- Add ***NODE_THICKNESS** to override usual shell nodal thickness
- Add options MIRROR and POS6N to ***DEFINE_TRANSFORMATION**
- The DELFR flag in ***CONTROL_SHELL** has new options for controlling **deletion of elements**
- New option ICOHED of ***CONTROL_SOLID** to control **cohesive element erosion** when neighboring (nodewise connected) shell or solid elements fail
- New keyword ***CONSTRAINED_RIGID_BODY_INSERT** for modeling “die inserts”
- Add **Rayleigh damping** (***DAMPING_PART_STIFFNESS**) for thick shell formulations 1, 2, 6

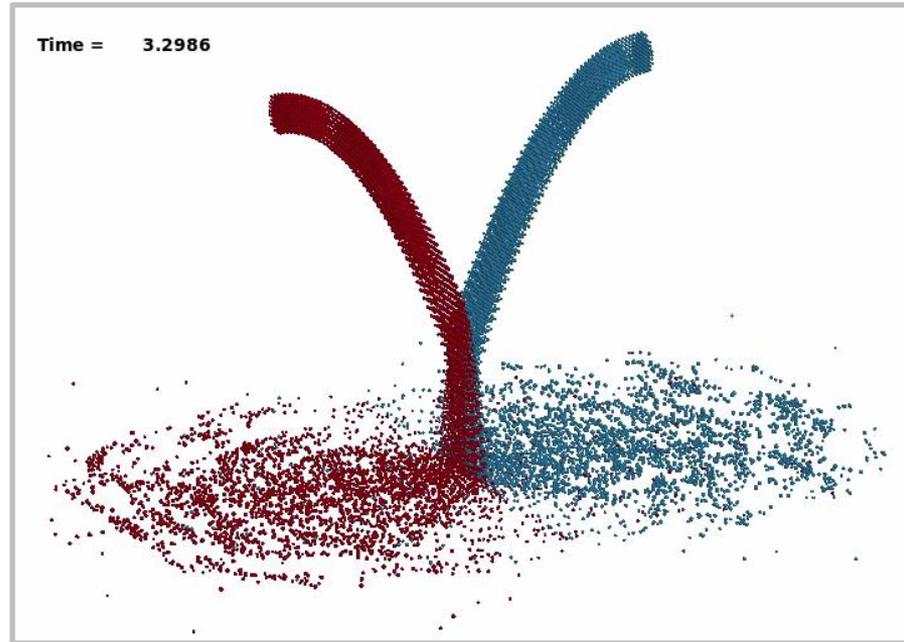


Meshfree methods

SPH particles injection

■ New keyword *DEFINE_SPH_INJECTION

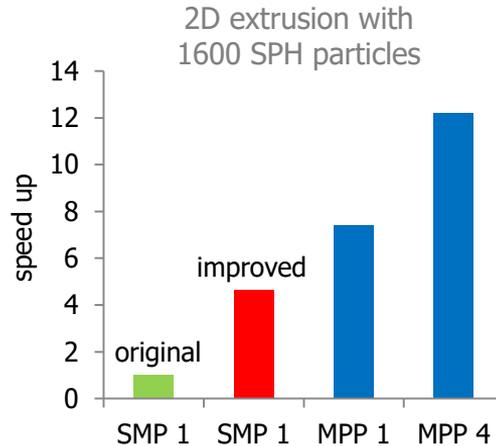
- Injection of SPH elements
automatic generation
of SPH particles
- Multiple injection planes
- User defined
injection speed & area
- Birth and death times
- e.g. for filling simulations



More SPH enhancements

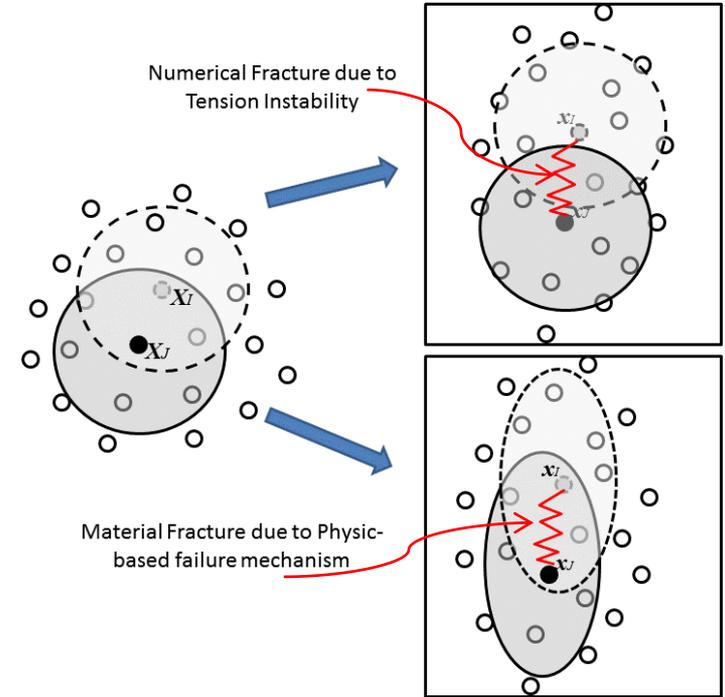
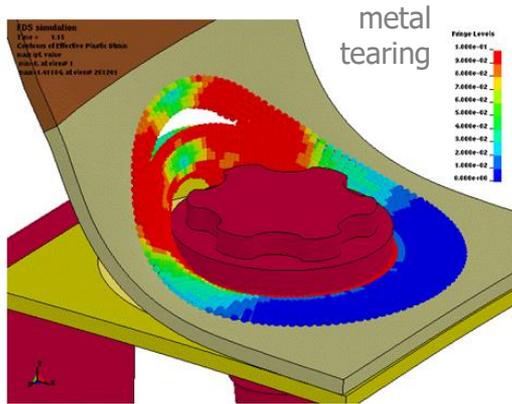
■ Several new features and improvements, e.g.

