WORKSHOP Introduction to material characterization

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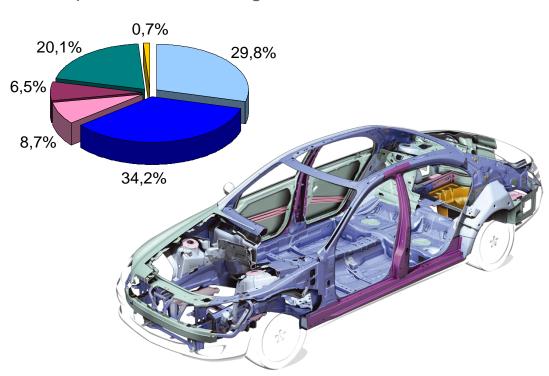
15th German LS-DYNA Forum 2018

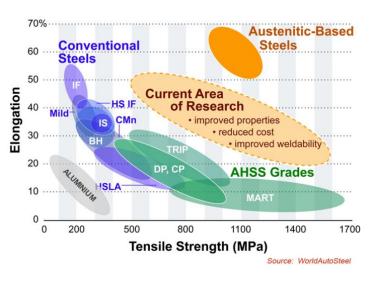
Bamberg, October 15, 2018



Motivation

Example of material usage in a modern car



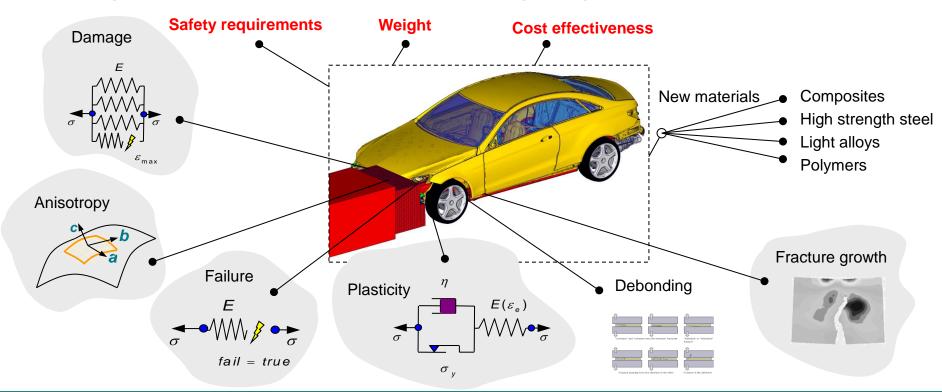


- Deep drawing steels
 - High strength steels
 - Very high strength steels
 - Ultra high strength steels
- Aluminum
- Polymers



Motivation

Challenges in the automotive industry for efficient lightweight structures



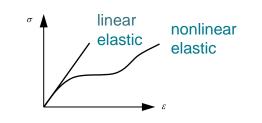


Rheological models

Stress-strain relationship

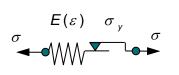
Elasticity

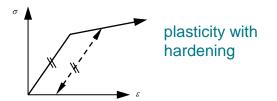
- Linear / nonlinear stress-strain relationship
- Loading and unloading paths identical
- Stress is a function of the strain
- Reversible deformations
- Elastic straining is non-isochoric for metals



Plasticity

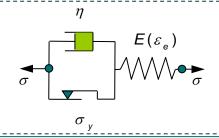
- Elastic behavior until yielding
- Irreversible deformations
- Hardening/softening behavior possible
- Isochoric for metals

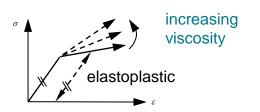




Viscoplasticity

- Stress states outside the yield surface activate viscoplastic response
- Relaxation of overstress over time
- Limiting cases are elasticity and plasticity

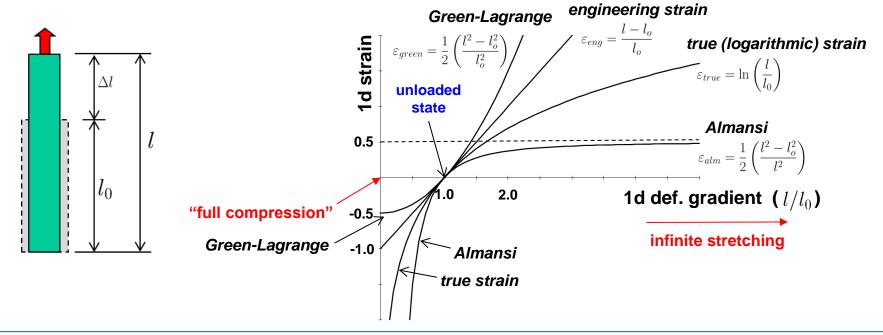






Strain measures

- For small deformations the strain measures is indifferent, all deliver the same result
- For large or finite deformations the strain measure depends on the type of problem, mathematical convenience, etc.



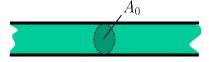


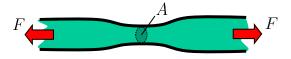
Stress measures

One-dimensional case

• in one dimension, the engineering and true stress measures are the most commonly used in practical engineering:

$$\sigma_{eng} = \frac{F}{A_o}$$
 $\sigma_{true} = \frac{F}{A}$





assuming an isochoric deformation (i.e., constant volume), the true stress may be expressed as:

$$\sigma_{true} = \frac{F}{A} = \frac{F}{A_0} \frac{A_0}{A} \stackrel{Al=A_0l_0}{=} \frac{F}{A_0} \frac{l}{l_0} = \sigma_{eng} (1 + \varepsilon_{eng})$$

 in the three dimensional case, the above stress measures are generalized to tensorial quantities of second order, where other stress tensors are also relevant, e.g., the second Piola-Kirchhoff, the Kirchhoff stress tensor, etc.

