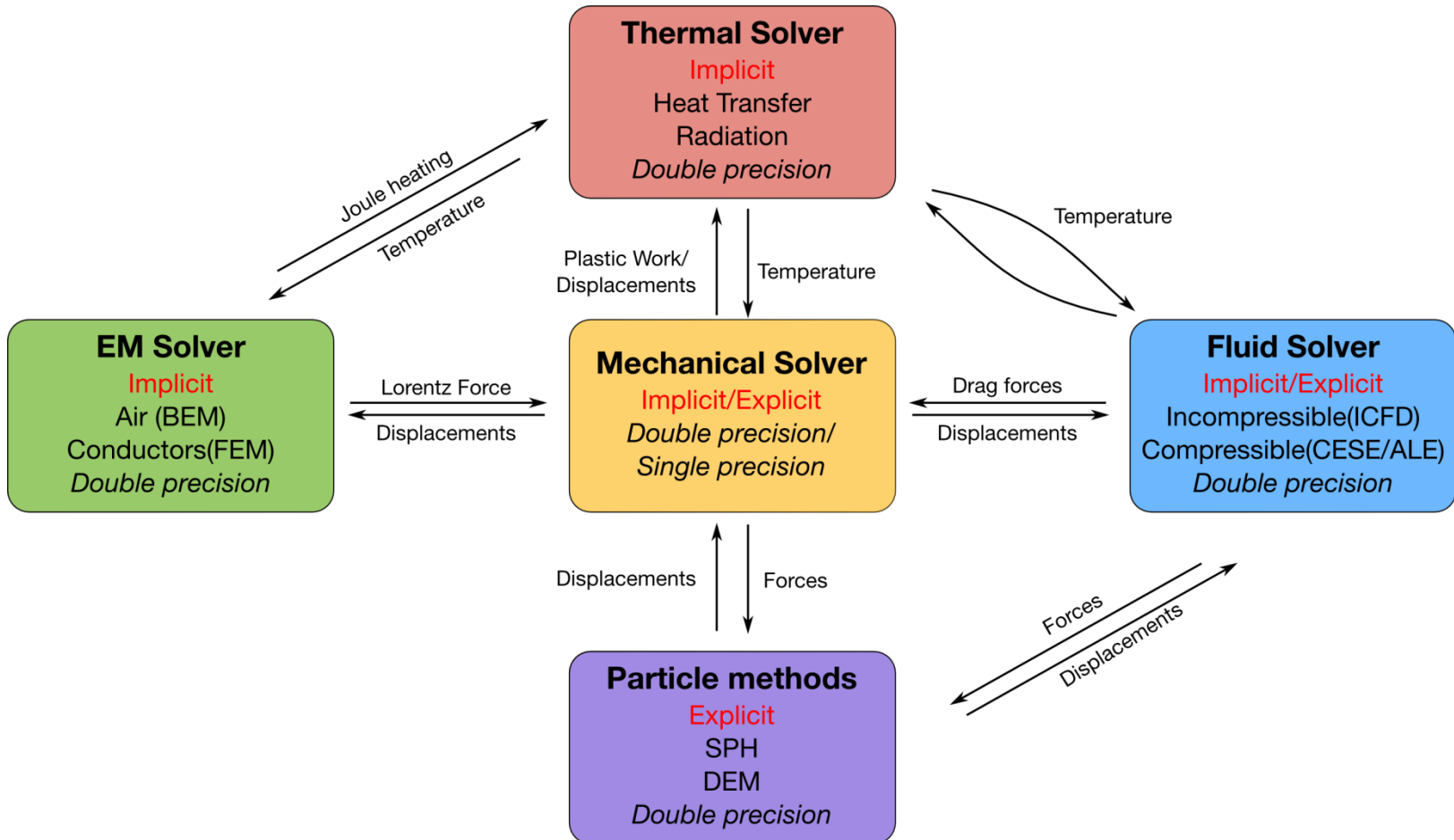


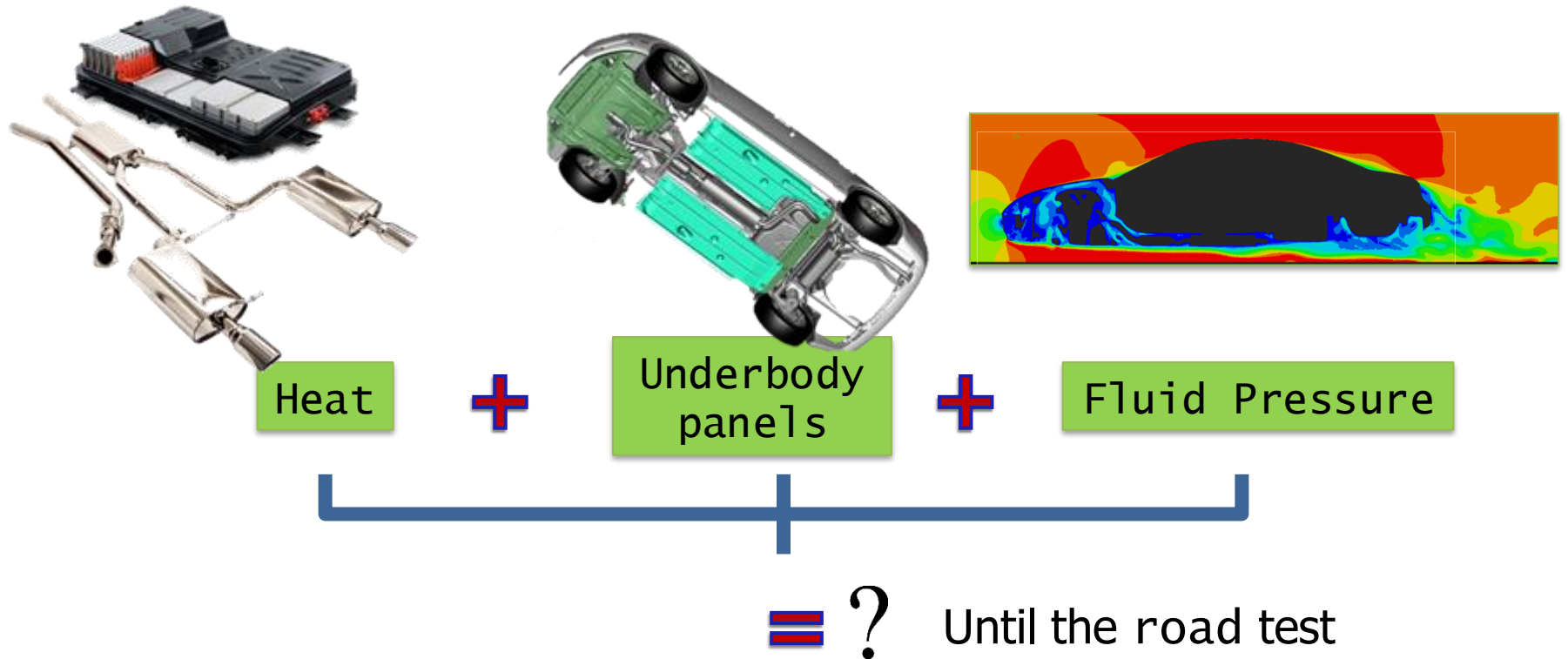
Review and Advances of Coupling Methods for the ICFD solver in LS-Dyna

Coupled problems require the simultaneous solution of more than one physics module of LS-DYNA to obtain an accurate result.



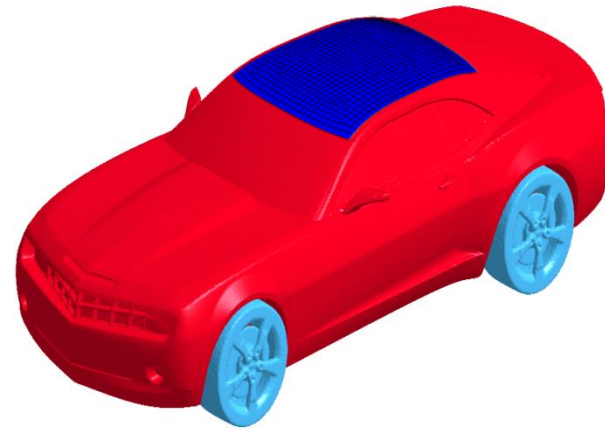
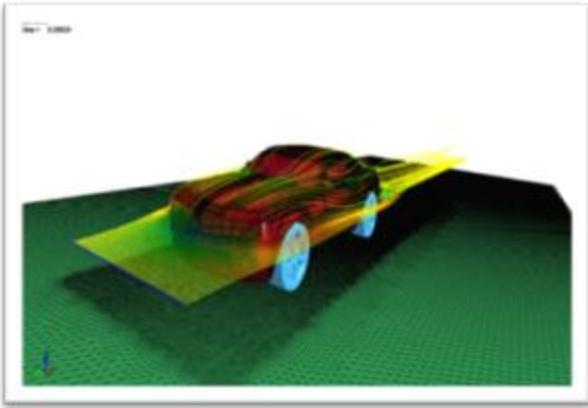
Accurate CFD analysis will require structural coupling

The mechanical behavior of structural parts subject to heat and fluid pressure loads have been neglected.

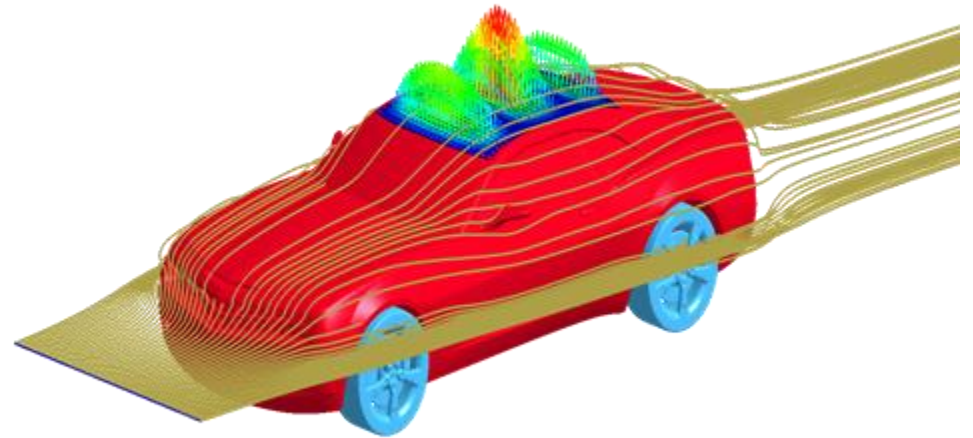


Fluid Structure Interaction

Roof vibration analysis



- CFD analysis of full vehicle.
- Couple parts of the structure to analysis the response in a realistic environment.



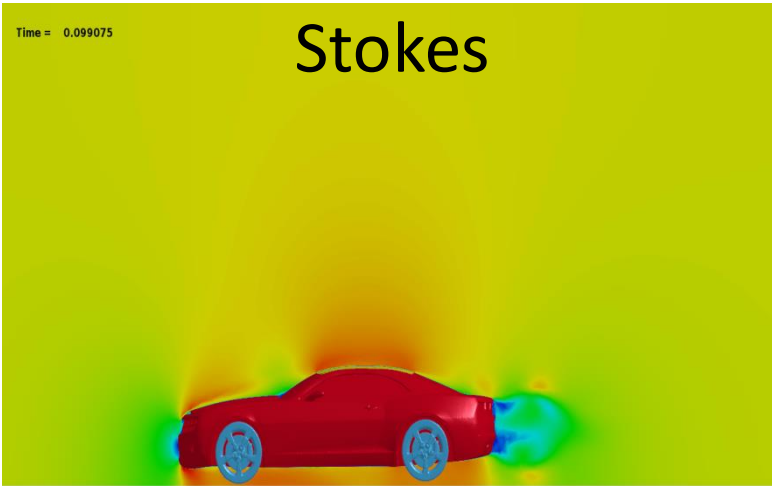
Fluid Structure Interaction

Three different options to solve the same problem:

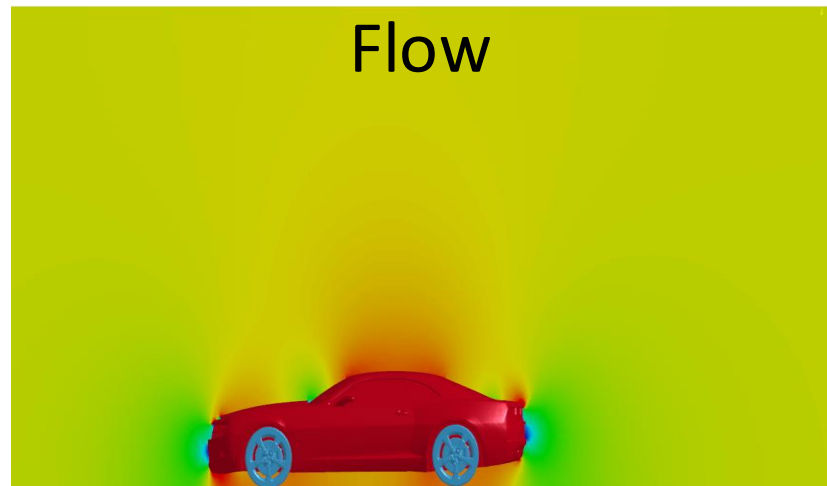
- Solve Full Navier –Stokes with FSI non linear coupling (using weak or strong coupling).
- Solve Potential flow with a non-linear step at the end.
- Solve the structural analysis alone using the output from Navier-Stokes (transient or steady state solver) and the `*LOAD_SEGMENT` automatically generated input deck. Use `*ICFD_DATABASE_DRAG` to write the files.