- *DEFINE_ADAPTIVE_SOLID_TO_SPH now supports 2D →
- New bucket sort algorithm for *CONTACT_2D_NODE_TO_SOLID
- Add support for materials 98, 181, 275
- Add support for OSU=1 (objective stress update)
- Output contact forces between SPH parts into sphout



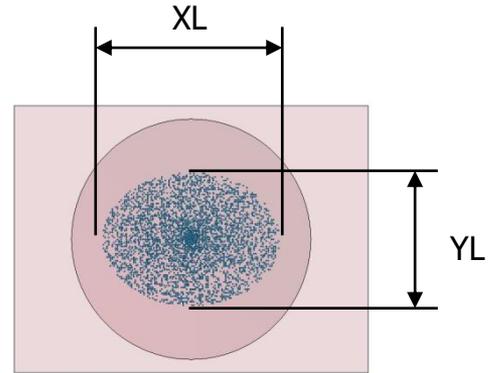
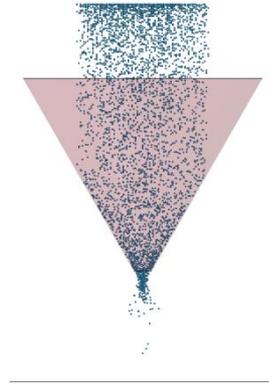
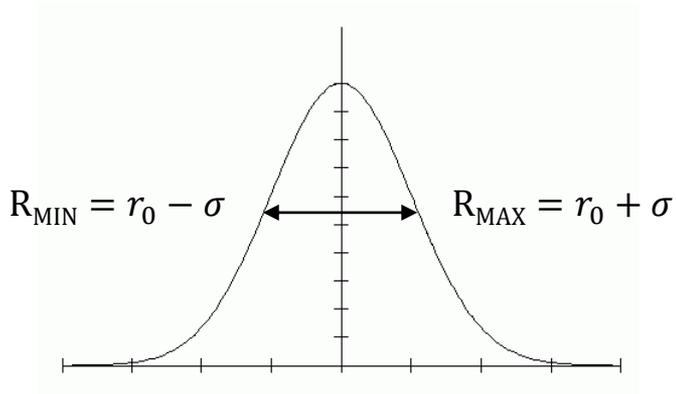
Smoothed Particle Galerkin (SPG)

- Improved physical material fracture
 - Related keyword is *SECTION_SOLID_SPG
 - The dilation parameters of SPG Eulerian kernel are automatically adjusted according to the local material deformation to prevent tensile instability



Discrete Elements (DEM): injection

- New options for *DEFINE_DE_INJECTION
 - Gauss distribution of newly generated particles
 - Option _ELLIPSE to define an elliptical injection region

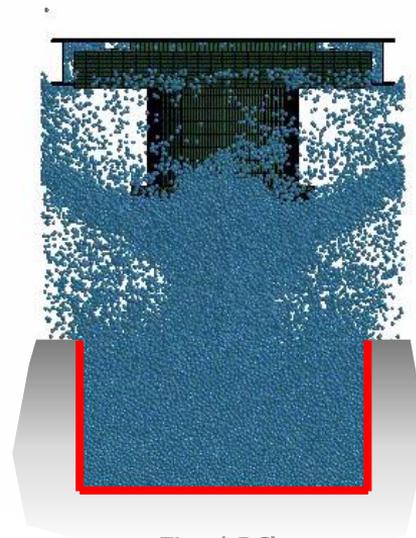


DEM: non-reflecting boundaries

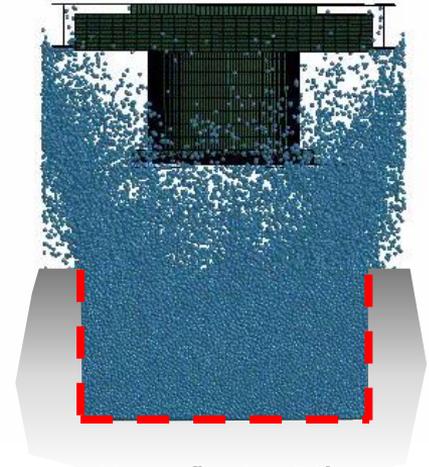
■ New keyword *BOUNDARY_DE_NON_REFLECTING

- Non-reflecting boundary conditions for discrete element spheres
- Used on the exterior boundaries of an analysis model of an infinite domain, such as a half-space
- Prevents artificial stress wave reflections generated at the model boundaries from reentering the model and contaminating the results
- Example: soil buried explosion →

LS-DYNA keyword deck by LS-PrePost
Time = 1.74e+05



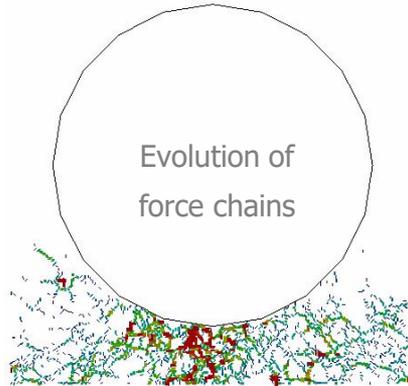
Fixed BC's



Non-reflecting BC's

DEM: output enhancements

- New result quantities for binary and ascii databases
 - Stress, force, pressure, density, force chain, and damage to d3plot
 - Porosity, void ratio, stress, pressure, and density to demtrh (*DATABASE_TRACER_DE)
 - Corresponding values are evaluated for representative volume element (RVE) defined by DE tracer