Stress measures

Some useful relations regarding the stress tensor

The true stress tensor is symmetric and can be split in two parts

$$\boldsymbol{\sigma} = \begin{bmatrix} \sigma_{11} & \sigma_{12} & \sigma_{13} \\ \sigma_{22} & \sigma_{23} \\ \sigma_{33} \end{bmatrix} = \mathbf{s} + \frac{1}{3} \mathrm{tr}(\boldsymbol{\sigma}) \, \mathbf{I} = \begin{bmatrix} s_{11} & s_{12} & s_{13} \\ s_{22} & s_{23} \\ s_{33} \end{bmatrix} - p \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$
Change in shape, but not in volume but not in shape but not in shape hut not

The principal stress tensor and its invariants

$$oldsymbol{\sigma} = egin{bmatrix} \sigma_1 & 0 & 0 \ 0 & \sigma_2 & 0 \ 0 & 0 & \sigma_3 \end{bmatrix} \qquad egin{array}{l} I_1 = \sigma_1 + \sigma_2 + \sigma_3 \ I_2 = \sigma_1 \sigma_2 + \sigma_2 \sigma_3 + \sigma_1 \sigma_3 \ I_3 = \sigma_1 \sigma_2 \sigma_3 \end{array}$$

$$J_1 = s_1 + s_2 + s_3 = 0$$

$$J_2 = \frac{1}{6} \left[(\sigma_1 - \sigma_2)^2 + (\sigma_2 - \sigma_3)^2 + (\sigma_3 - \sigma_1)^2 \right]$$

$$J_3 = s_1 s_2 s_3 = \frac{2}{27} I_1^3 - \frac{1}{3} I_1 I_2 + I_3$$

The equivalent or von Mises stress is defined as

$$\sigma_{eq} = \sqrt{3J_2} = \sqrt{\frac{1}{2}} \left[(\sigma_1 - \sigma_2)^2 + (\sigma_2 - \sigma_3)^2 + (\sigma_3 - \sigma_1)^2 \right]$$



Constitutive law

The relation between stress and strain

- the constitutive law defines the response of a given material to external loads
- within the framework of continuum mechanics, the constitutive law is the relation between the strains and stresses in a material point, which in the general three-dimensional case can be expressed as

$$oldsymbol{\sigma} = \mathbb{D} : oldsymbol{arepsilon} \qquad \qquad oldsymbol{\phi} = egin{bmatrix} \sigma_{11} & \sigma_{12} & \sigma_{13} \ \sigma_{21} & \sigma_{22} & \sigma_{23} \ \sigma_{31} & \sigma_{32} & \sigma_{33} \end{bmatrix}, \; oldsymbol{arepsilon} = egin{bmatrix} arepsilon_{11} & arepsilon_{12} & arepsilon_{13} \ arepsilon_{21} & arepsilon_{22} & arepsilon_{23} \ arepsilon_{31} & arepsilon_{32} & arepsilon_{33} \end{bmatrix}$$

Constitutive operator

 for a uniaxial stress state and an elastic material with Young's modulus E, the equation above can be reduced to

$$\sigma = E \varepsilon^e$$

- for most materials, the constitutive law is nonlinear and a function of other variables such as plastic strain, strain rate, temperature, etc.
- when you define the material parameters (e.g., hardening curve) for a material model in LS-DYNA, you are actually indirectly prescribing the constitutive law



Material modeling in LS-DYNA

A selection of LS-DYNA material models based on von Mises plasticity

- *MAT_PLASTIC_KINEMATIC (#003)
 Von Mises based model with bilinear isotropic and kinematic hardening
- *MAT_PIECEWISE_LINEAR_PLASTICITY (#024)

 Von Mises based elasto-plastic material model with isotropic hardening and strain rate effects;

 One of LS-DYNA's most used material models



Simple plasticity model

*MAT_PLASTIC_KINEMATIC (*MAT_003)



*MAT 003

*MAT PLASTIC KINEMATIC

This is a bilinear elasto-plastic model which accounts for kinematic, isotropic or mixed hardening. Strain rate dependence can be considered and element deletion can be activated. It is a very simple and very fast material model that can be used to model plasticity in a simplified way.

*MAT	_PLASTIC	C_KINEMATIC					
\$	MID	RO	E	PR	SIGY	ETAN	BETA
, 	5	7.86E-6	210.0	0.33	310.0	50.0	0.5
\$	SRC	SRP	FS	VP			
! ! !	5.0						P
							0.5 P'
• SI	GY:	Yield stress	8				*
■ E	TAN:	Tangent mo	odulus				\ \

ETAN: Tangent modulus

BETA: Hardening parameter (isotropic/kinematic hardening)

SRC, SRP: Strain rate parameter C and P for *Cowper Symonds* strain rate model

Failure strain for eroding elements

Formulation for rate effects



Isotropic plasticity model

*MAT_PIECEWISE_LINEAR_PLASTICITY (*MAT_024)



*MAT_024

Keyword definition

\$ MID	RO	E	PR	SIGY	ETAN	FAIL	TDEL
1	7.85E-06	210.0	0.3		i		
\$ С	P	LCSS	LCSR	VP			
		100		1			
\$ EPS1	EPS2	EPS3	EPS4	EPS5	EPS6	EPS7	EPS8
\$ ES1	ES2	ES3	ES4	ES5	ES6	ES7	ES8

MID: Material identification

RO: Density

E: Young's modulus

PR: Elastic Poisson's ratio

SIGY: Yield stress (in case of linear hardening)

ETAN: Hardening modulus (in case of linear hardening)



*MAT_024

Keyword definition

*MAT	_PIECEW	ISE_LINEAR_	PLASTICITY					
\$	MID	RO	E	PR	SIGY	ETAN	FAIL	TDEL
	1	7.85E-06	210.0	0.3				
\$	С	P	LCSS	LCSR	VP			
			100		1			
\$	EPS1	EPS2	EPS3	EPS4	EPS5	EPS6	EPS7	EPS8
\$	ES1	ES2	ES3	ES4	ES5	ES6	ES7	ES8

- EPS1-EPS8: Effective plastic strain values (optional, supersedes SIGY and ETAN)
- ES1-ES8: Corresponding yield stress values to eps1-eps8

*MAT 024

Keyword definition

\$	MID	RO	E	PR	SIGY	ETAN	FAIL	TDEL
	1 7	.85E-06	210.0	0.3		i		
3	С	P	LCSS	LCSR	VP	_		
			100		1			
	EPS1	EPS2	EPS3	EPS4	EPS5	EPS6	EPS7	EPS8
	ES1	ES2	ES3	ES4	ES5	ES6	ES7	ES8

FAIL: Failure flag

■ TDEL: Minimum time step size for automatic element deletion

C, P: Strain rate parameters C and P for Cowper-Symonds strain rate model

LCSS: Load curve or table ID (yield curve, supersedes SIGY and ETAN)