Fluid Structure Interaction. Results.

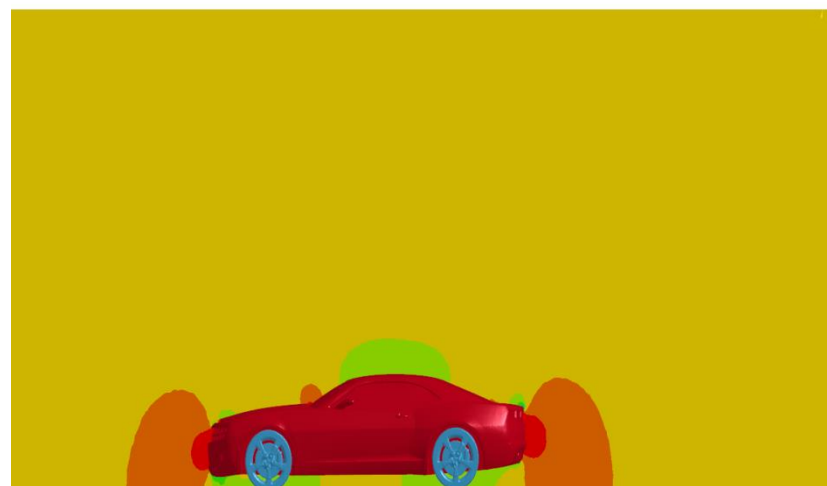
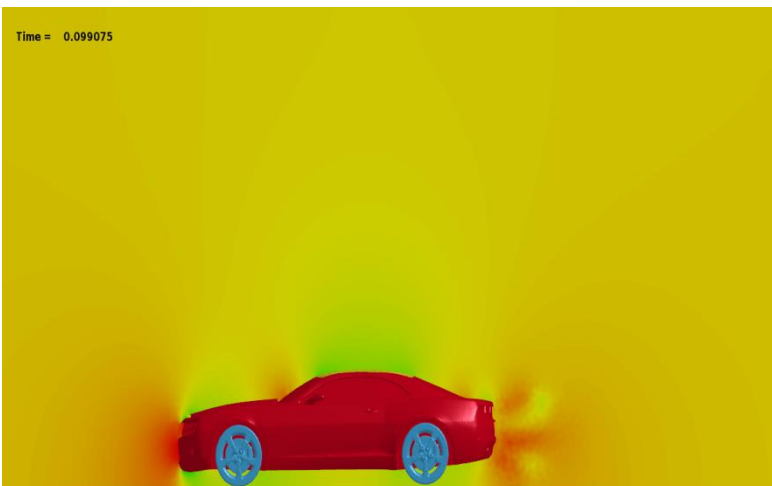
Navier
Stokes



Potential
Flow



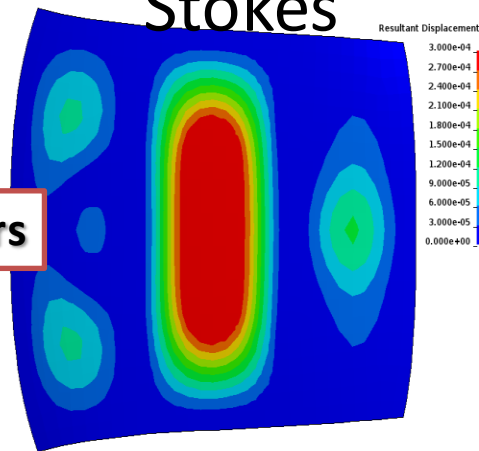
Velocity



Pressure

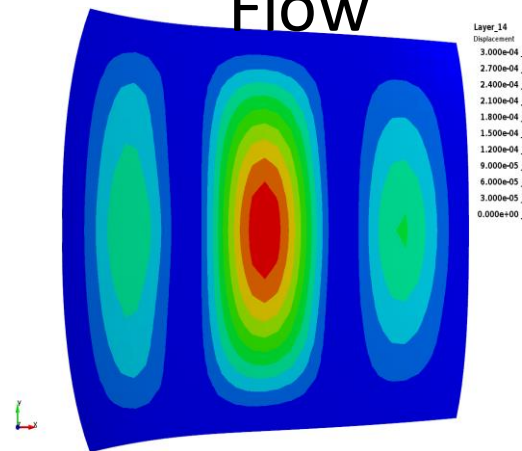
Fluid Structure Interaction. Results.

Navier
Stokes



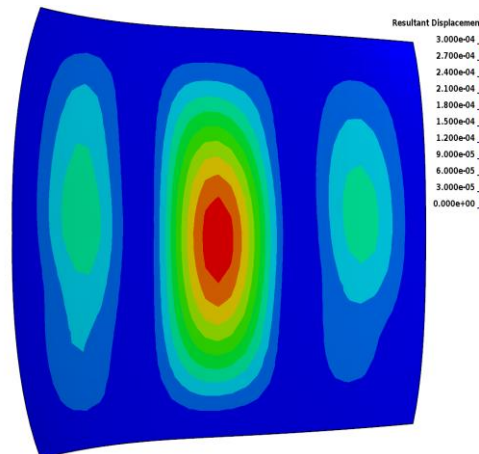
24 hours

Potential
Flow



20 minutes
46 times faster

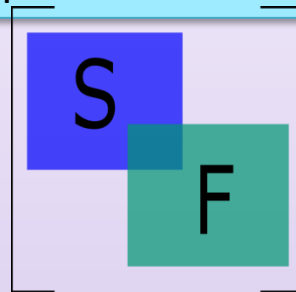
2 seconds



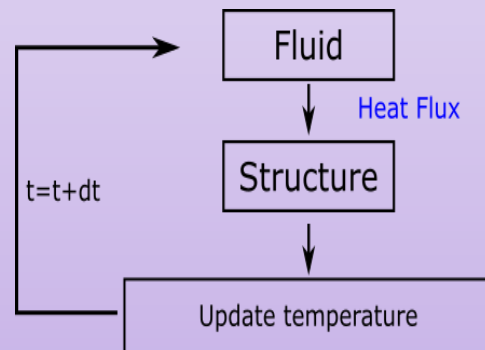
Using `*LOAD_SEGMENT`
from Navier-Stockes solution

Thermal Coupling

Monolithic coupling: big jumps of physical properties.



Weak coupling: small jumps or very fine mesh at the interface.



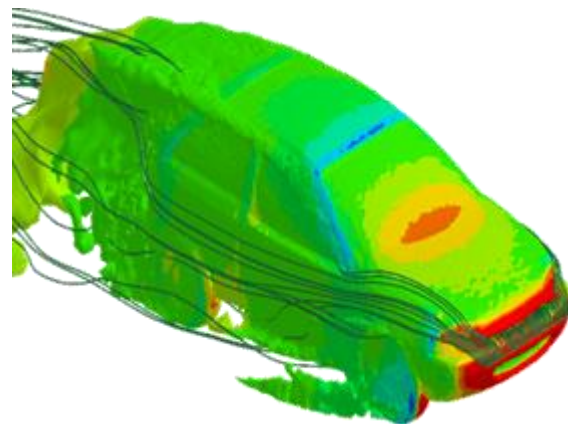
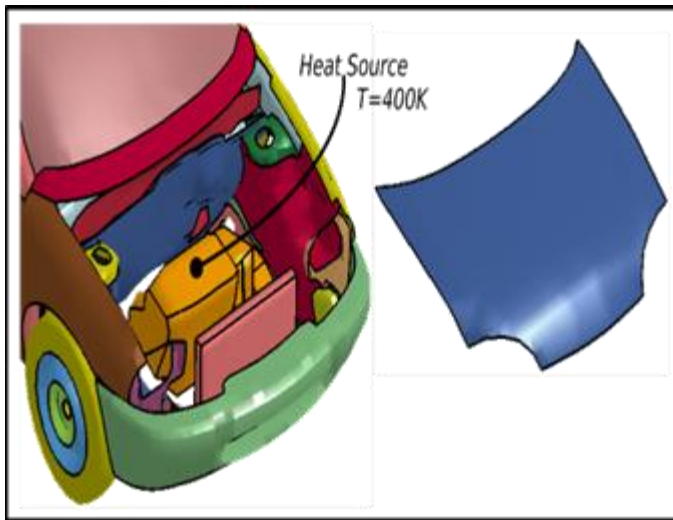
Thermal coupling

Options to solve the same problem:

- Solve Full Navier –Stokes with thermal non linear coupling (using monolithic or weak coupling). Shut off N.S after a certain steady state has been reached and continue with a pure thermal coupling analysis.
- Solve Navier Stokes using the steady state or potential flow solver and continue with conjugate heat transfer analysis once steady state has been reached.
- Solve the thermal analysis alone using the output from Navier-Stokes (transient or steady state solver) and the *BOUNDARY_CONVECTION_SET automatically generated input deck. Use ***ICFD_DATABASE_HTC** to write the files.

Conjugate Heat: Radiation

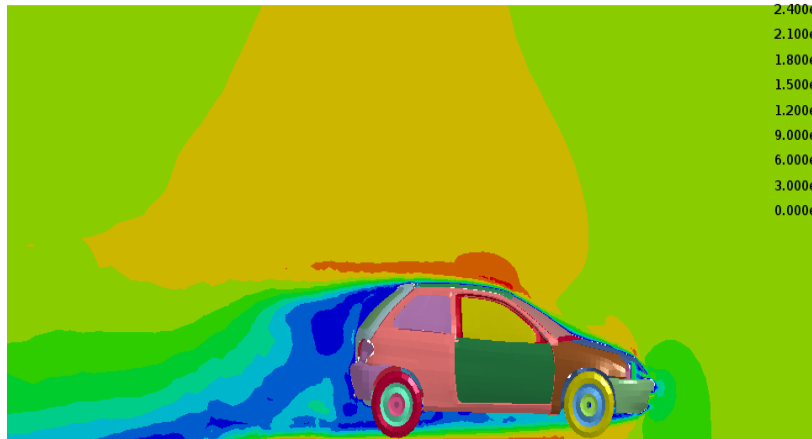
- Run steady state Navier-Stokes or Potential flow. Use ***ICFD_CONTROL_GENERAL** to set it up.
- Once steady state reached or Potential flow finishes the conjugate heat solver will use the steady velocity for the thermal analysis.



Conjugate Heat: Radiation. Results.

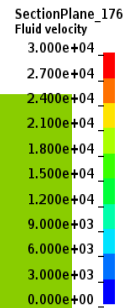
Navier Stokes Velocity

Time = 1.51



Potential Flow Velocity

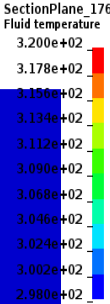
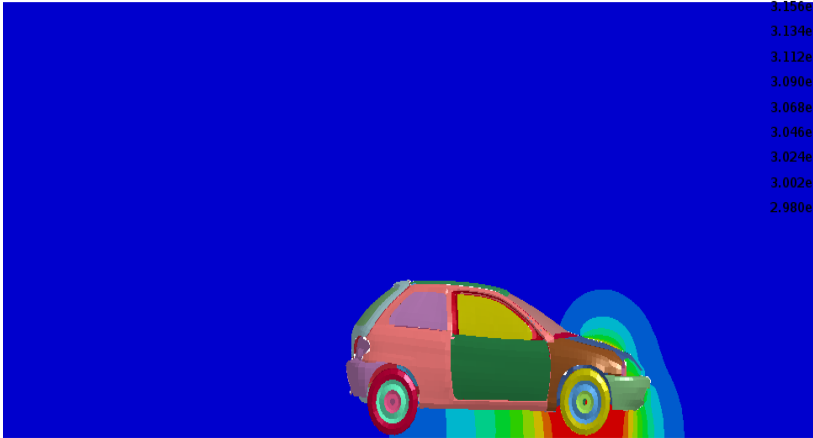
Time = 1.5



Conjugate Heat: Radiation. Results.