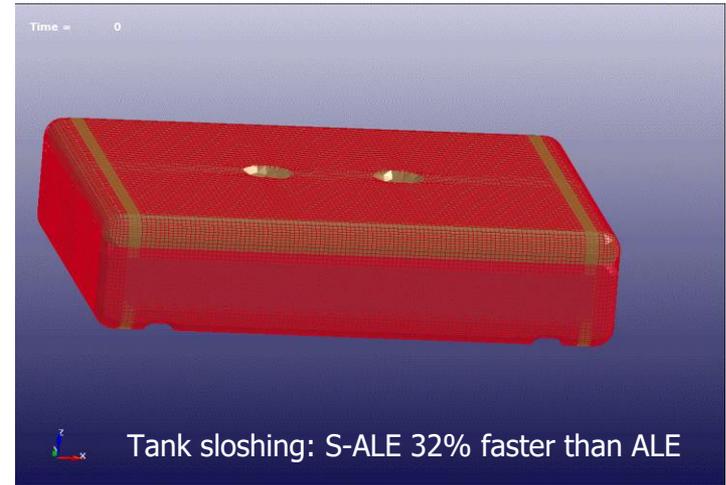
"A force chain consists of a set of particles within a compressed granular material that are held together and jammed into place by a network of mutual compressive forces"



ALE / S-ALE

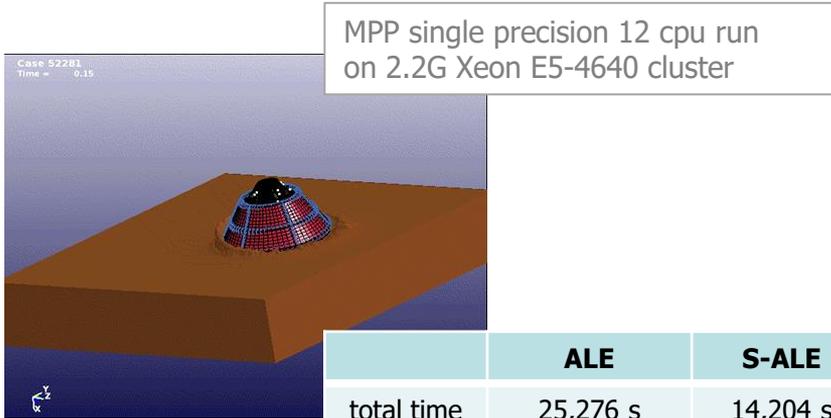
Structured ALE solver (S-ALE)

- Newly implemented scheme for Arbitrary Lagrangian Eulerian method
 - Same theory: advection (remapping), interface reconstruction, FSI - coupling to Lagrange structure
 - Different Implementation: new automated mesh generation, much more compact solver, time saving in searching and sorting, stable and user-friendly
 - Structured ALE mesh automatically generated by *ALE_STRUCTURED_MESH
 - SMP, MPP, MPP-Hybrid supported: Redesigned algorithm enabled SMP parallelization Enhancement on MPP efficiency
 - Documents, Tutorials, Examples on <http://ftp.lstc.com/anonymous/outgoing/hao/sale>

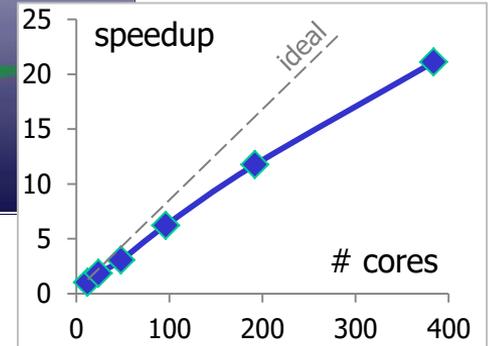
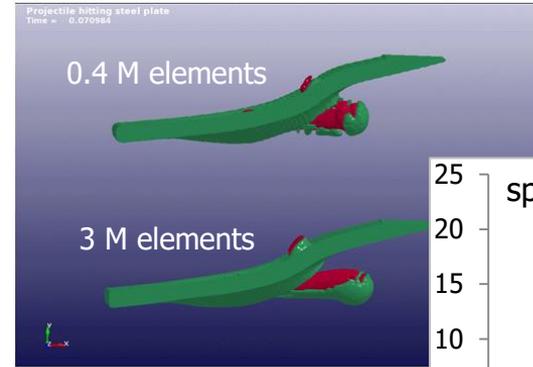


Structured ALE solver (S-ALE)

- Newly implemented scheme for Arbitrary Lagrangian Eulerian method
 - Applications: AWG/Orion problem (left) and oblique long rod penetration (right)