LCSR: Load curve ID defining strain rate effects on yield stress

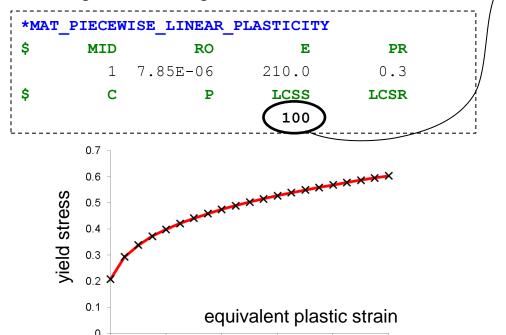
VP: Formulation for rate effects (1 for viscoplastic formulation)

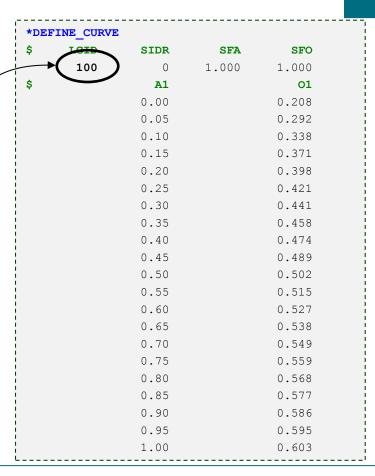


*MAT_024

Working with load curves

Defining a hardening curve in *MAT_024







0.2

0.4

0.6

0.8

1.0

0.0

*MAT 024

Some general remarks on *MAT_PIECEWISE_LINEAR_PLASTICITY

- "Work horse" in crash simulations
- Available for shells and solids
- Load curve based input makes this material model very flexible
- No kinematic hardening is considered (*MAT_225 is similar to *MAT_024, but allows the definition of kinematic hardening)
- Unless viscoplasticity (i.e., VP=1) is activated, the plasticity routine does not iterate (works very well in explicit, possibly problematic for large steps in implicit analysis)
 - Recommended for **implicit**:
 Set IACC=1 in *CONTROL_ACCURACY
 to make *MAT_024 always iterate

- The points between the rate-dependent curves are interpolated, either linearly or logarithmically
- The load curves are extrapolated in the direction of plastic strain by using the last slope of the curve
- No extrapolation is done in the direction of strain rate, i.e., the lowest (highest) curve defined is used if the current strain rate lies under (above) the input curves
- Negative and zero slopes are permitted but should generally be avoided

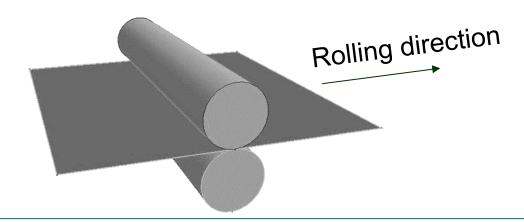


Anisotropic Plasticity

Anisotropy of metal sheets

Deformation induced anisotropy

- Metals may show anisotropic behavior due to previous loading and irreversible deformations (classical phenomenon of plasticity)
- Most prominent examples are forming and stamping processes where major and minor plastic strains develop in areas where high deformation occurs
- Also pre-stretching of steel parts (rods, tubes, etc.) leads to anisotropy
- Anisotropy is usually characterized by the Lankford parameter





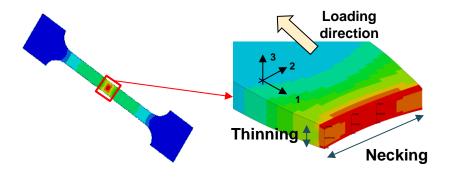
Anisotropy of metal sheets

The Lankford parameter (R-value)

Definition

$$R = \frac{\dot{\varepsilon}_{22}^p}{\dot{\varepsilon}_{33}^p} = -\frac{\dot{\varepsilon}_{22}^p}{\dot{\varepsilon}_{11}^p + \dot{\varepsilon}_{22}^p}$$

Interpretation



$$R = 1.0$$
 \rightarrow $\dot{\varepsilon}_{22}^p = \dot{\varepsilon}_{33}^p$

 $R=1.0 \rightarrow \dot{\varepsilon}_{22}^p = \dot{\varepsilon}_{33}^p \longrightarrow \text{Necking and thinning are comparable}$

$$R < 1.0$$
 \rightarrow

$$_{22}^{p}<\dot{arepsilon}_{33}^{p}\qquad --$$

R < 1.0 \rightarrow $\dot{\varepsilon}_{22}^p < \dot{\varepsilon}_{33}^p$ — Less necking, **More thinning**

$$\dot{\varepsilon}_{22}^p > \dot{\varepsilon}_{33}^p$$

R>1.0 ightarrow $\dot{arepsilon}_{22}^p>\dot{arepsilon}_{33}^p$ — More necking, Less thinning

$$R_{00} = R_{45} = R_{90} = 1$$

Isotropic material

$$R_{00} = R_{45} = R_{90} \neq 1$$

 $R_{00} = R_{45} = R_{90} \neq 1$ — Anisotropic behavior in thickness direction

$$R_{00} \neq R_{45} \neq R_{90}$$

$$\longrightarrow$$

Anisotropic behavior in the plane and in thickness direction

Material modeling in LS-DYNA

A selection of anisotropic elasto-plastic models

*MAT_3-PARAMETER_BARLAT (#036)
 Anisotropic plasticity model based on Barlat and Lian (1989)



- *MAT_TRANSVERSELY_ANISOTROPIC_ELASTIC_PLASTIC (#037)
 Elasto-plastic model for transverse anisotropy
- *MAT_ ORTHO_ELASTIC_PLASTIC (#108)
 Orthotropic material model in both elasticity and plasticity
- *MAT_HILL_3R (#122)
 Hill's 1948 planar anisotropic material model with 3 R-values
- *MAT_BARLAT_YLD2000 (#133)
 Elasto-plastic anisotropic plasticity model based on Barlat 2000
- *MAT_WTM_STM (#135) Anisotropic elasto-plastic model based on the work of Aretz et. al (2004)
- *MAT_CORUS_VEGTER (#136)
 Anisotropic yield surface construction based on the interpolation by second-order Bezier curves



Anisotropic plasticity model

*MAT_3-PARAMETER_BARLAT (*MAT_036)