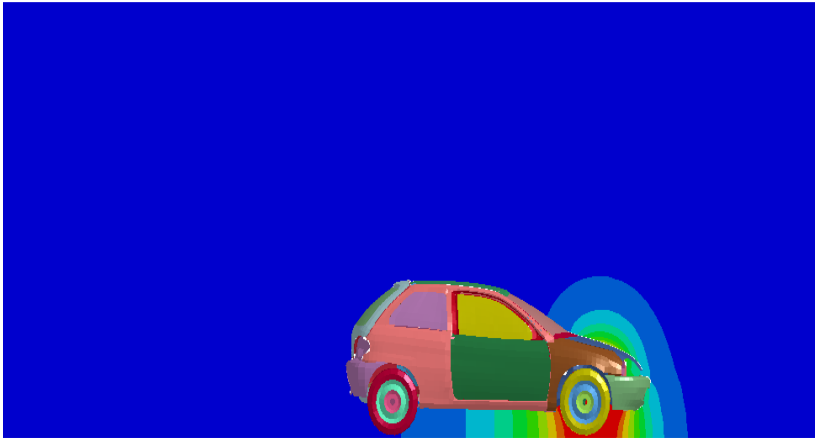
Navier Stokes Temperature

Time = 1.51



Potential Flow Temperature

Time = 1.5



Time: 48 hours

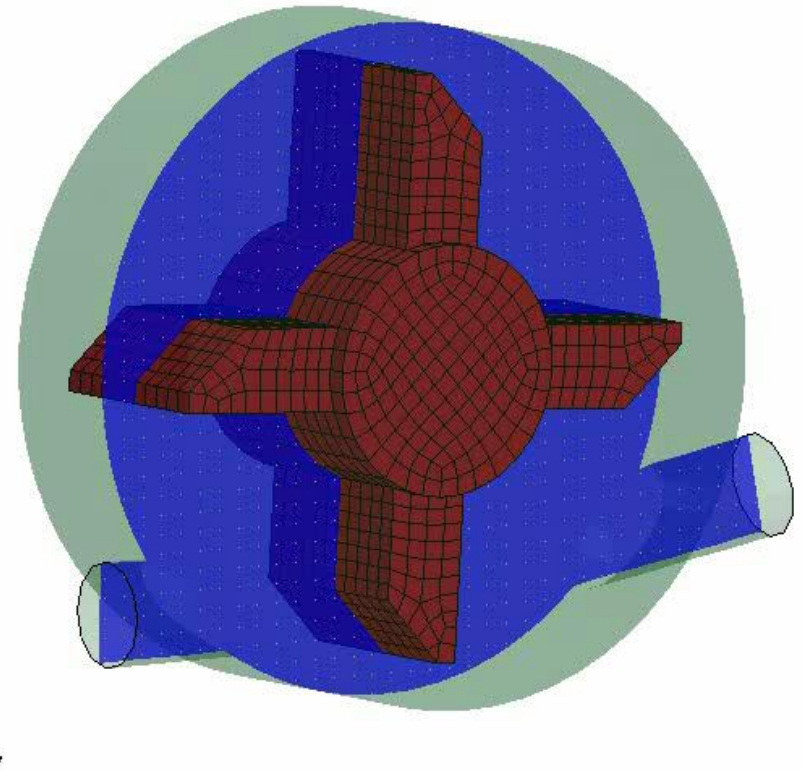
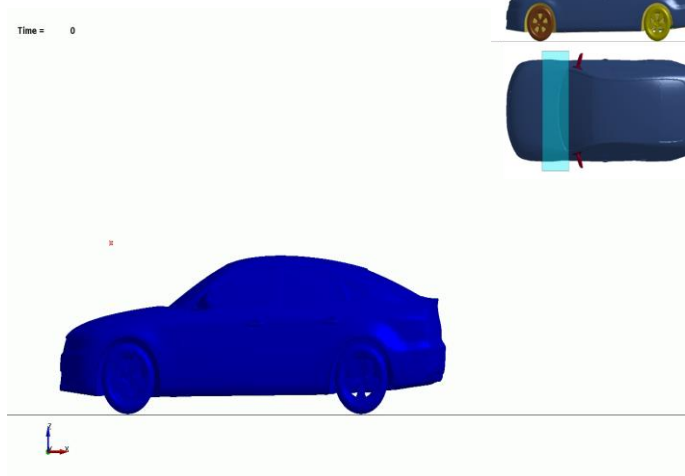
**Time: 1 hour 52 min
26 times faster**

DEM Coupling

Time = 0, #nodes=11231, #elem2d=12722, #elem3d=51046

- Two-way coupling
- Particles affect fluid volume

Water management: Rain Simulation



Recent developments introduced in R10 :

- Added Steady state solver. See ICFD_CONTROL_GENERAL and ICFD_CONTROL_STEADY.
- Added wave damping capabilities. See ICFD_DEFINE_WAVE_DAMPING
- Added Windkessel boundary conditions for blood flow. See ICFD_BOUNDARY_WINDKESSEL
- Option to output loads coming from the fluid and applied on the structure by using ICFD_DATABASE_DRAG keyword option. Similar feature for thermal and HTC and using ICFD_DATABASE_HTC
- Two way coupling with DEM particles
- Option to shut off Navier Stokes solve after a certain time for conjugate heat transfer analysis. See ICFD_CONTROL_TIME.

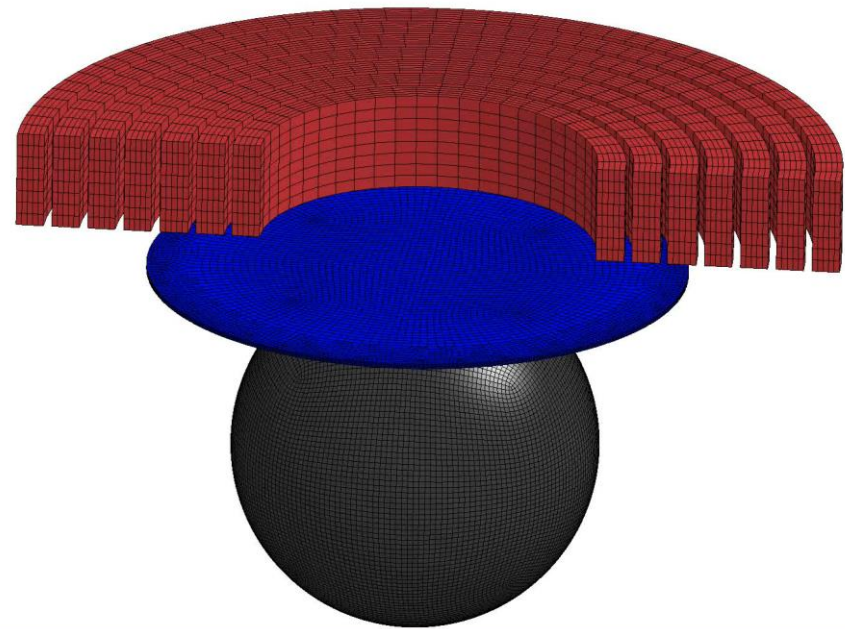
Currently working on :

- Periodic boundary conditions
- Sliding mesh capabilities
- Immersed FSI capabilities
- Monolithic FSI
- 1D parachute model.
- Boundary layer mesh improvements in complex geometry cases.

The EM solver. An overview of its uses and applications

Current main usage:

- The EM solver solves Eddy currents
Using a coupled FEM-BEM method
- This implies that no air mesh
is needed which allows complex shapes
And strong deformations to occur
- The EM solver is therefore the perfect
candidate to solve coupled mechanical
thermal problems where strong
deformations occur such as in
Electromagnetic forming bending welding
and so forth



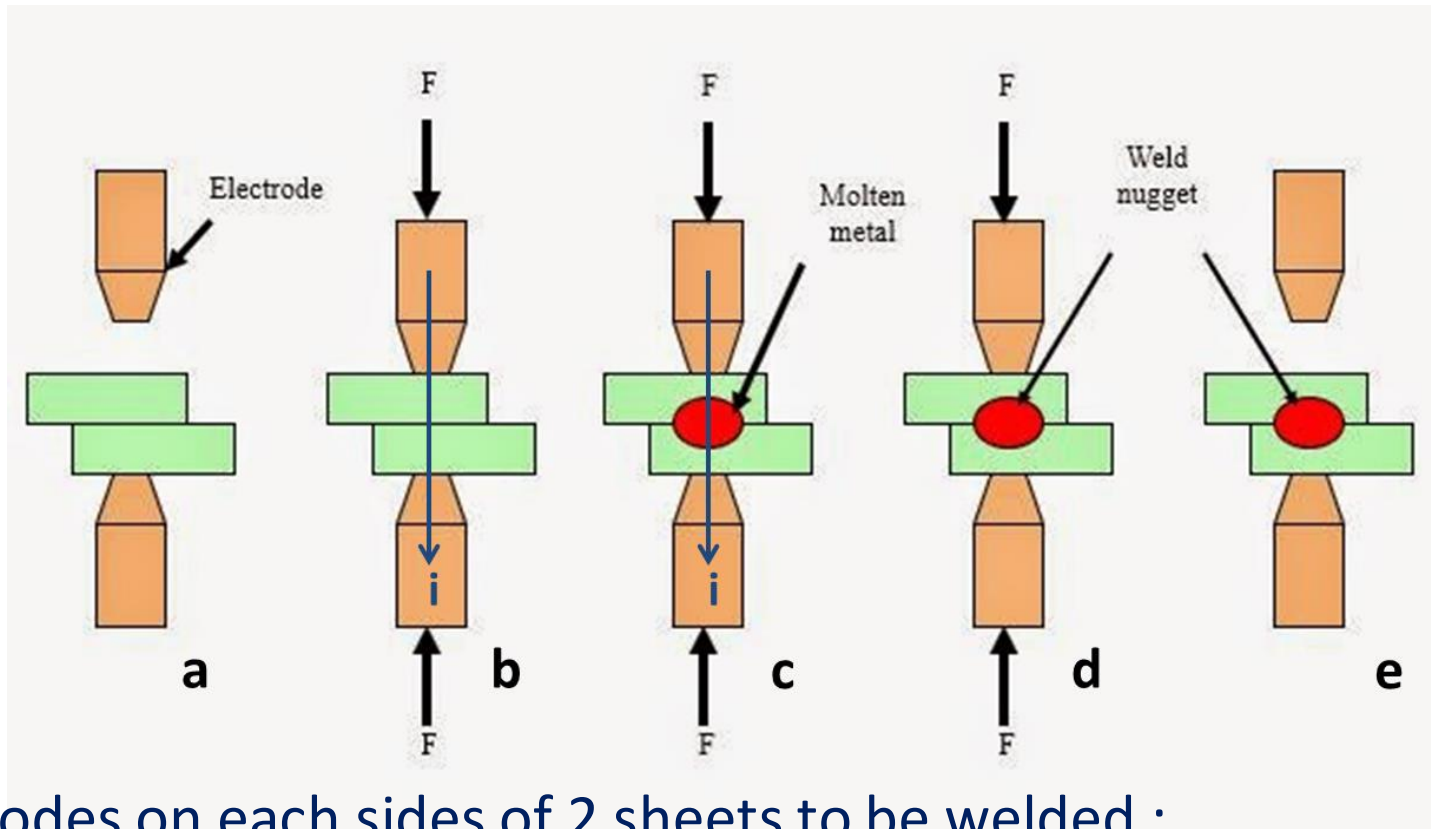
Current main usage:

- More features have recently been introduced for such applications :
 - Axisymmetric solver (R10)
 - Conductivity function of material properties defined by the user with a `DEFINE_FUNCTION`
 - Option to define a circuit using a circuit equation and a `DEFINE_FUNCTION` to allow more complex types of circuits.
- Investigation is under way to add magnetic material capabilities through the introduction of an alternative monolithic solver.

Three new applications :

- Resistive Spot Welding (RSW) capabilities
 - Extension of the resistive heating solver.
 - Introduction of EM_ISOPOTENTIAL to define a potential difference between electrodes and EM_CONTACT_RESISTANCE to define a contact resistance
 - Current capabilities are 3D, currently working on 2D solver.
- Battery short cut modelling
 - Extension of the resistive heating solver.
 - Introduction of circuit models to model ion transfers in batteries (See EM_RANDLES)
 - Extension of EM capabilities to Thick shells
- Cardiac solver for heart modelling
 - Extension of the resistive heating solver
 - Ten Tusscher & Panfilov cell models

Introduction - RSW



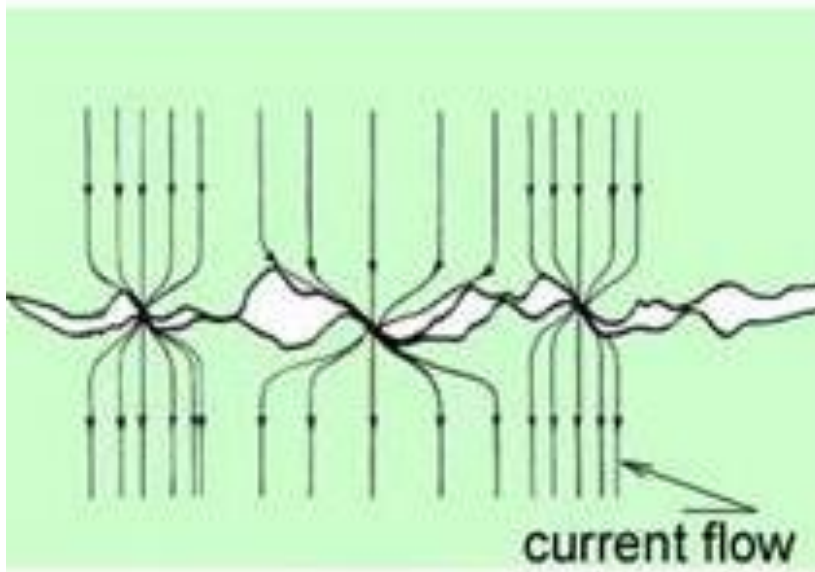
Electrodes on each sides of 2 sheets to be welded :

- Pressure
- Current flow \Rightarrow Joule heating \Rightarrow formation of a molten weld nugget

Coupled mechanical/EM/thermal simulations

RSW and contact resistance

In RSW, **contact resistance** plays a very important role in the heating of the nugget