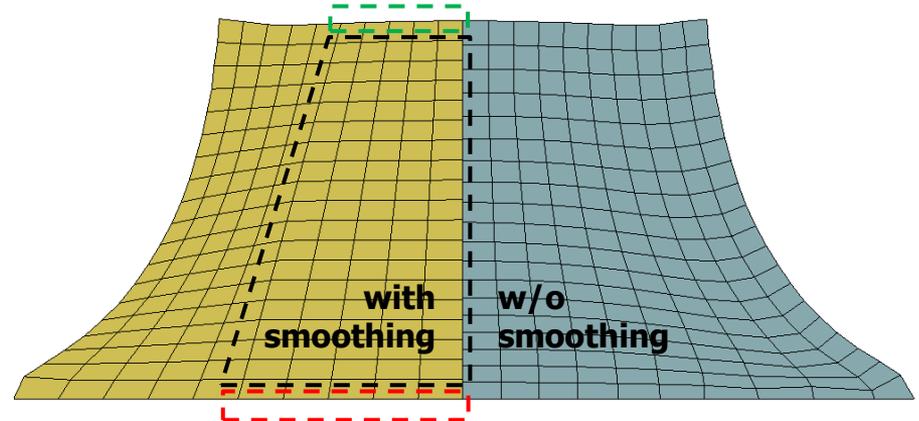
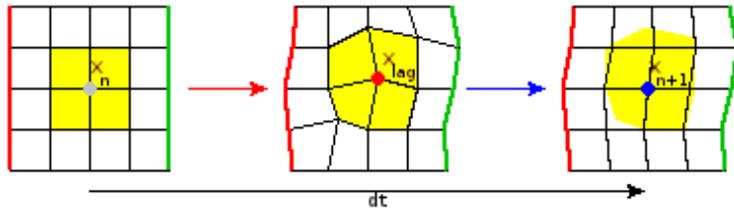


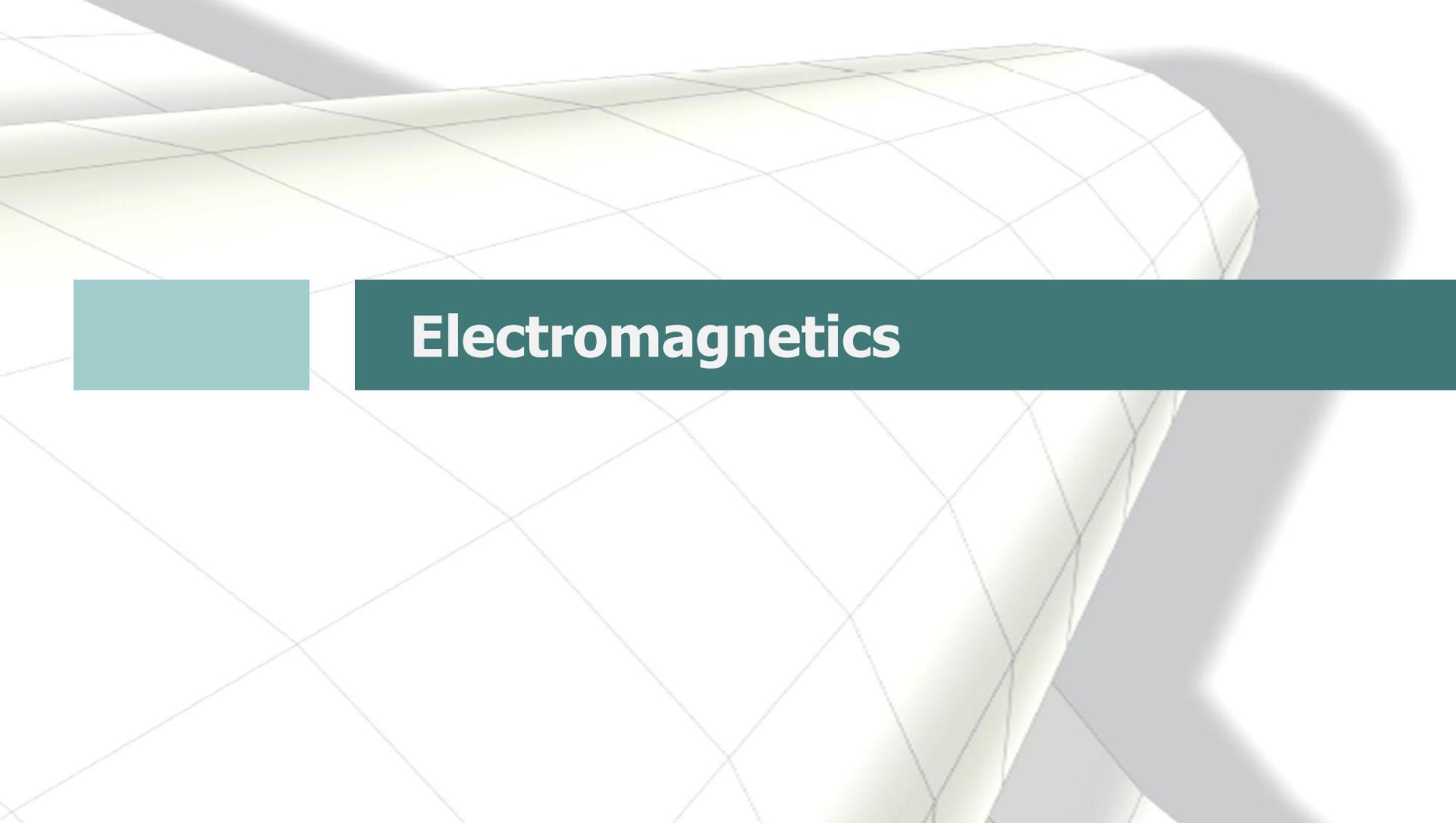
	ALE	S-ALE
total time	25,276 s	14,204 s
advection	11,140 s	5,350 s
FSI	5,746 s	3,983 s
memory	34M	23M