*MAT_036

*MAT_3-PARAMETER_BARLAT

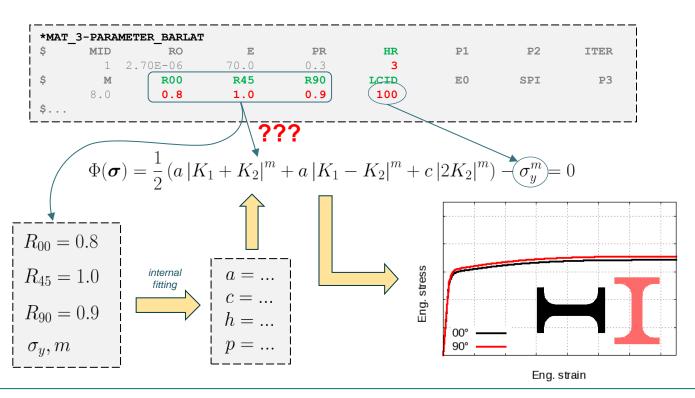
*MA	r_3-para	METER_BARLA	T						
\$	MID	RO	E	PR	HR	P1	P2	ITER	i
i I	1	7.85E-06	210.0	0.3	3				
\$	M	R00/AB	R45/CB	R90/HB	LCID	E0	SPI	Р3	
!	8.0	0.8	0.9	1.1	100				, ,
\$	AOPT	С	P	VLCID		PB	NLP/HTA	HTB	i
l I	2								
\$				A1	A2	A3	HTC	HTD	
				1.00	0.0	0.0			i
; \$	V1	V2	v3	D1	D2	D3	BETA		i
I I				0.0	0.0	0.0			! !

■ MID:	Material identification	■ P2:	Material parameter #2	■ HB:	Parameter 'h' of yield function
RO:	Density	ITER:	Iteration flag	■ R00:	R-Value in 0° degree direction
■ E:	Young's modulus	■ M:	Exponent for yield surface	R 45:	R-Value in 45° degree direction
PR:	Elastic Poisson's ratio	■ AB:	Parameter 'a' of yield function	R 90:	R-Value in 90° degree direction
■ HR:	Hardening rule	CB:	Parameter 'c' of yield function	LCID:	Load curve or table if HR=3
■ P1:	Material parameter #1				



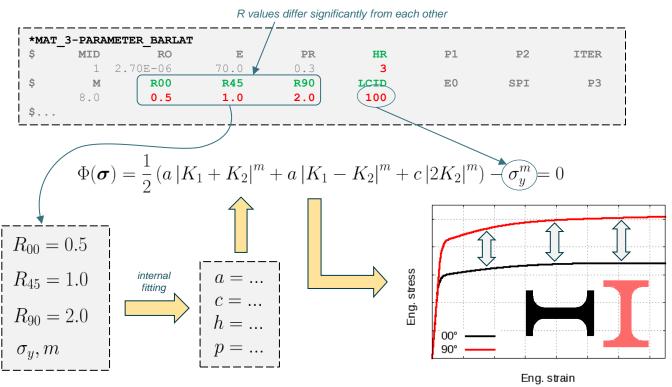
*MAT_036 + HR=3

The original Barlat & Lian formulation (1989)



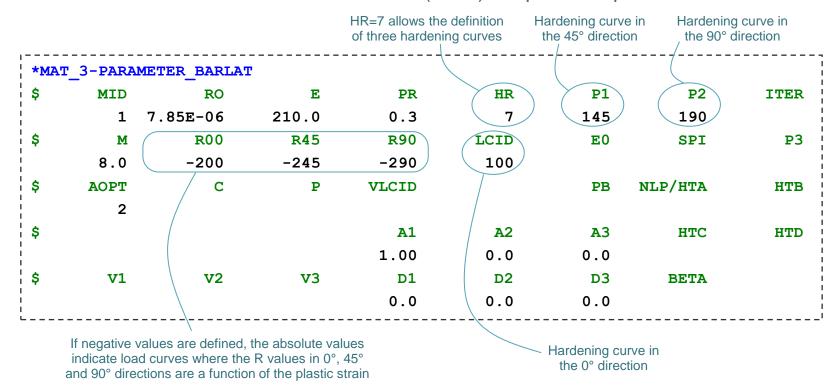
*MAT_036 + HR=3

The original Barlat & Lian formulation (1989)



*MAT 036 + HR = 7

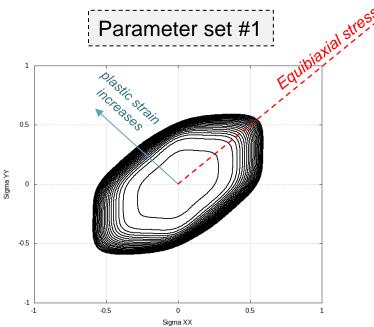
Extended formulation based on Fleischer et al. (2007) – input example

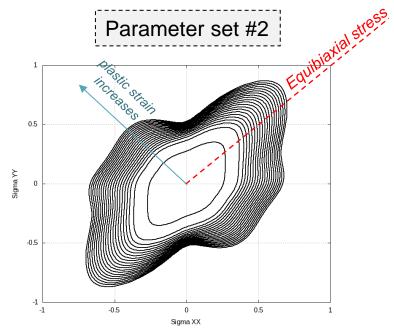


*MAT_036 + HR=7

Yield surface

The extended formulation of *MAT_036 is very flexible and extremely useful in order to match experimental data. Nevertheless, different sets of parameters may lead to non-convex and non-monotonic yield surfaces.