New model in LS-DYNA for local contact resistance (in 3D) depending on local parameters, using *DEFINE_FUNCTION, e.g. Jonny-Kaars model :

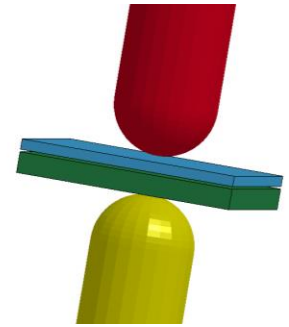
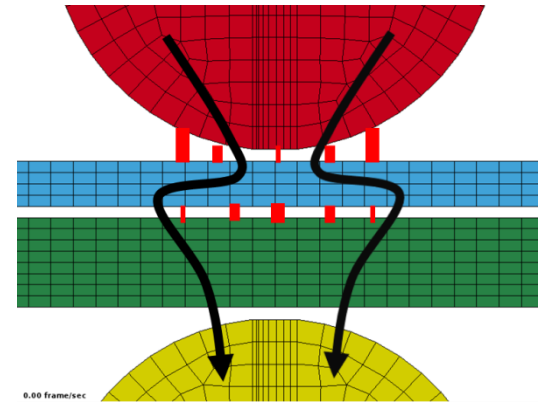
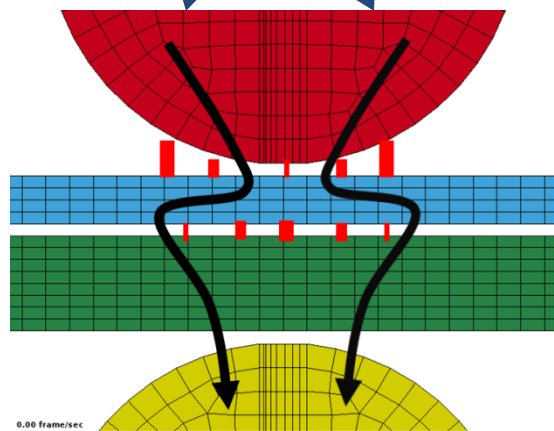
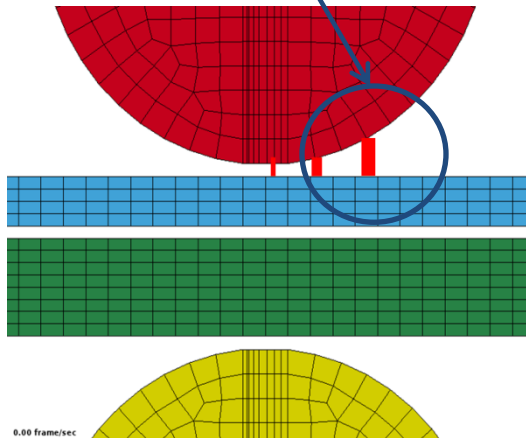
$$r(T, P) = r_0 \left(\frac{P - P_k}{P_0 - P_k} \right)^{\varepsilon_p} \cdot \left(\frac{T - T_{\text{lim}} + (293,15 \text{ K} - T) \cdot 2^{-\frac{1}{\varepsilon_T}}}{293,15 \text{ K} - T_{\text{lim}}} \right)^{\varepsilon_T}$$

EM model for contact resistance (1)

Local contact resistance =
FUNCTION(
pressure,
temperature,
Electrical conductivity,
Contact distance, ...
Using *DEFINE_FUNCTION

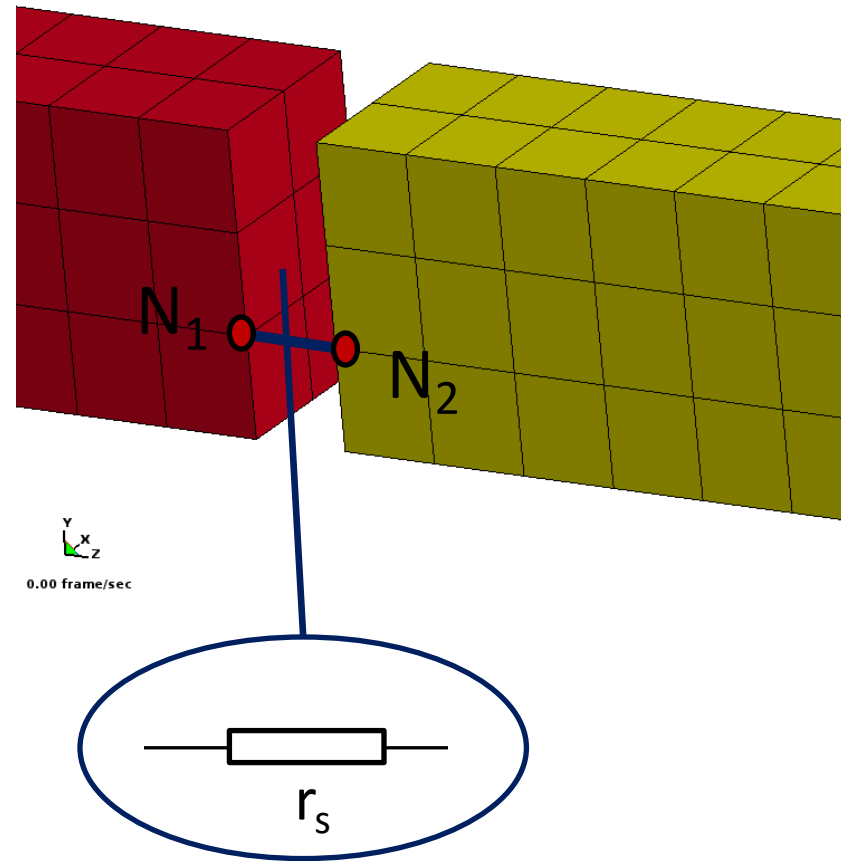
Current flow
depends on
Bulk and
contact resistance

Joule heating
Is locally added
To thermal solver



EM model for contact resistance (2)

Contact resistance added in stiffness matrix



FEM solve:

$$(S_0 + D) * \varphi = 0$$

Where

- S_0 is the Laplacian operator (nodes x nodes)
- D has
 - $1/r_s$ at (N_1, N_1) and (N_2, N_2)
 - $-1/r_s$ at (N_1, N_2) and (N_2, N_1)
 - 0 elsewhere

Row N_1 gives:

$$(S_0 * \varphi)_{N_1} + (D * \varphi)_{N_1} = 0$$

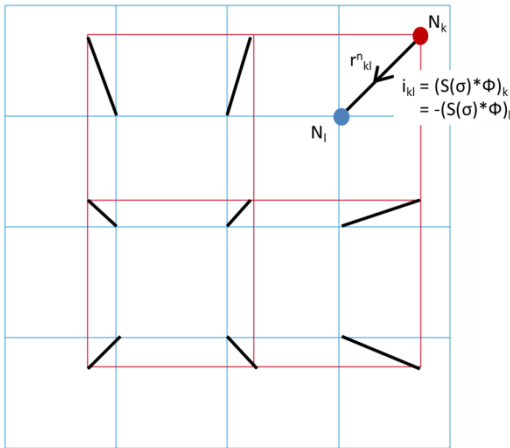
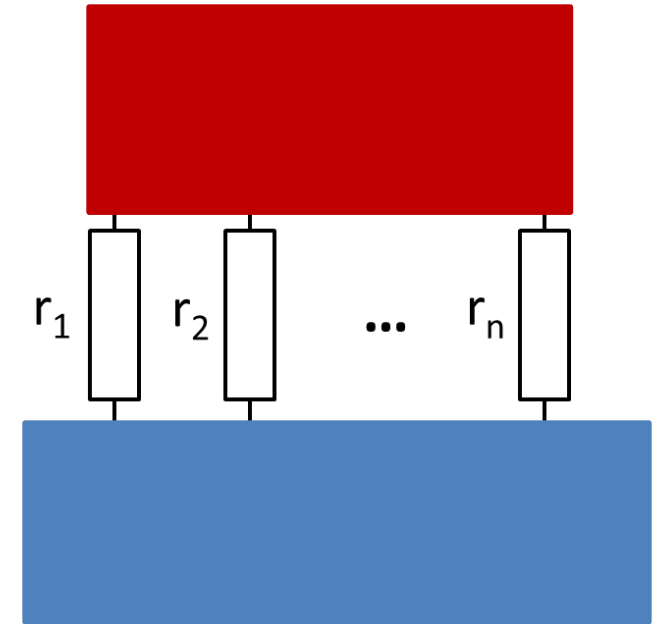
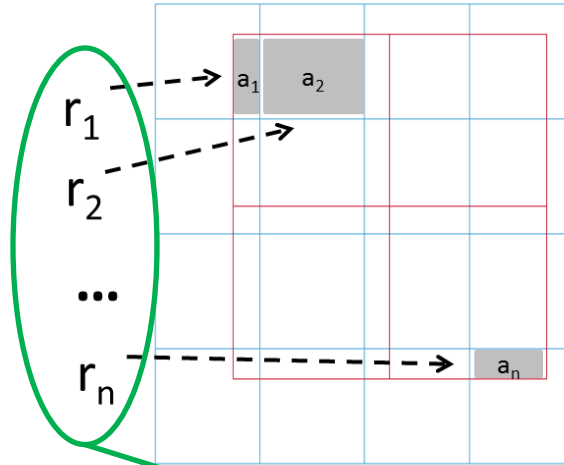
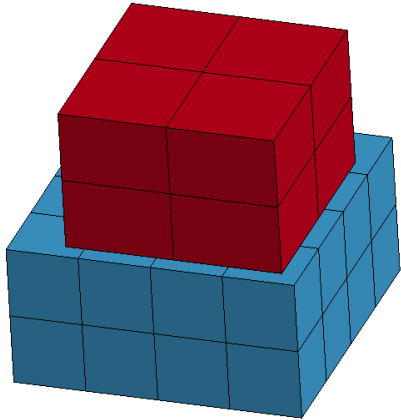
$$i_1 + 1/r_s (\varphi_1 - \varphi_2) = 0$$

$$(\varphi_2 - \varphi_1) = r_s i_1$$

And similar at row N_2

On rows not connected to contact
 $S_0 * \varphi = 0$ ensures the free divergence of the current in the plates (no charge accumulation)

Contact resistance depends on local parameters



Local contact resistance =
 FUNCTION(
 a_k , Total contact area,
 pressure,
 temperature,
 Electrical conductivity,
 Contact distance,
 Using ***DEFINE_FUNCTION**

EM cards to setup contact resistance

*EM_CONTROL_CONTACT

EMCT	CCONLY	COTYPE	EPS1	EPS2	EPS3	D0
1	1					

*EM_CONTACT

CONTID	COTYPE	PSIDM	PSIDS	EPS1	EPS2	EPS3	D0
18	1	1	2	0.3	0.3	0.3	

*EM_CONTACT_RESISTANCE

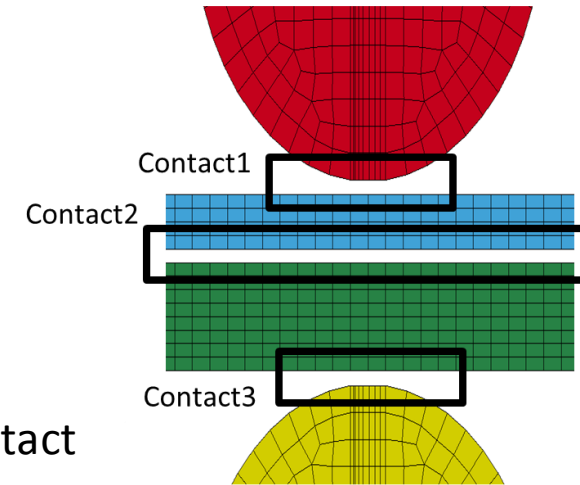
CRID	CONTID	CTYPE	CIRCID	JHRTYPE	D0
12	18	1		1	