ALE interpolation smoothing

- New keyword *ALE_SMOOTHING for higher mesh quality
 - Smoothing constraint keeps ALE slave nodes at their initial parametric locations between other ALE nodes. If these nodes are not ALE nodes, the slave node has to follow their motion.
 - Supported for ALE solids, ALE shells, and ALE beams



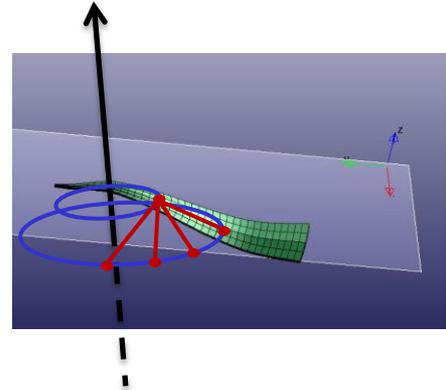
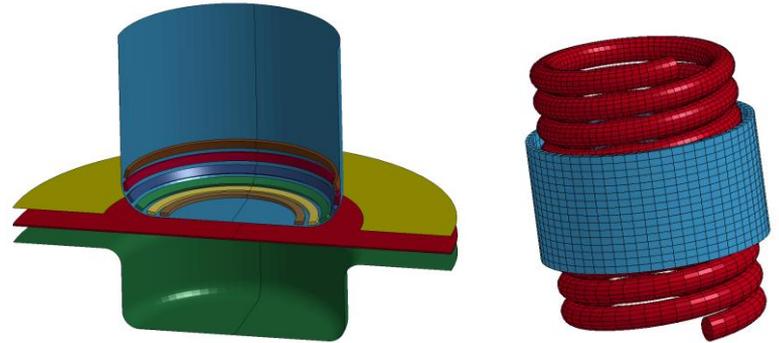


Electromagnetics

Electromagnetics: 2D axisymmetric solver

■ Motivation and Overview

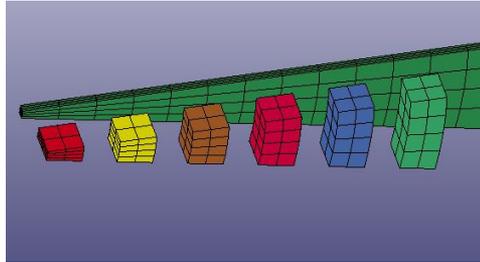
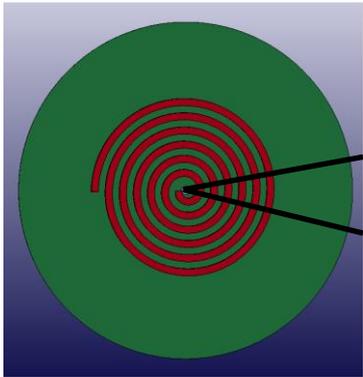
- Many EM models are (quasi) axisymmetric: geometries have cylindrical invariance (coils, field shapers, ...)
- Introduction of EM 2D axisymmetric solver to save computation time
- EM 2D coupled with mechanics and thermal 3D
- User needs to provide a 3D mesh with rotational invariance
- Coupled with 3D mechanics and thermal, hence all the 3D features of LS-DYNA are available
- EM solved by combined FEM + BEM (as in 3D)
- The simulation can be done on a slice of the full 360°, with suitable mechanical and thermal boundary conditions