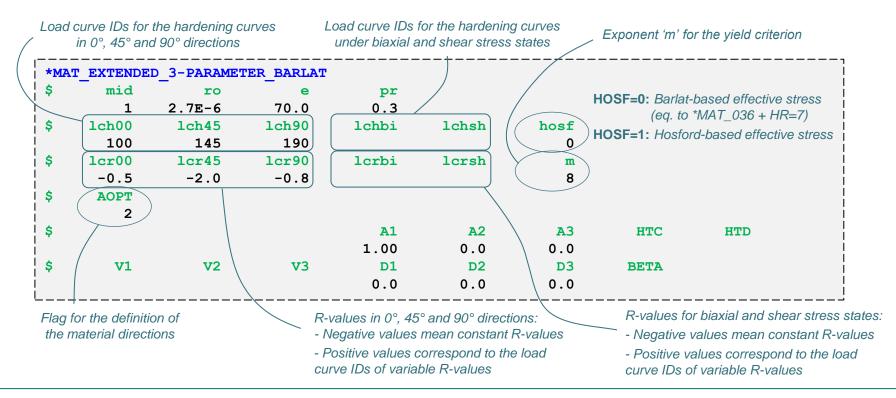






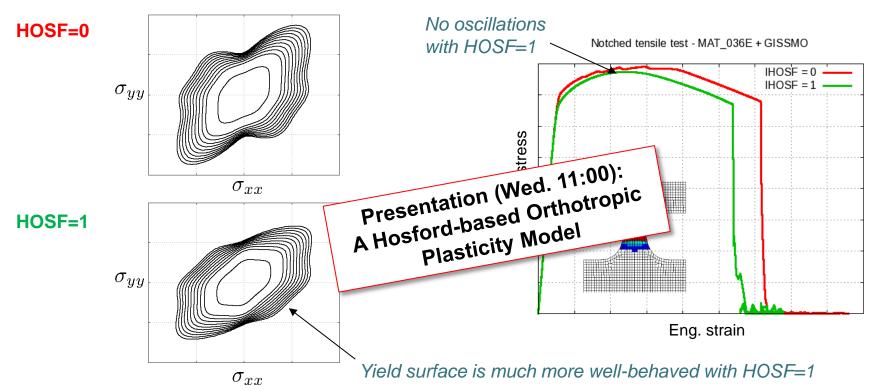
*MAT 036E

Extended formulation with different input format (from R9 on)



*MAT 036E

Comparison between Barlat- (HOSF=0) and Hosford-based (HOSF=1) formulations





Material calibration



Material calibration

Overview of material models an the required tests

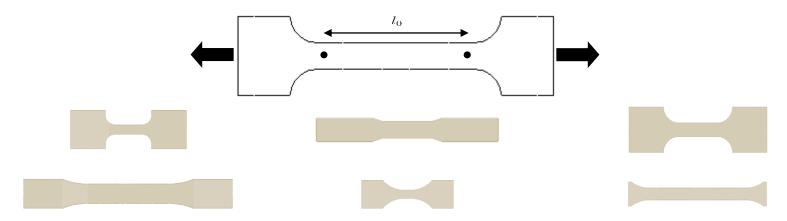
Test Material behavior	Quasi-static tensile	Quasi-static compression	Quasi-static Shear/biax	Dynamic tensile/bending	Cyclic tensile/bending/ compression
Elasticity	✓	(✓)	(✓)		
Visco-elasticity	✓	(✓)	(✓)	✓	✓
Plasticity	✓	(✓)	(✓)		
Visco-plasticity	✓	(✓)	(✓)	✓	
Damage	✓		✓	(✓)	_

Workshop (Wed. 9:00): Failure prediction with GISSMO



Tensile test

- it is a very common and very important test
- with the tensile test it is possible to identify many important mechanical properties such as elastic modulus, yield stress, ultimate tensile strength and elongation
- different specimens available (flat and round specimens, different strain gauges)

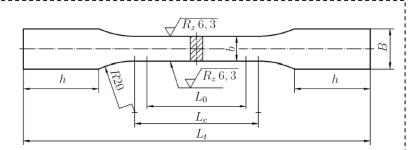


different standards, e.g., for metallic materials DIN EN 10002



From test data to material input

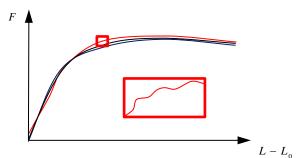
- tensile test necessary information and raw data processing
 - specimen geometry and boundary conditions



for each test:

- geometry dimensions
- gauge length
- fixed support
- velocity/strain rate

raw data



raw data information

$$F \Rightarrow \sigma_{\it eng} ~~ L - L_{\it 0} \Rightarrow \varepsilon_{\it eng}$$

raw data processing

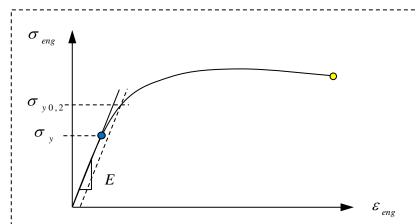
- smoothing, filtering and averaging
- start at (0, 0)

averaging of all test curves



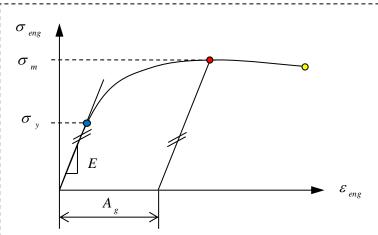
From test data to material input

Young's Modulus and yield stress



Young's modulus → initial slope yield stress → beginning of plastic deformation

Ultimate Strength and necking point



Necking initiation is related to the maximum of the engineering stress-strain curve:

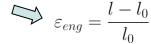
$$\frac{\partial \sigma_{eng}}{\partial \varepsilon_{eng}} = 0$$

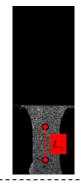


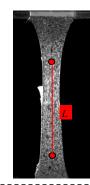
From test data to material input

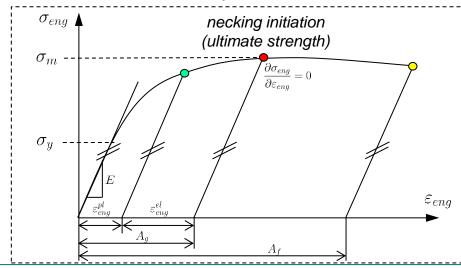
- engineering (or nominal) stress-strain curve
 - engineering stress: axial force per initial area
 - engineering strain: elongation per initial length
 - the engineering stress-strain curve is a usual result from experiments

$$\sigma_{eng} = \frac{F}{A_0}$$







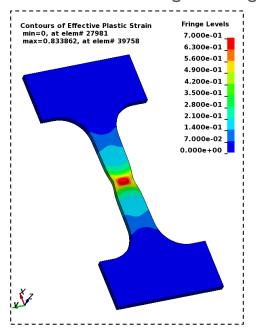


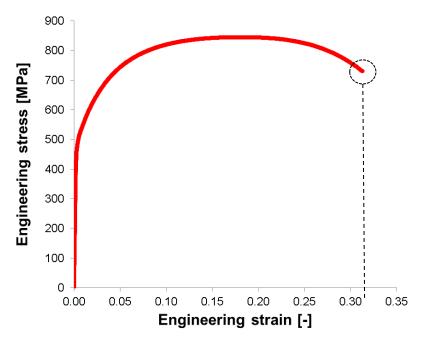
Behavior after necking initiation is unstable:

- further deformation without increasing load
- stress not uniformly distributed over necking region
- triaxial state of stress is unknown
- localization of strain manifested by local necking



Difference between engineering and true strain

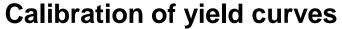




Max. true plastic strain: 70%

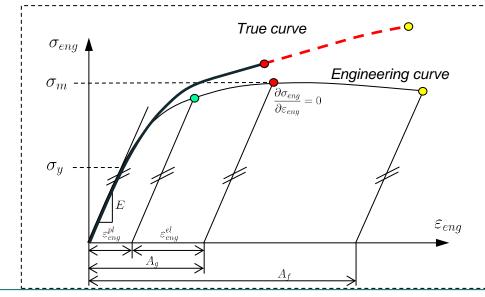
Max. engineering strain: 32%





From test data to material input

- True stress-strain curve
 - True stress: axial force per current unit area
 - True (logarithmic) strain



Standard tensile test: current area A is unknown!



$$\sigma_{true} = \frac{F}{A}$$

$$\Rightarrow$$

$$\sigma_{true} = \frac{F}{A}$$

$$\varepsilon_{true} = \ln \frac{l}{l_0} = \ln(1 + \varepsilon_{eng})$$

True stress **before necking initiation**: Calculation with the assumption of constant volume

$$\sigma_{true} = \frac{F}{A} = \frac{F}{A_0} \frac{A_0}{A}$$
$$= \frac{F}{A_0} \frac{l}{l_0} = \sigma_{eng} (1 + \varepsilon_{eng})$$

True stress after necking initiation: Extrapolation is necessary!



Calibration of yield curves

Extrapolation strategies after the necking point

In order to identify the **true stress strain curve** after the necking point, several methods are normally used, among then:

- Using information from a shear test
- Using information from a biaxial test
- Through Digital Image Correlation (DIC)
- Reverse engineering

Irrespective of the method adopted for the extrapolation, a suitable model can be used to generate the hardening curve. Some of the most commonly used extrapolation equations are:

• Ludwig:
$$\sigma_y^{true} = k(\varepsilon_{true}^{pl})^n$$

$$\sigma_y^{true} = a - be^{-c\varepsilon_{true}^{pl}}$$

Swift:
$$\sigma_y^{true} = k(\varepsilon_0 + \varepsilon_{true}^{pl})^n$$

• Hocket-Sherby:
$$\sigma_u^{true} = a - be^{-c(\varepsilon_{true}^{pl})^n}$$

• Gosh:
$$\sigma_y^{true} = k(\varepsilon_0 + \varepsilon_{true}^{pl})^n - p$$



Calibration of yield curves

Parametrization of the yield curve

Direct *calculation* of the yield curve until A_g for isochoric materials

$$\sigma_y = \sigma_{eng}(1 + \varepsilon_{eng})$$

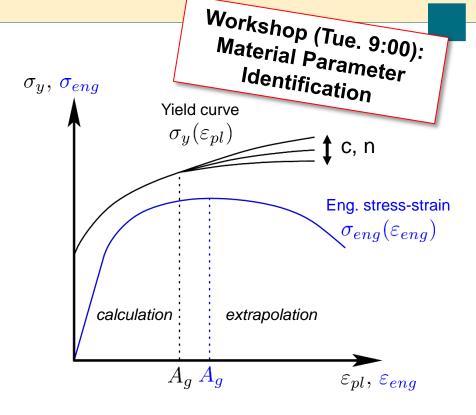
$$\varepsilon_{pl} = \ln(1 + \varepsilon_{eng}) - \frac{\sigma_{eng}}{E}$$

Extrapolation from A_g with Hockett-Sherby

$$\sigma_y(\varepsilon_{pl}) = A - B e^{(-c \varepsilon_{pl}^n)}$$

 C^1 -continuity at A_q :

Reduction of the function by two variables



> Remaining variables c and n are the remaining free parameters

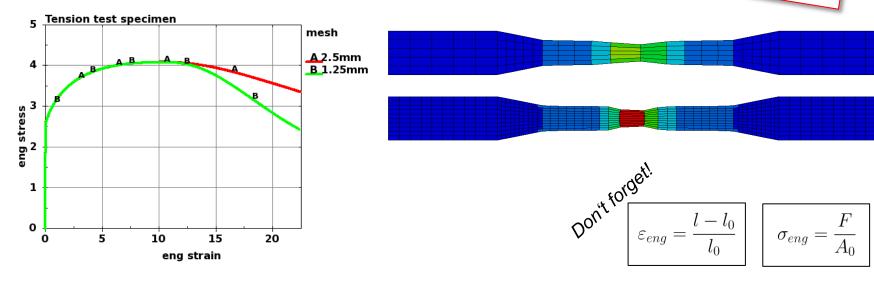


Calibration of yield curves

Element size dependence

After the necking point the result depends on the element size

Workshop (Wed. 9:00): Failure prediction with GISSMO



After the necking point:

For most material models the characterization only applies to a certain element size!



The lab @ DYNAmore

On site material testing

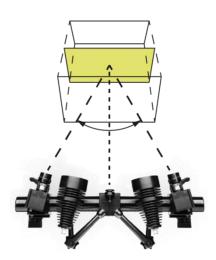
Testing equipment

Universal testing machine for quasi-static tests (<100kN)



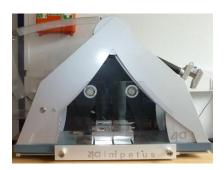
- Tension
- Compression
- Shear
- ^l Biaxial
- Bending
 - Cyclic

Optical measurement (DIC)



- Measurement of the strain field during the test
- Evaluation of the engineering strain in post-processing

4a Pendulum dynamic tests (<4.3 m/s)



- Bending (plastics, composites)
- Compression (foam)