LCID	D0
14	

*DEFINE_FUNCTION

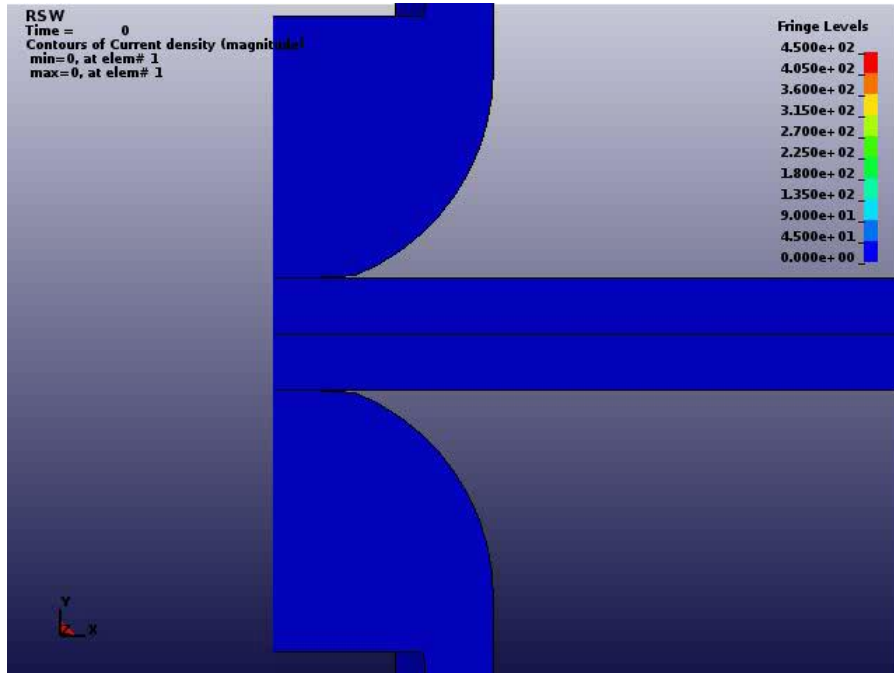
FID
14

Per contact

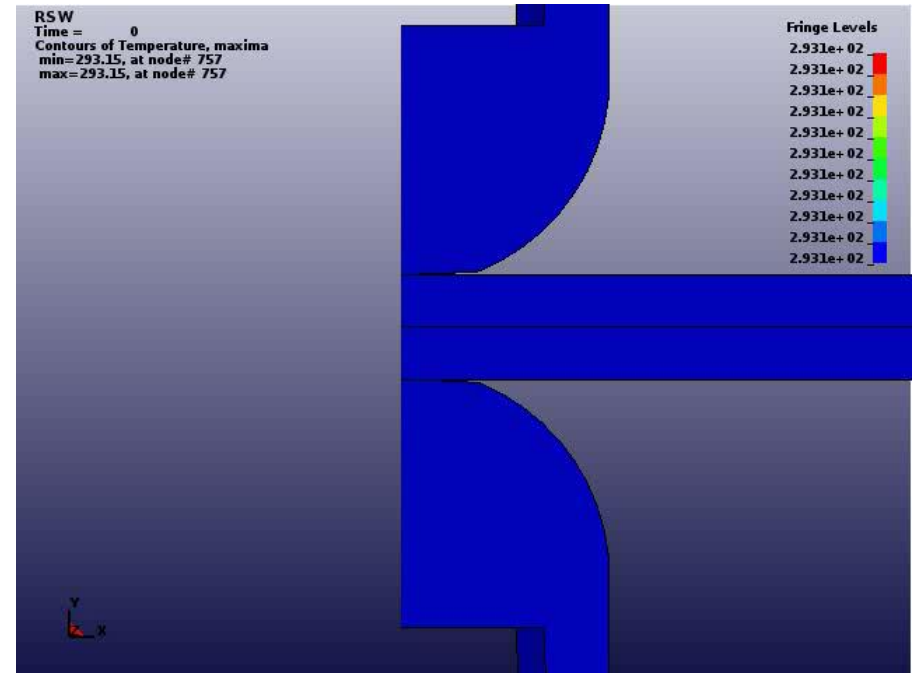


time	Simulation time
area_glo	Global contact area A (see equation (8))
area_loc	Local contact area A (see equation (8))
dist_ct	Distance between the 2 faces in contact
ctpress_mst	Contact pressure on master side
ctpress_slv	Contact pressure on slave side
temp_mst	Contact temperature on master side
temp_slv	Contact temperature on slaveside
cond_mst	Electrical conductivity on master side
cond_slv	Electrical conductivity on slave side
vmstress_mst	Von mises stress on master side
vmstress_slv	Von mises stress on slave side

Typical RSW simulation



Current density



Temperature

Application

- The new LS-DYNA EM-Contact enables many approaches to cover the contact resistance for RSW
- The Jonny-Kaars-Model is an approach based on a resistance function of temperature and pressure where its parameter are fitted according experiments.

$$r(T, P) = r_0 \left(\frac{p - p_k}{p_0 - p_k} \right)^{\varepsilon_p} \cdot \left(\frac{T - T_{\text{lim}} + (293,15 \text{ K} - T) \cdot 2^{-\frac{1}{\varepsilon_T}}}{293,15 \text{ K} - T_{\text{lim}}} \right)^{\varepsilon_T}$$

pressure temperature

Battery Abuse Simulations in LS-DYNA



Pierre L'Eplattenier, Sarah Bateau-Meyer, Iñaki Çaldichoury,

Battery - Introduction

Dual-Packs

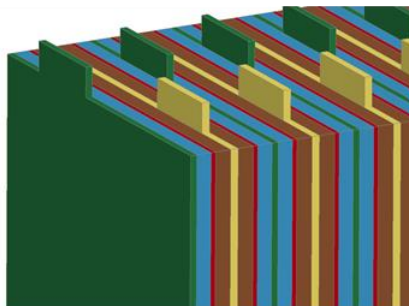
Vehicle



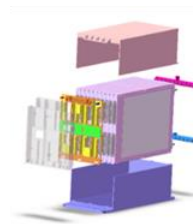
Cell



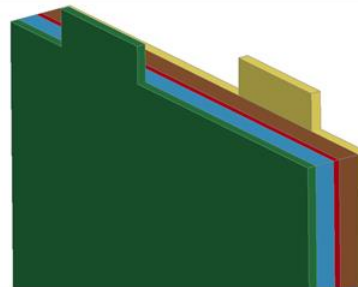
Cell (zoomed in z)



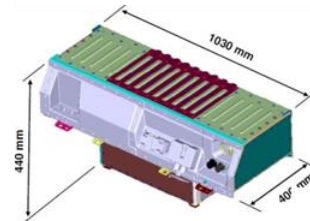
Module



Unit cell (zoomed in z)



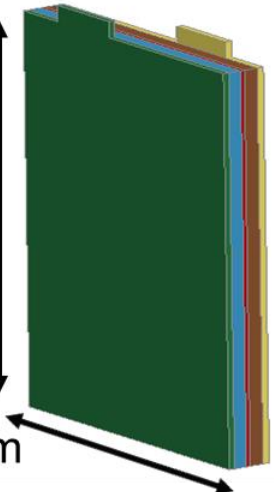
Pack



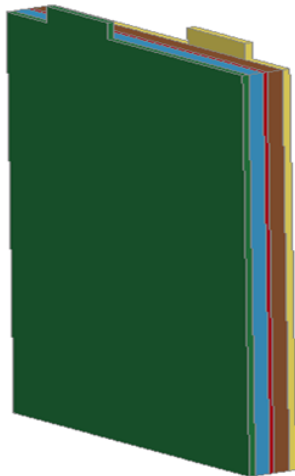
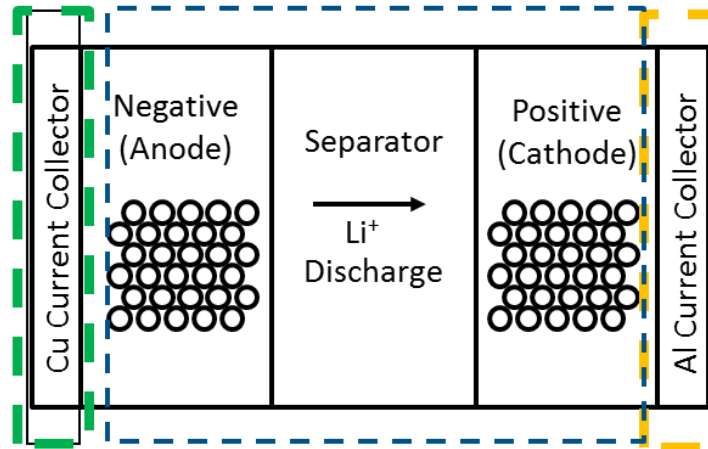
180μm

20cm

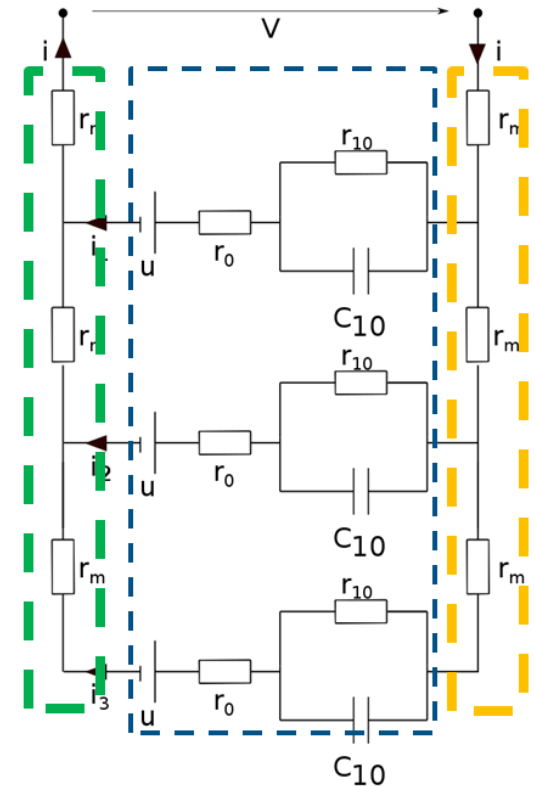
15cm



Battery – Distributed Randles circuit model



- Current collectors transport electrons to/from tabs; modeled by resistive elements
- Jelly roll (anode – separator – cathode) transports Li⁺ ions; modeled with Randle circuit



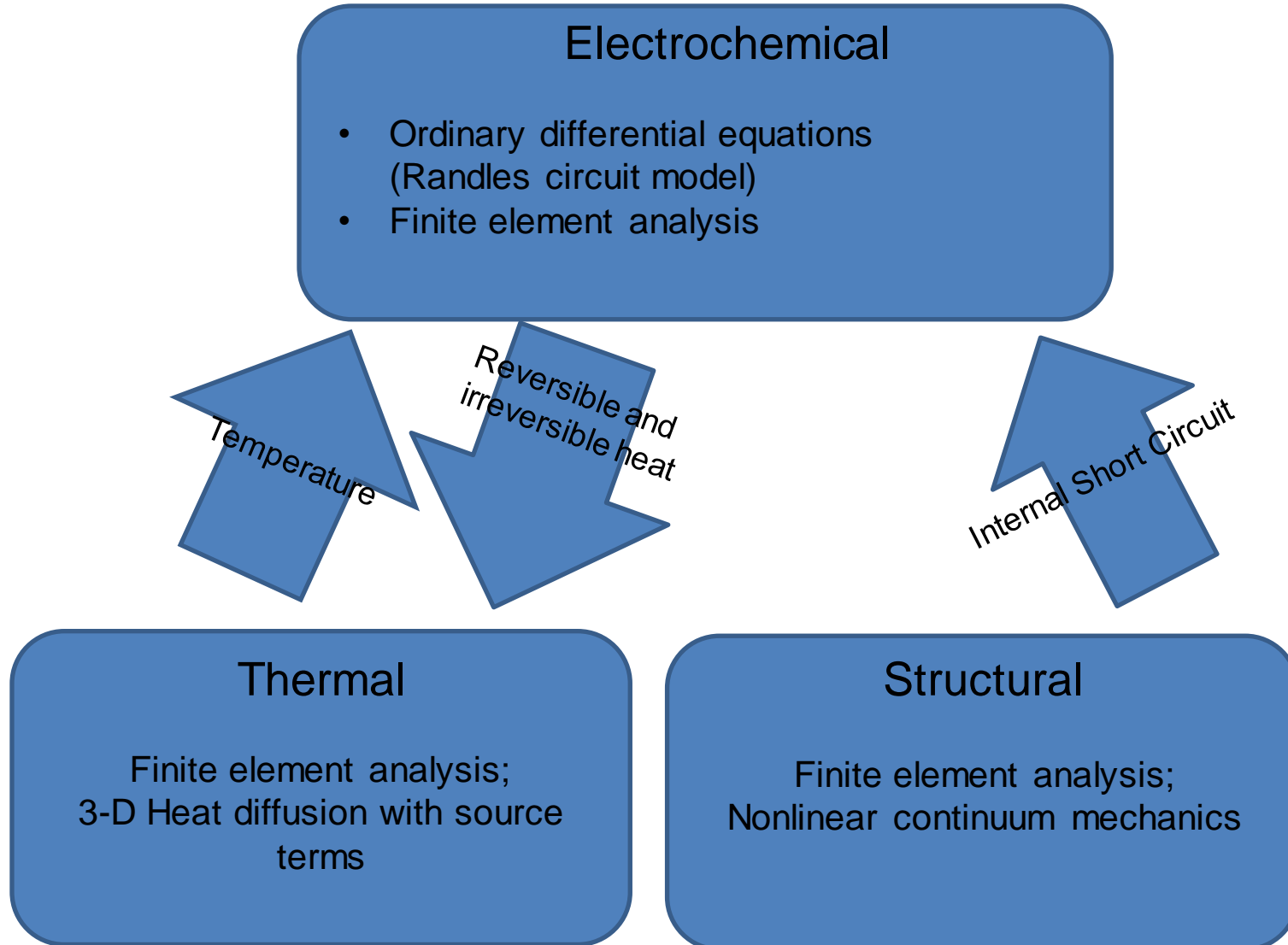
r_0 : Ohmic & kinetic

r_{10} & c_{10} : Diffusion

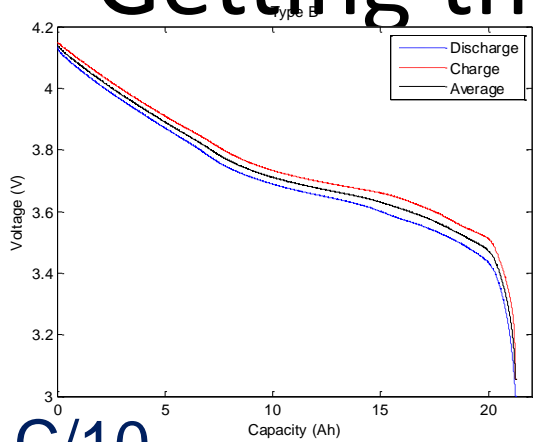
u : Equilibrium voltage (OCV)