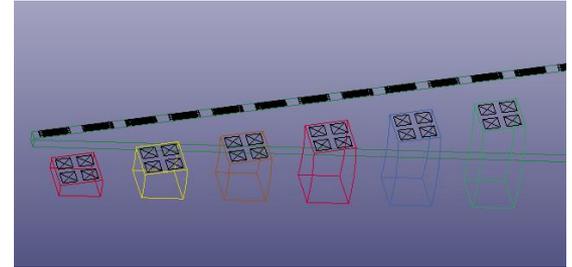
2D axisymmetric EM solver

■ How to set up a 2D axisymmetric case

- New keywords `*EM_2DAXI`, `*EM_CIRCUIT_CONNECT`, `*EM_ROTATION_AXIS`



Slice of the full 360° mesh

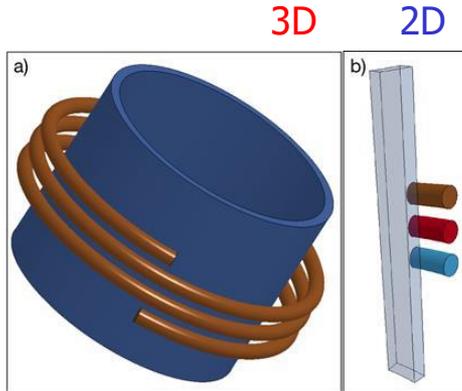


Define mechanical/thermal boundary conditions and electromagnetic properties

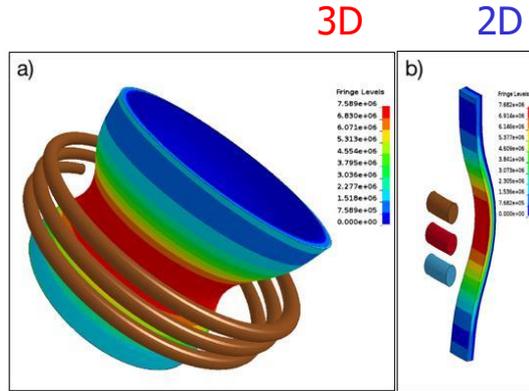
2D axisymmetric EM solver

■ Comparison with 3-dimensional EM solver

- Forming of a tube with a helix coil
- 2D much faster, but same accuracy

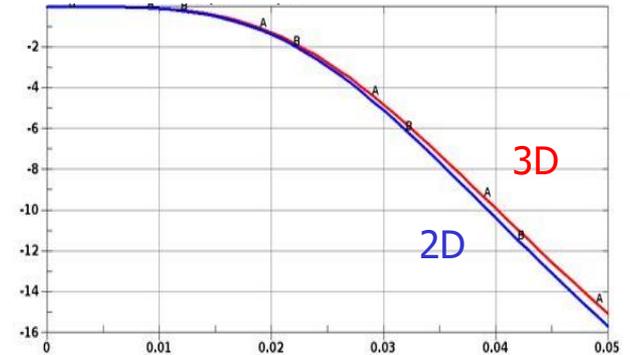


Setup for ring expansion



Current density distribution

Max. displacement vs time



Computation time

3D: 2 hours on 24 cores

2D: 5 minutes on 1 core



CFD & FSI

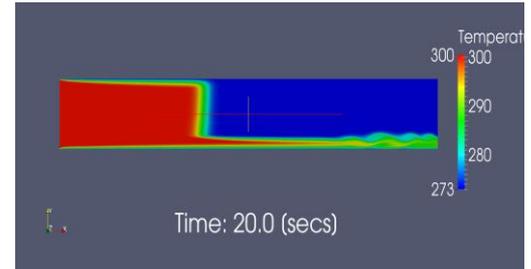
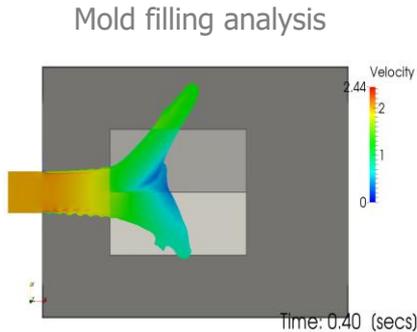
Flow in Porous Media

■ New features for porous media simulations

- Choose between anisotropic Navier-Stokes model and Darcy-Forcheimer model as porous media solver via *ICFD_CONTROL_SOLVE
- Added new porous media models for *ICFD_MODEL_POROUS, e.g. depending on anisotropy and permeability



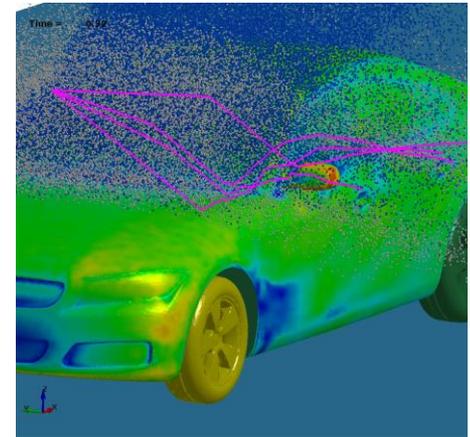
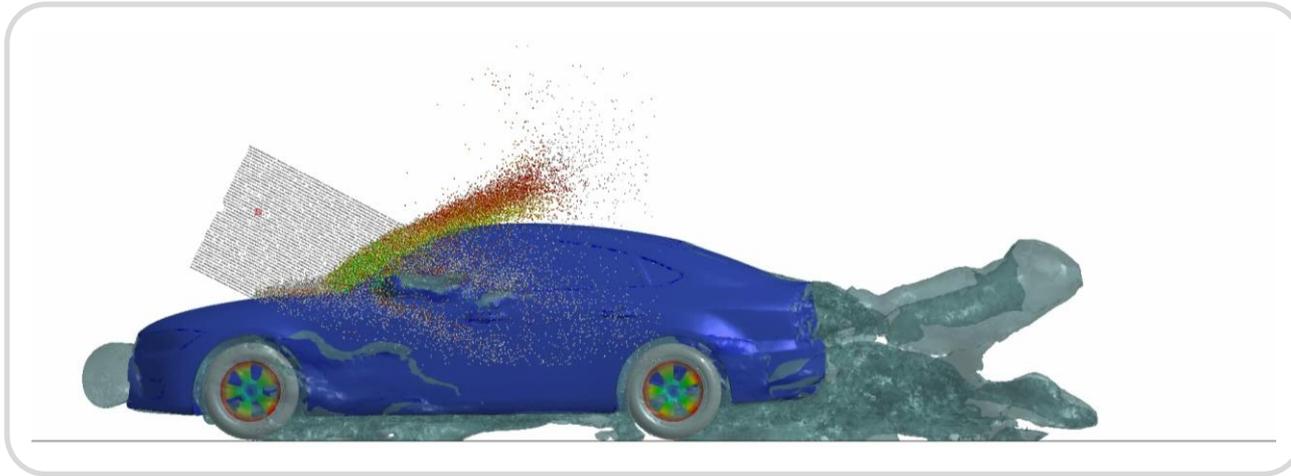
High Reynolds Flow through a car radiator



Heat transfer in a hybrid channel

Coupling with Discrete Elements

- New keyword *ICFD_CONTROL_DEM_COUPLING
 - One-way or two-way coupling between the fluid and the solid particles
 - Allows wide range of applications that include erosion, fracture and particle interaction
 - Example: Water management, rain simulation



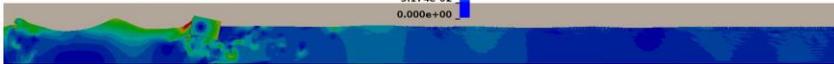
Free surface wave generation

- New inflow boundary condition for wave generation
 - With new keyword `*ICFD_BOUNDARY_FSWAVE`
 - 1st order Stokes waves with free surface
 - Definition of wave amplitude, wave length, and wave incidence angle