Workshop (Tue. 11:00): VALIMAT



On site material testing

Testing equipment

Quasi-static tension



Quasi-static bending





Quasi-static compression



Quasi-static biax





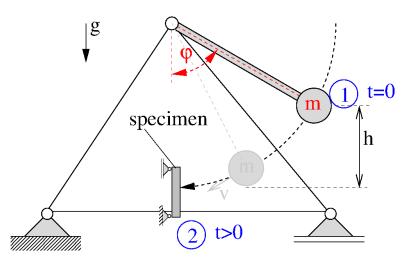
Testing and modelling of foams using

*MAT_FU_CHANG_FOAM (*MAT_083)



Dynamic Tests with pendulum – experimental setup

- 4a impetus testing machine:
 - single pendulum
 - dynamic velocities 0.5-4.3 m/s
 - measurement of angle and acceleration at impactor with mass m





t=0: position of m is fixed at 1 with an initial $W_{pot} = mgh$

t>0: m moves from 1 to 2
$$W_{pot} \ {\rm changes} \ {\rm to} \ W_{kin} = {\textstyle \frac{1}{2}} m v^2$$

at 2:
$$\min W_{pot}$$
 and $\max W_{kin}$ impactor hits specimen with $\vec{p} = m\vec{v}$

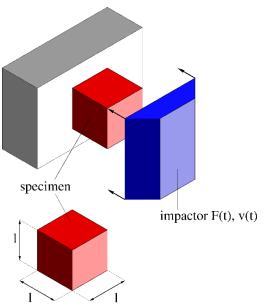


Compression test – experimental setup

- compression test:
 - specimen is fixed by adhevive tape
- variation of nominal strainrate $\dot{\varepsilon}$ due to
 - different specimen size I
 - different initial velocities v

strain ra	ate in 1/s	l in mm	v in m/s
	0.001	20	0.00002
	0.01	20	0.0002
AM	0.1	15	0.0015
profession of	0.3	15	0.0045
	40	20	0.8
ARCHA T	100	15	1.5
	200	20	4.0



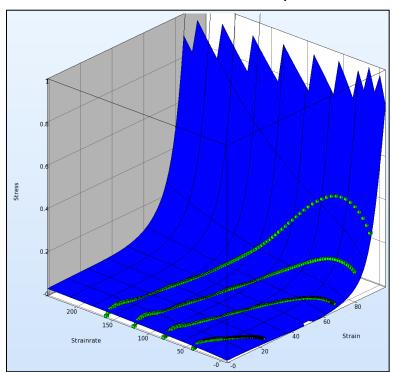


nominal strain rate: $\dot{arepsilon}=rac{v}{l}$

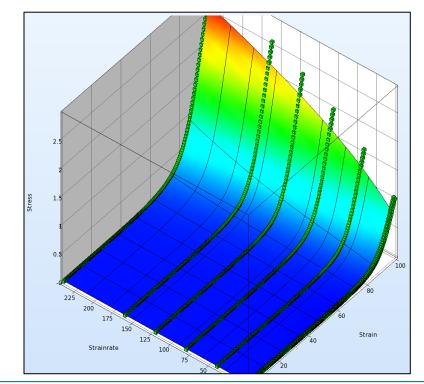


Example: LS-OPT meta model

Stress strain cuves from Experiment

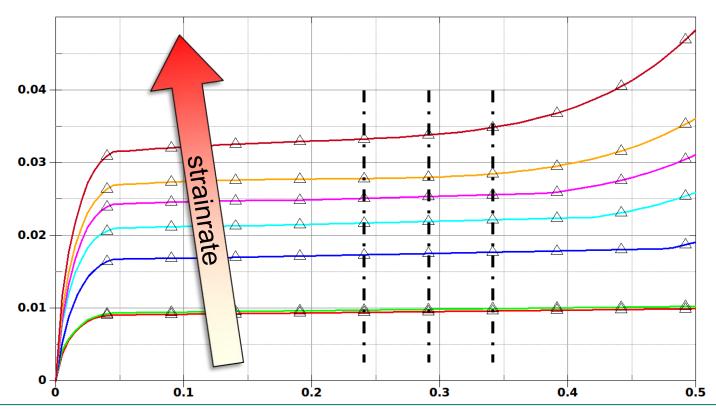


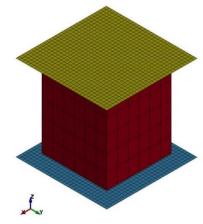
Stress Strain curves with constant strain rates





Example: Fu-Chang-Foam





Testing and modelling of Polymers using

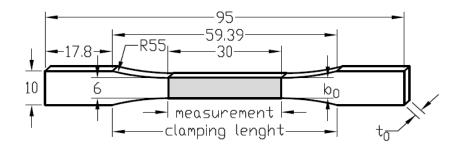
*MAT_SAMP (*MAT_187)

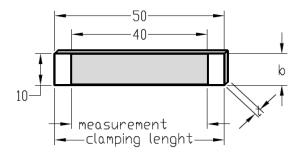


Specimen

- Tensile specimen
 - static and dynamic tests
 - Strain via DIC
 - Engineering strain with I₀=30 mm
 - Target mesh size: 2mm
 - Milled specimen

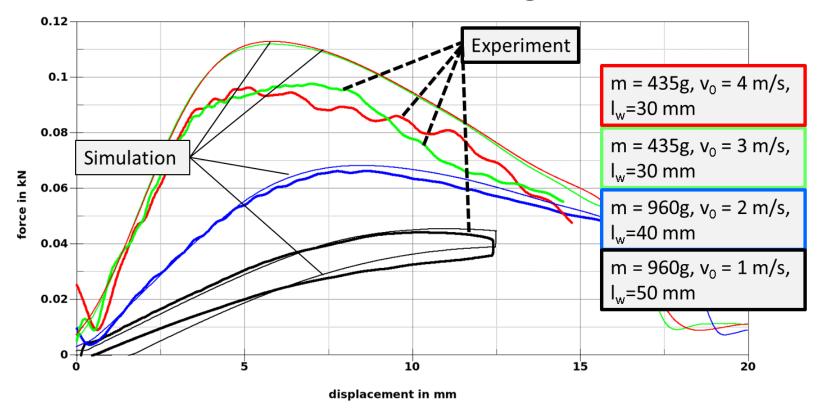
- 3 point Bending:
 - Static and dynamic tests
 - Milled specimen
 - Large of strain rates possible