r_m : Current collectors

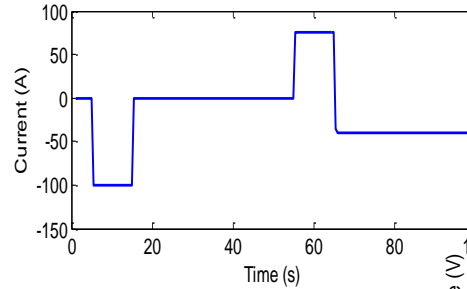
Coupling between the solvers



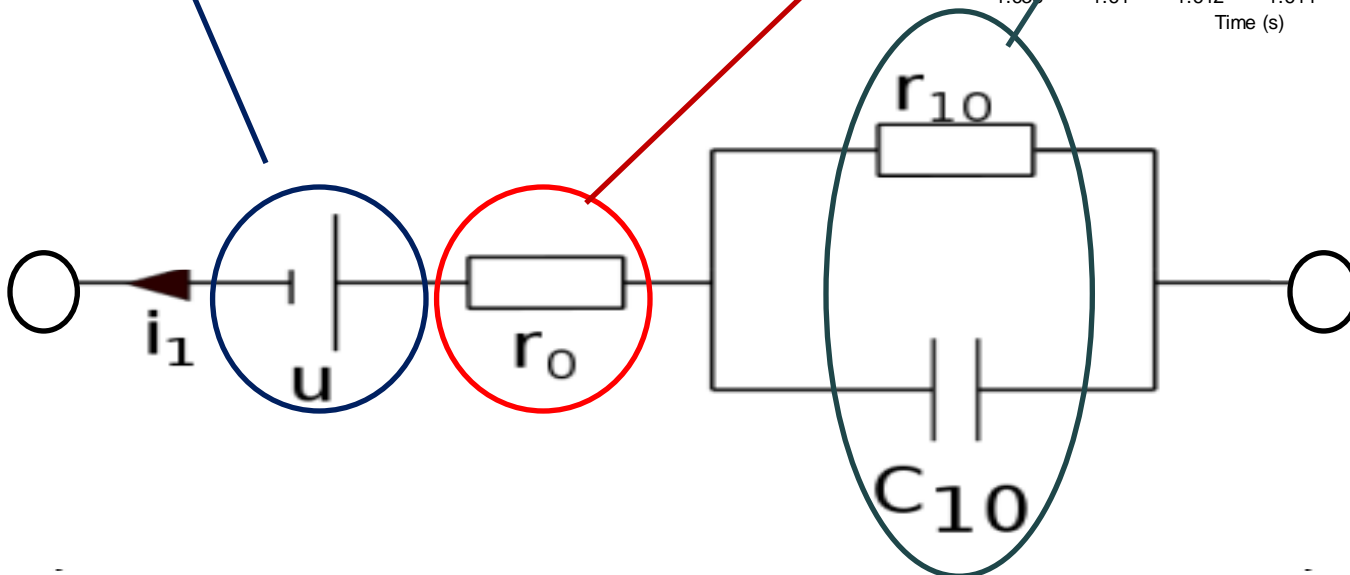
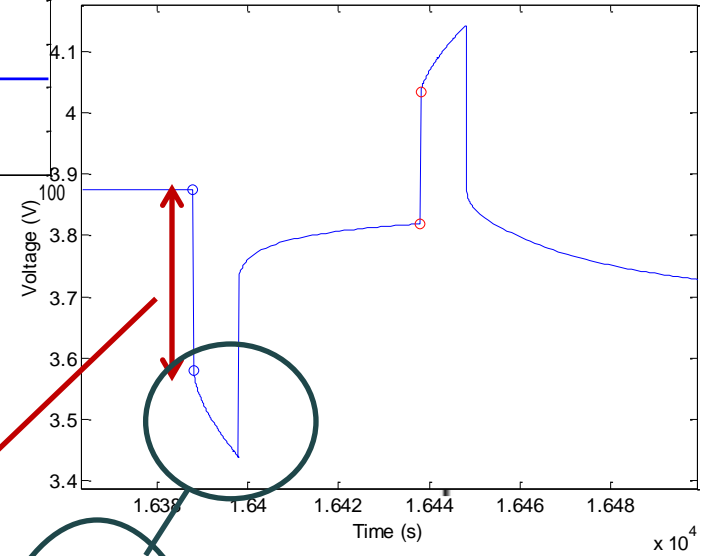
Getting the Randles circuit parameters



C/10
capacity tests

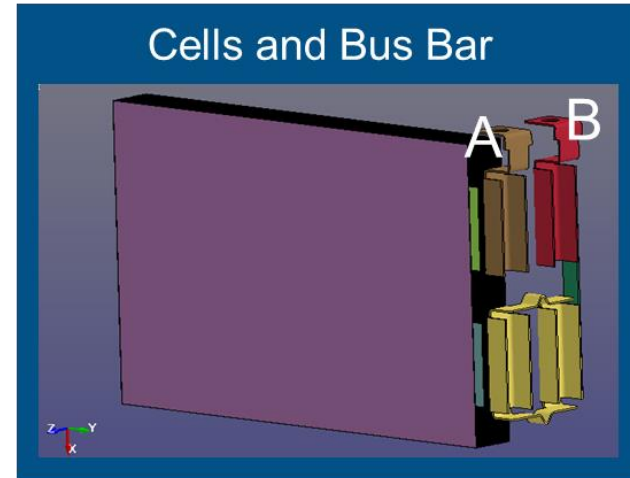
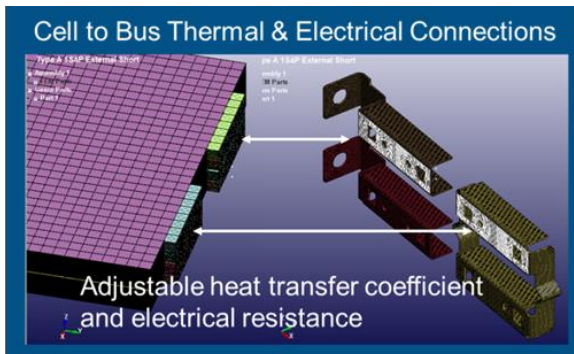


HPPC tests



External short (1)

External short on a cell module



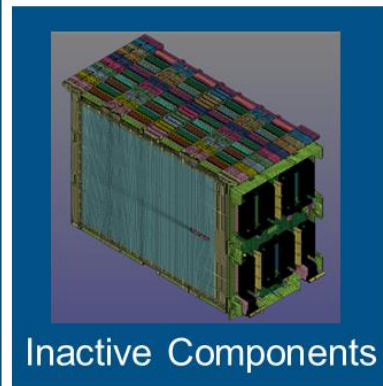
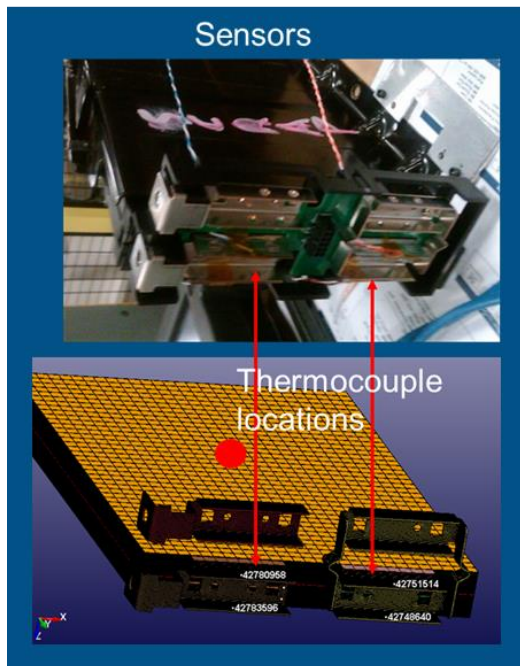
Short circuit resistance applied between A and B creates current pathway

In collaboration with J. Marcicki et al
Ford Research and Innovation Center,
Dearborn, MI, USA



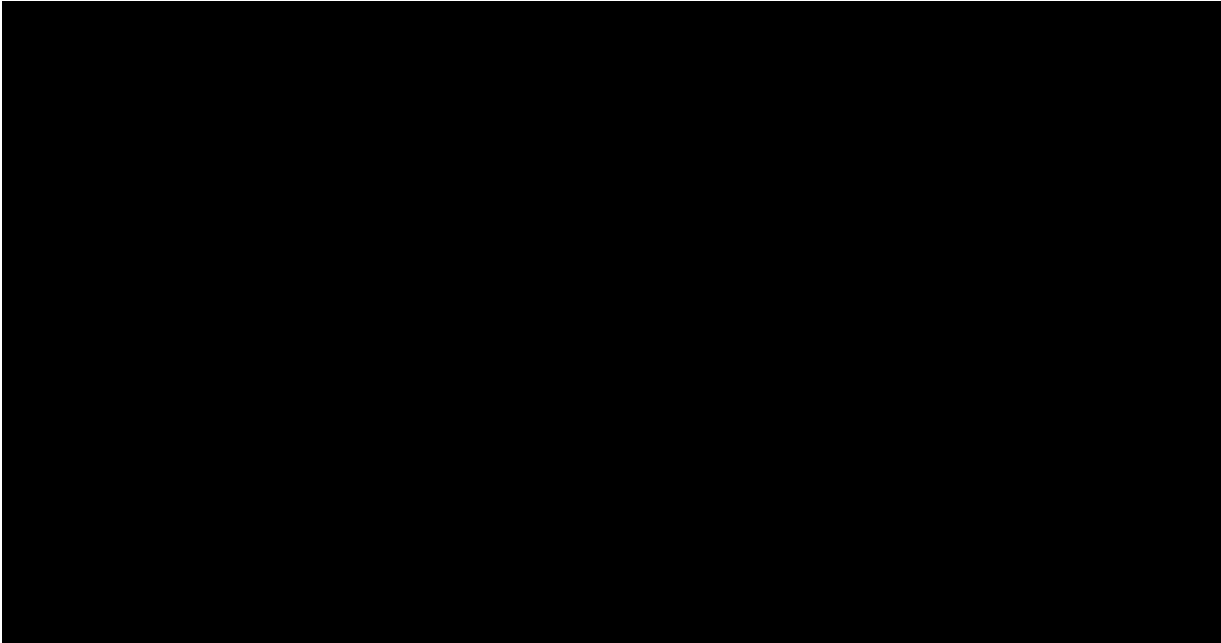
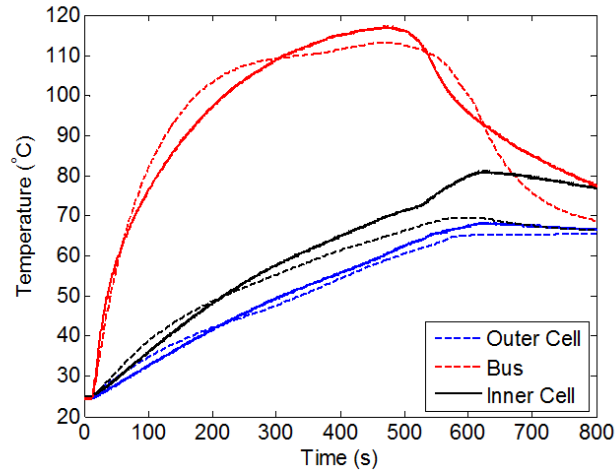
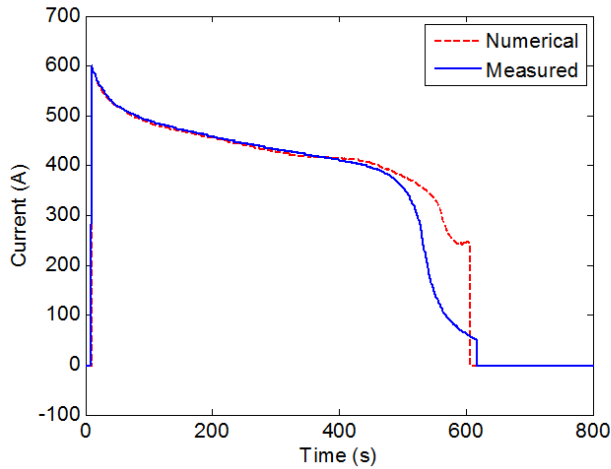
ONE FORD

ONE TEAM • ONE PLAN • ONE GOAL



external short (1):

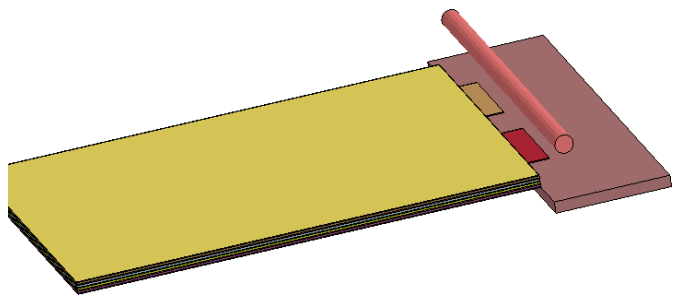
Model Predicted Current versus Experiment (Solid) Model Predicted (Dashed) Temperatures versus Experiment (Solid)