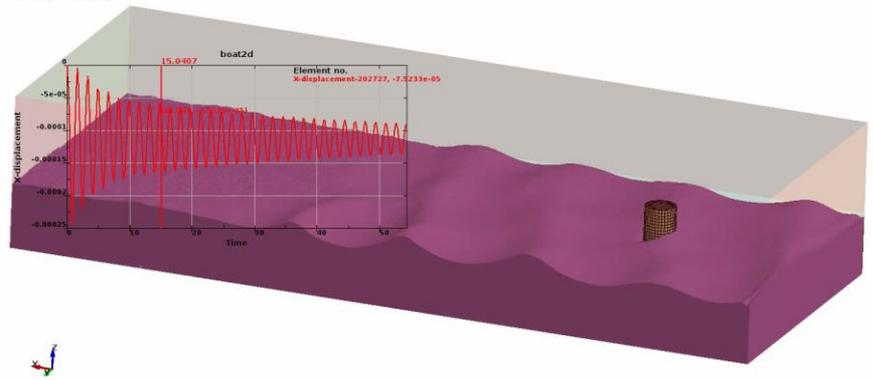
LS-DYNA keyword deck by LS-PrePost
Time = 16.106

Levelset_14
Fluid velocity
8.278e-01
7.760e-01
7.243e-01
6.726e-01
6.208e-01
5.691e-01
5.174e-01
4.656e-01
4.139e-01
3.622e-01
3.104e-01
2.587e-01
2.069e-01
1.552e-01
1.035e-01
5.174e-02
0.000e+00

Boite
Displacement
6.207e-02
5.586e-02
4.966e-02
4.345e-02
3.724e-02
3.104e-02
2.483e-02
1.862e-02
1.241e-02
6.207e-03
0.000e+00

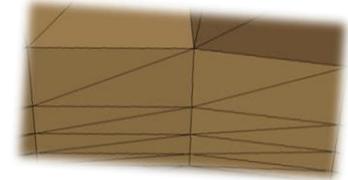


Time = 15.041



More CFD enhancements

- Added new features for *ICFD_CONTROL_TURBULENCE
 - e.g. new turbulence sub-models (Realizable k-epsilon, Standard Wilcox 98/06, SST Menter 2003)
- New keyword *MESH_BL
 - Define a boundary-layer mesh as a refinement on the volume mesh
 - Constructed by subdividing elements near the surface
- New keyword *ICFD_MODEL_NONNEWT
 - Added a few models for non newtonian materials and temperature dependant viscosity, i.a. power law, Carreau, Cross, Herschel-Bulkley, Sutherland, ...
- New option _VOL for *ICFD_DATABASE_DRAG
 - For computing pressure forces on volumes ID (useful for forces in porous domains), output in icfdragivol.dat and icfdragivol.#VID.dat





CESE

Compressible CFD Solver (CESE)

- New energy conservative conjugate heat transfer method
 - Standard conjugate-heat transfer (CHT) methods for compressible flows do not conserve energy, this leads to time-dependent errors in such simulations.
 - A class of new energy-conservative conjugate-heat transfer (CHT) methods for compressible flows has been developed recently (Radenac et al. 2014).
 - Now implemented in 3 different sets:
 - 1) Fixed mesh (both structure and fluid) CESE Navier-Stokes solvers.
 - 2) Moving mesh CESE Navier-Stokes FSI solvers.
 - 3) Immersed boundary method (IBM) Navier-Stokes FSI solvers
 - Unique features include:
 - A unified treatment of space and time
 - The introduction of the conservation element and the solution element as a vehicle for enforcing space-time flux conservation, locally and globally.
 - A novel shock capturing strategy without a Riemann solver.
 - Unlike conventional schemes, flow variables and their derivatives are solved simultaneously.

Compressible CFD Solver (CESE)

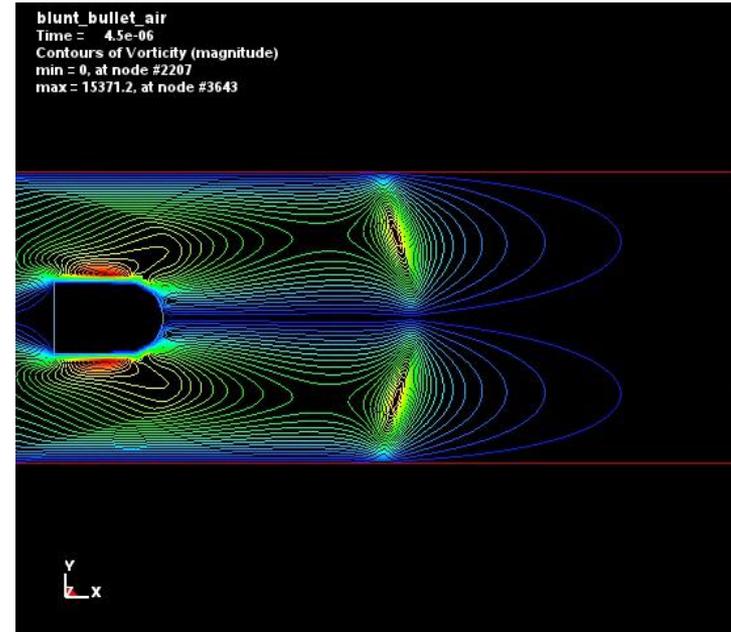
■ New energy conservative conjugate heat transfer method