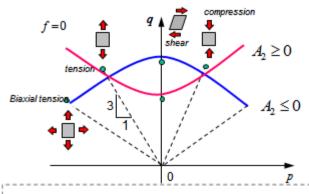


Results of MAT_024 + GISSMO card: bending tests



Material modelling of polymers in LS-DYNA

Isotropic plasticity with SAMP-1 (*MAT_187)

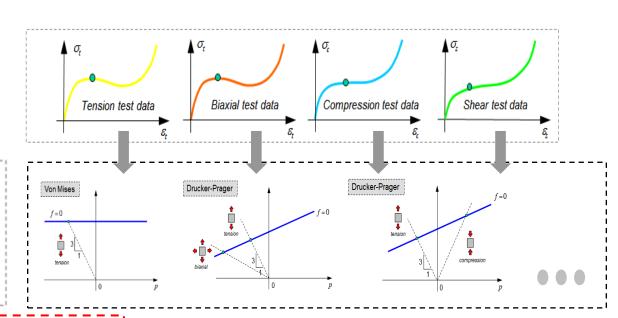


Yield surface:

$$f(p, \sigma_{vm}, \overline{\varepsilon}^{pi}) = \sigma_{vm}^2 - A_0 - A_1 p - A_2 p^2 \le 0$$

Condition for convexity:

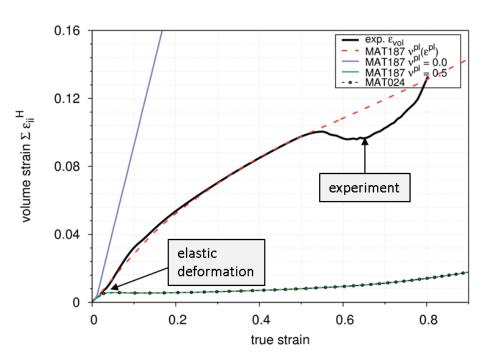
$$A_2 \le 0 \Leftrightarrow \sigma_z \ge \frac{\sqrt{\sigma_t \sigma_\epsilon}}{\sqrt{3}}$$

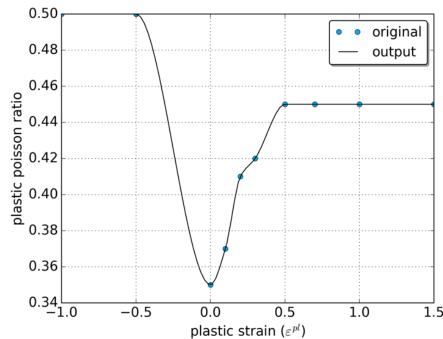


Dependency of plastic poisson ratio



SAMP#1: plastic poisson's ratio

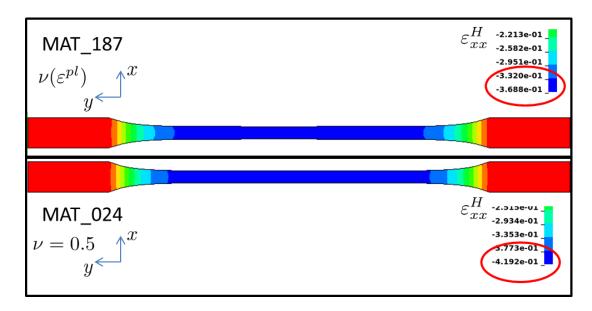






SAMP#1: plastic poisson's ratio

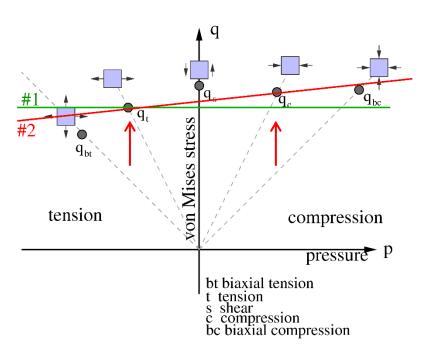
- Taking ratio into account:
 - influence on strain transversal to loading direction
 - influence plastic strain at notch tip
 - important for complex FE-models

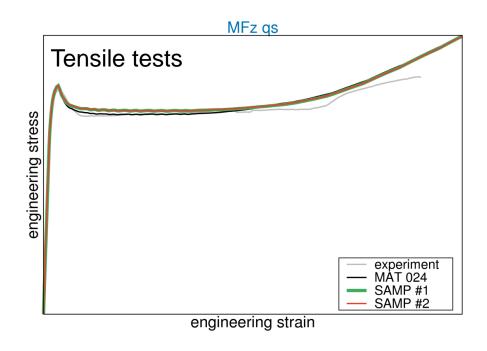


Important for simulation of thermoplastics with increasing macroscopic volume (e.g. Crazing at ABS, HIPS, PC/ABS



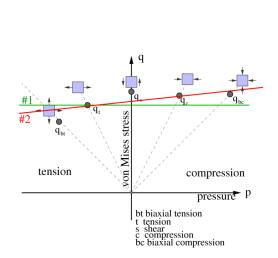
SAMP #2: taking compression into account

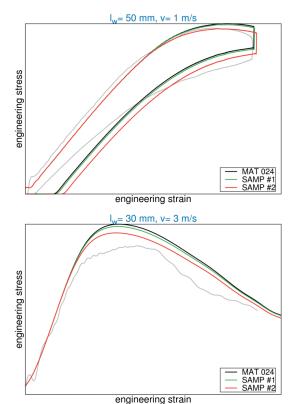


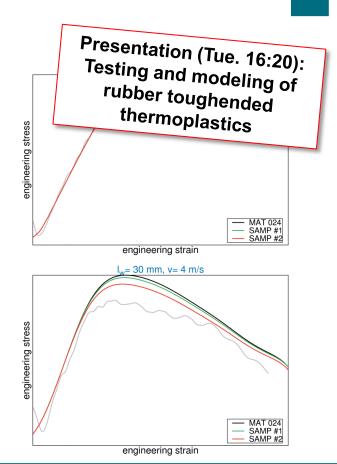




Bending results









Experimental material characterization at DYNAmore Stuttgart



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Services

- Material deformation characterization and LS-DYNA material model calibration for:
 Polymers, Foams, Metals
- Experiments
 - Tensile, bending, compression, punch test
 - Component testing
 - Local strain analysis with DIC
- Damage and fracture characterization and calibration for GISSMO and eGISSMO models