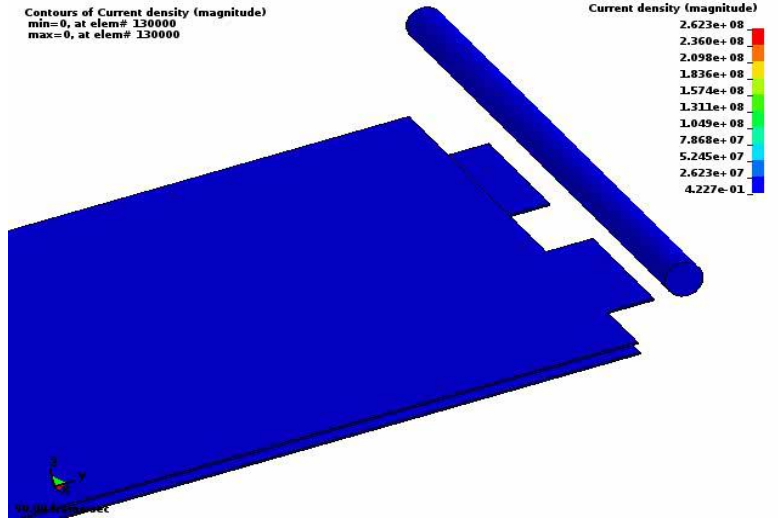
In collaboration with
J. Marcicki et al
Ford Research and
Innovation Center,
Dearborn, MI, USA

External short (2)

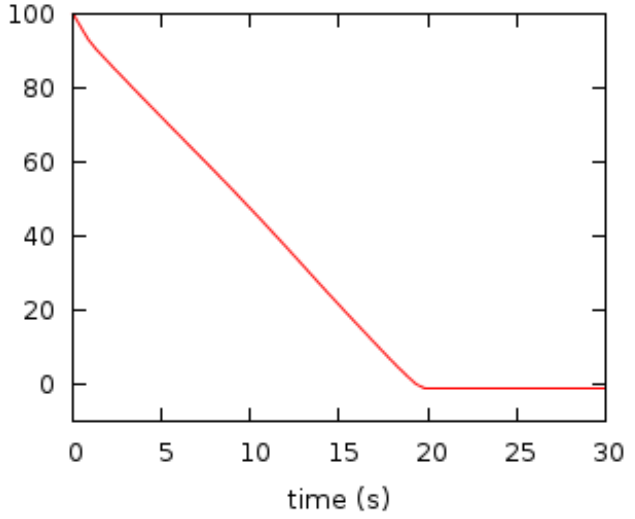
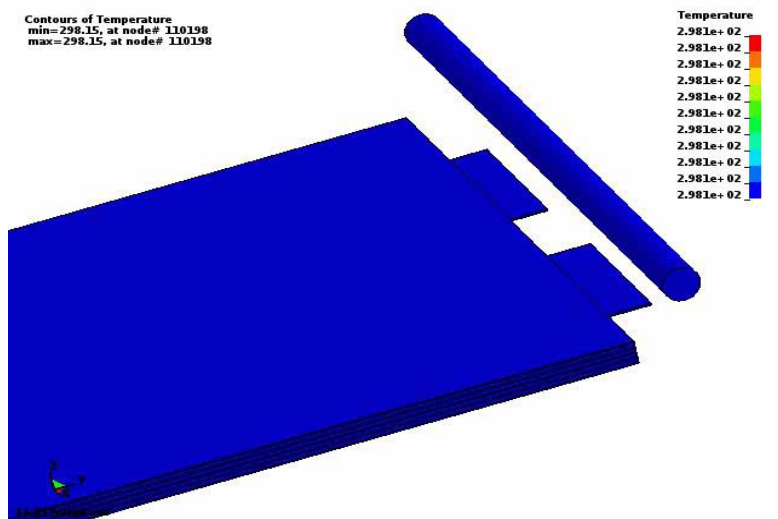
Conducting cylinder falling on the tabs of a cell creates an external short



Current density

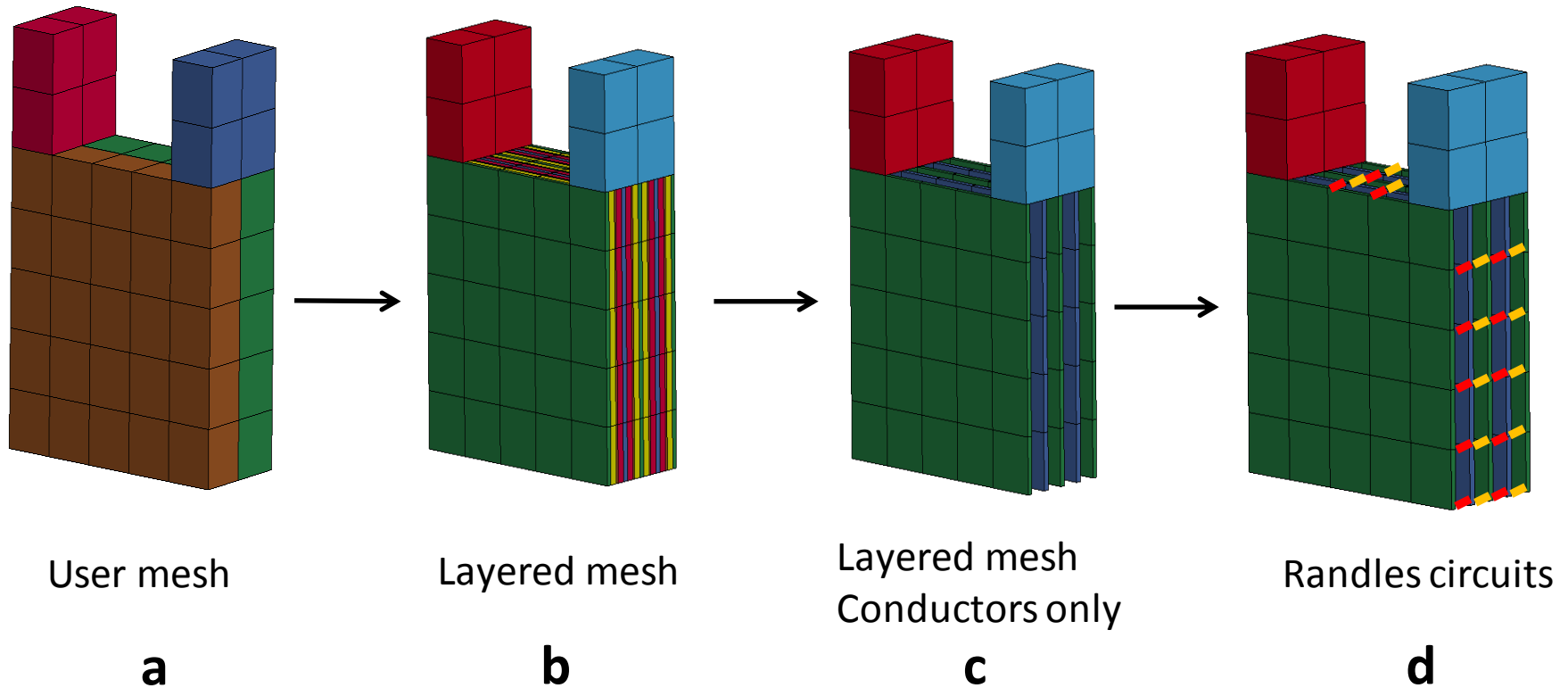


Temperature

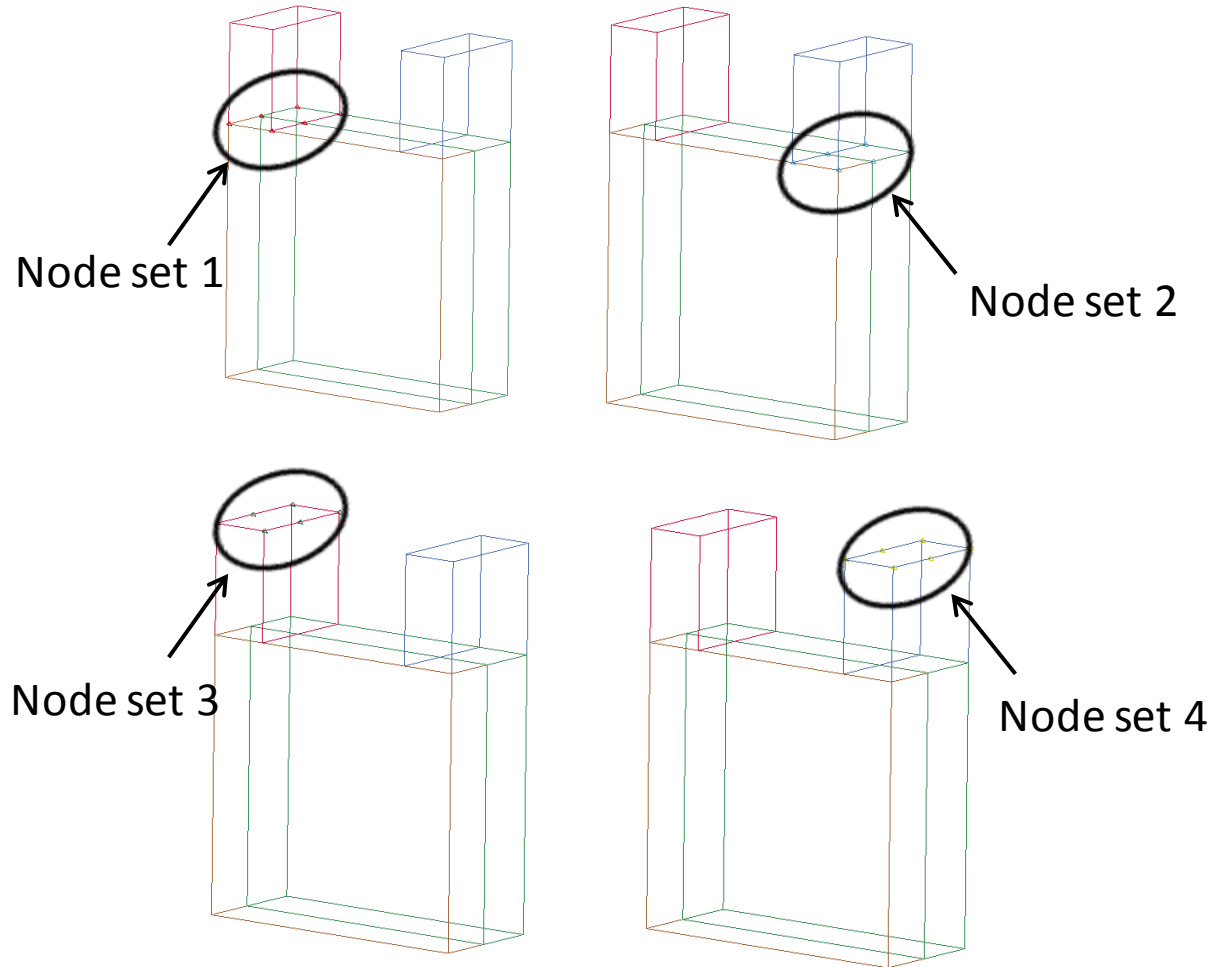
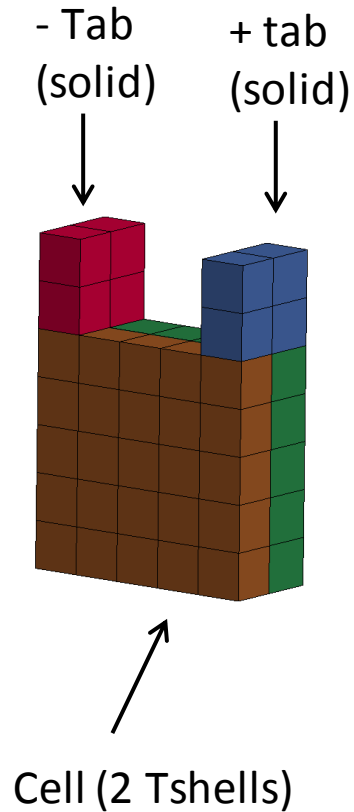


SOC vs time

Randles circuits using Composite Tshells



Composite Tshells: Definition of the node sets



Electrical connections using `*EM_ISOPOTENTIAL` and `*EM_ISOPOTENTIAL_CONNECT`

Composite Tshells: Keyword setup

```
*PART_COMPOSITE_TSHELL
```

```
$# title
Layered_Solid
$# pid elform shrf unused unused hgid unused tshear
   3   5 0.833
$# mid1 thick1 b1 ithid1 mid2 thick2 b2 ithid2
   21  0.225 0.000  0    12  0.325 0.000  0
   9   0.100 0.000  0    16  0.325 0.000  0
   5   0.250 0.000  0    16  0.325 0.000  0
   9   0.100 0.000  0    12  0.325 0.000  0
  21  0.225 0.000  0     0  0.000 0.000  0
```