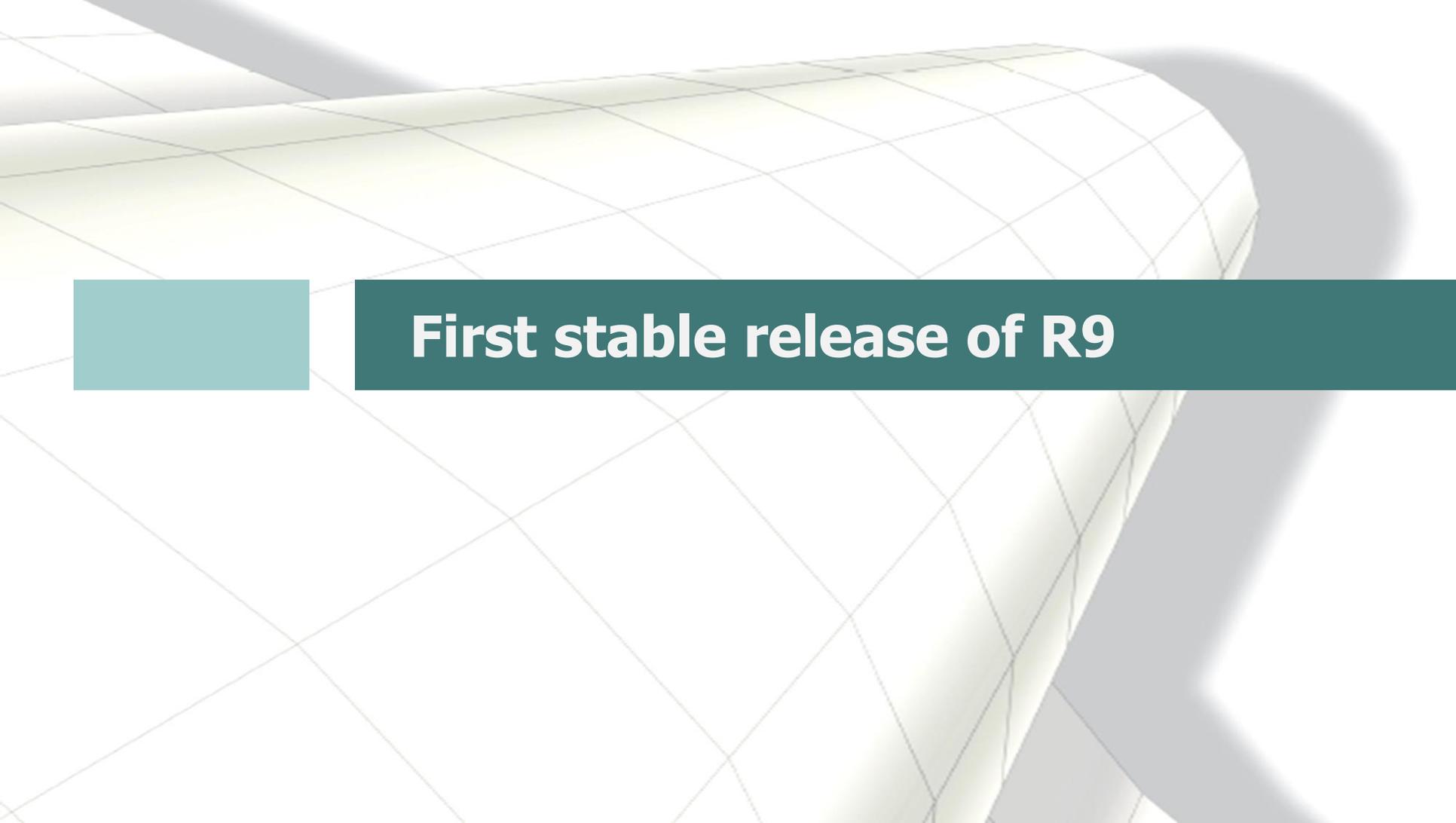
■ Advantages

- Permits CESE to maintain its energy conservation property
- Efficient: the boundary condition remains local
- Robust: fluid and structure solutions advance independently, with the heat flux being accumulated to pass to the structural thermal solver

■ Example: 2D Blunt bullet problem

■ Fluid vorticity





First stable release of R9

Bug fixes

- A wide range of code corrections, inter alia,
 - Correct calculation of wrap angle in seatbelt retractor
 - Fixed thick shell forms 3 and 5 when used in implicit solutions with non-isotropic materials
 - Fix possible issue related to constrained contacts in MPP implicit not initializing properly
 - Fixed stress initialization (*INITIAL_STRESS_SECTION) for type 13 tetrahedral elements
 - Fix for the combination of type 13 tet elements and *INITIAL_STRESS_SOLID
 - Fixed issues involving *LOAD_THERMAL_D3PLOT
 - Fixed the TRUE_T option on *MAT_100 and *MAT_100_DA
 - Correct/improve material tangent for *MAT_181 with PR>0 (foam option)
 - Fix for D3PLOT output of very large data sets in single precision
 - Fixes for writing and reading of dynain data in LSDA format
 - Fix thick shells stress/strain output to dynain
 - Fix a bug that occurs when *DEFINE_BOX is included by *INCLUDE_TRANSFORM
 - ...

... find more in release notes:

<http://www.dynasupport.com/news/ls-dyna-r9.0.1-r9.109912-released>



Conclusion: LS-DYNA R9.0.1

- Newest release contains variety of new features
- Recommended for multiphysics and implicit analyses or if new options are needed
- R9 Keyword User's Manual can be downloaded from www.dynamore.de/en/downloads/manuals