Layer1:positive current collector

```
*EM_MAT
```

```
$-----1-----2-----3-----4-----5-----6-----7-----8
$ em_mid mtype sigma eosId randletype
   21     2  5.e6      1
   12     1
   9      1
  16     1
   5     2  6.e6
   2     2  1.e6
   4     2  2.e6
```

Layer2:positive electrode

Positive tab

```
*PART_COMPOSITE_TSHELL
```

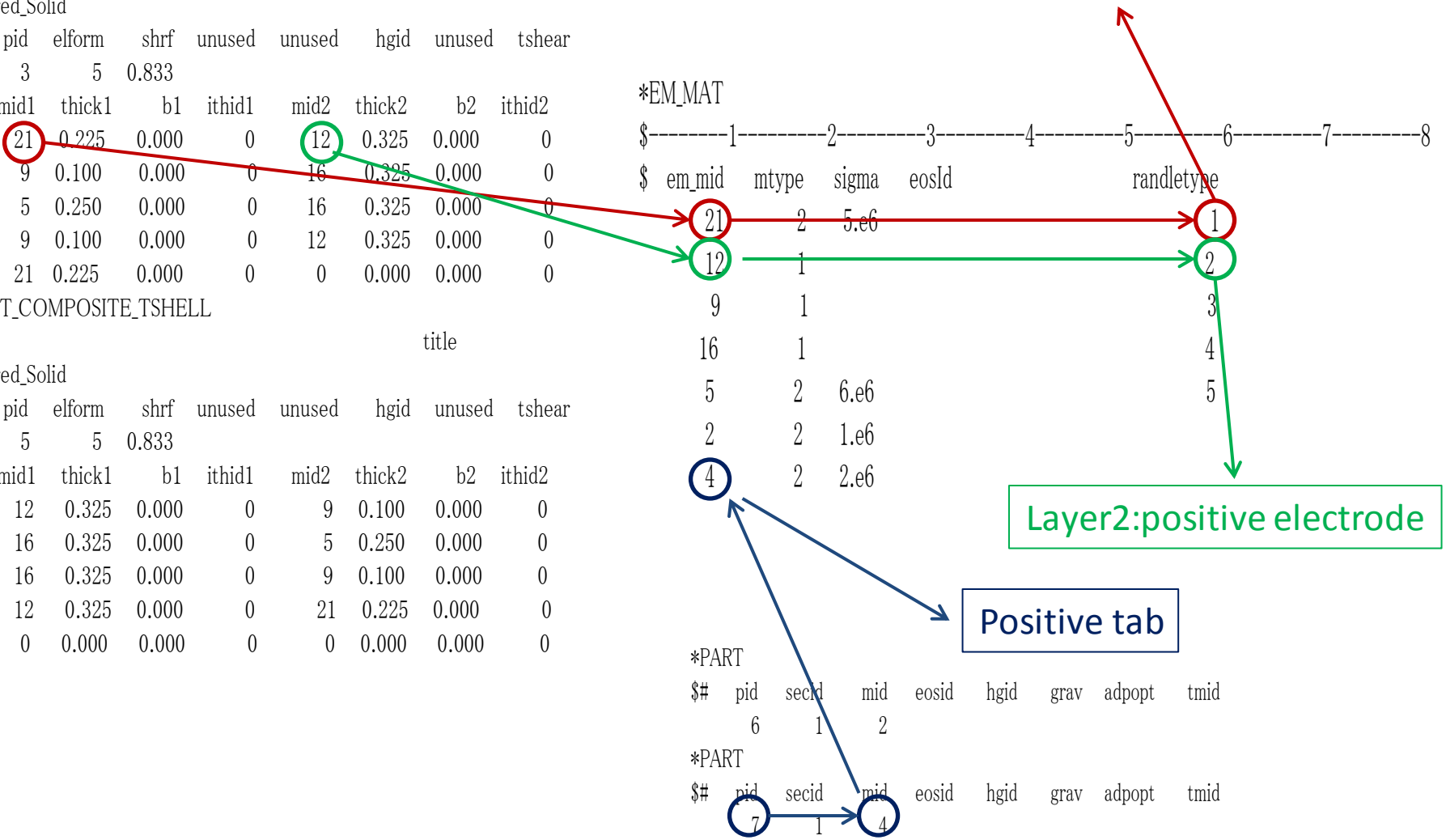
```
$# title
Layered_Solid
$# pid elform shrf unused unused hgid unused tshear
   5   5 0.833
$# mid1 thick1 b1 ithid1 mid2 thick2 b2 ithid2
  12  0.325 0.000  0     9  0.100 0.000  0
  16  0.325 0.000  0     5  0.250 0.000  0
  16  0.325 0.000  0     9  0.100 0.000  0
  12  0.325 0.000  0    21  0.225 0.000  0
   0  0.000 0.000  0     0  0.000 0.000  0
```

```
*PART
```

```
$# pid secid mid eosid hgid grav adpopt tmid
   6   1    2
```

```
*PART
```

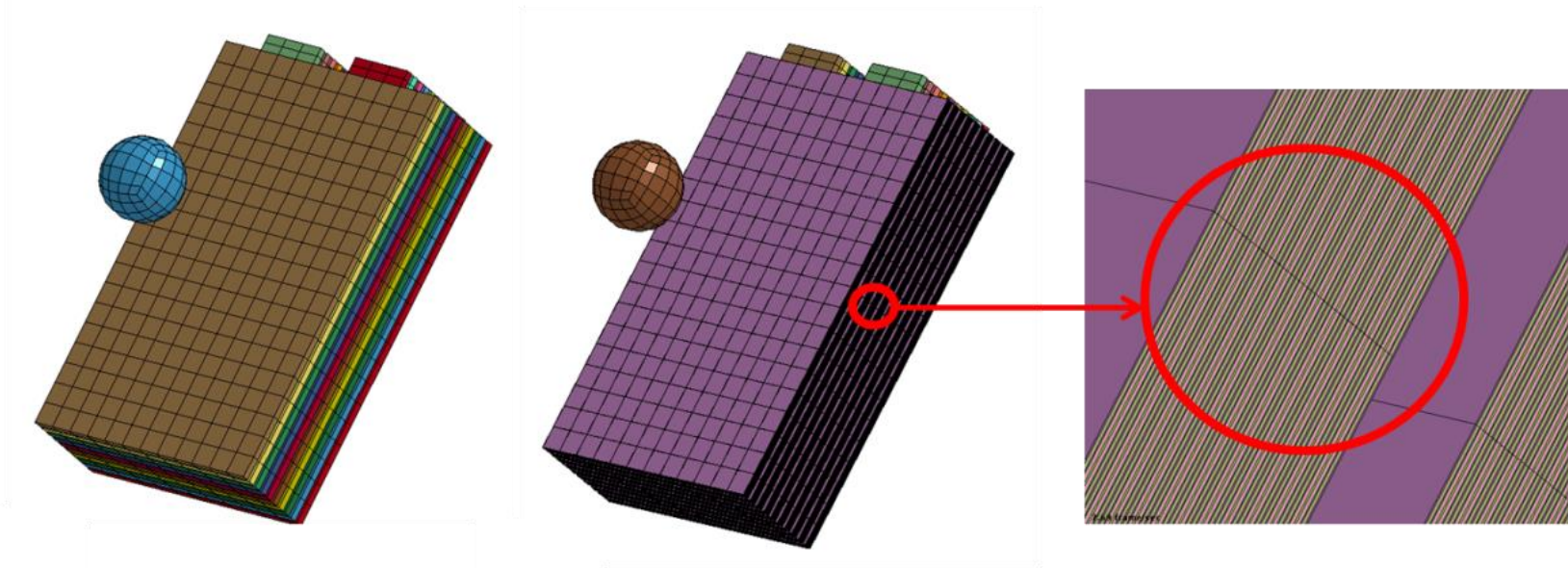
```
$# pid secid mid eosid hgid grav adpopt tmid
   7   1    4
```



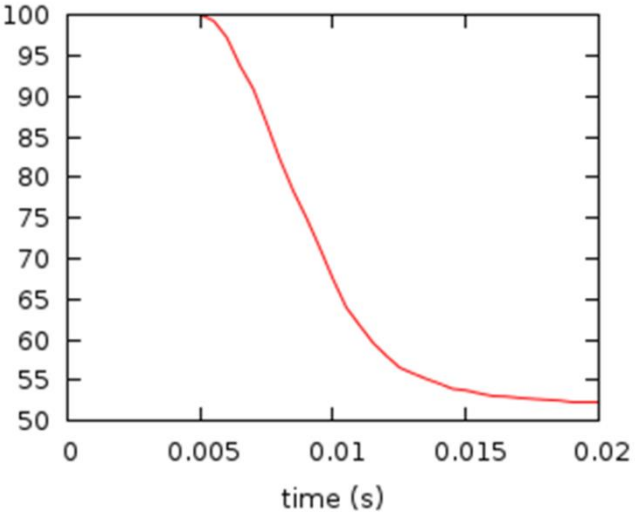
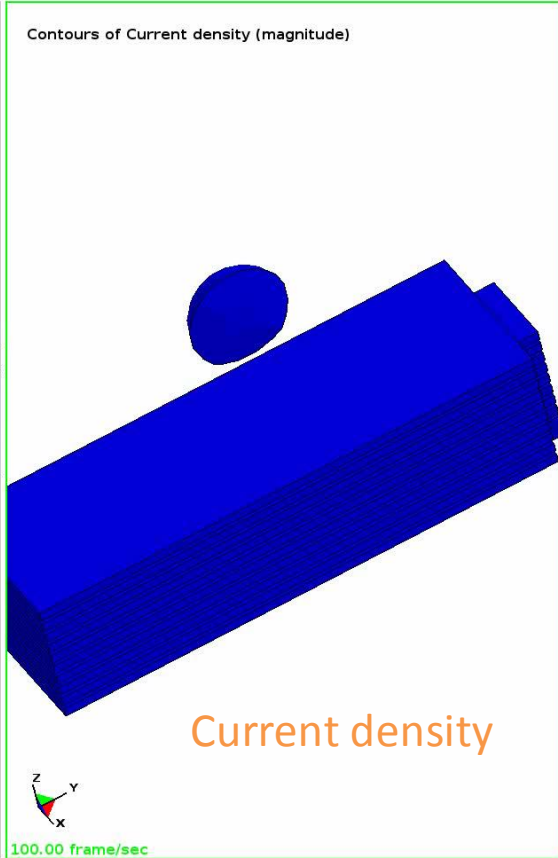
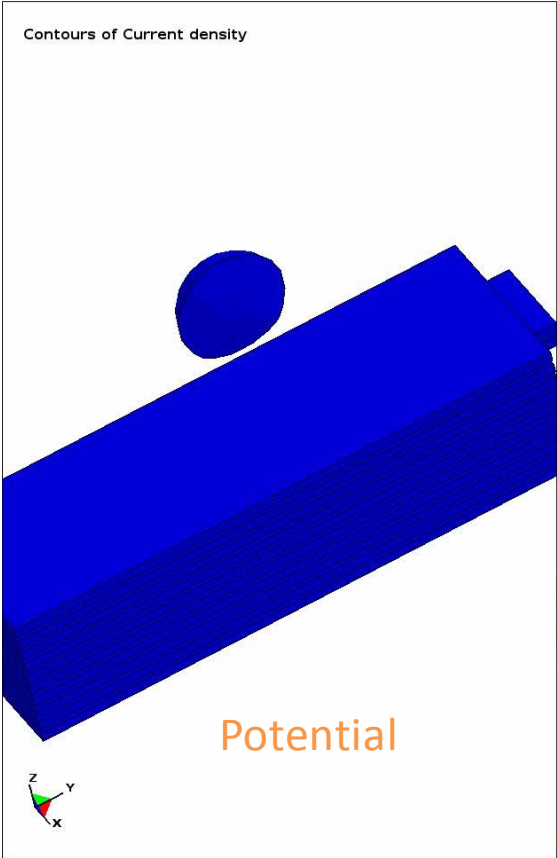
Composite Tshells: Internal short (1)

Module of 10 adjacent cells crushed by a sphere

- Each cell is composed of
 - 228 *ELEMENT_TSHELL
 - 22 unit cells (89 layers)
 - 252 Randles circuit in each *unit* cell
- 55,440 Randles circuit total



Composite Tshells: Internal short (1)



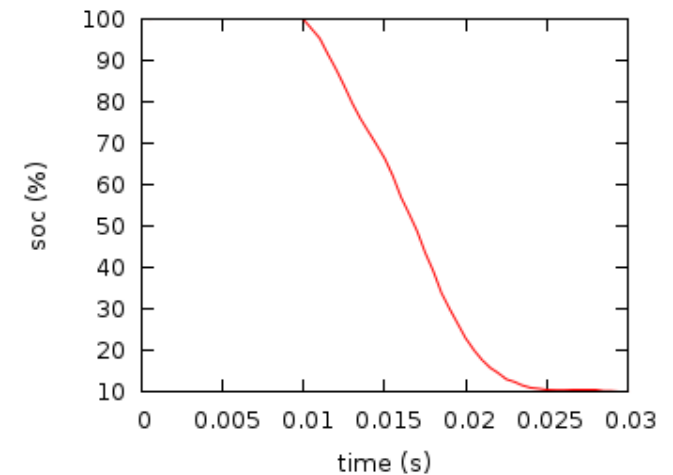
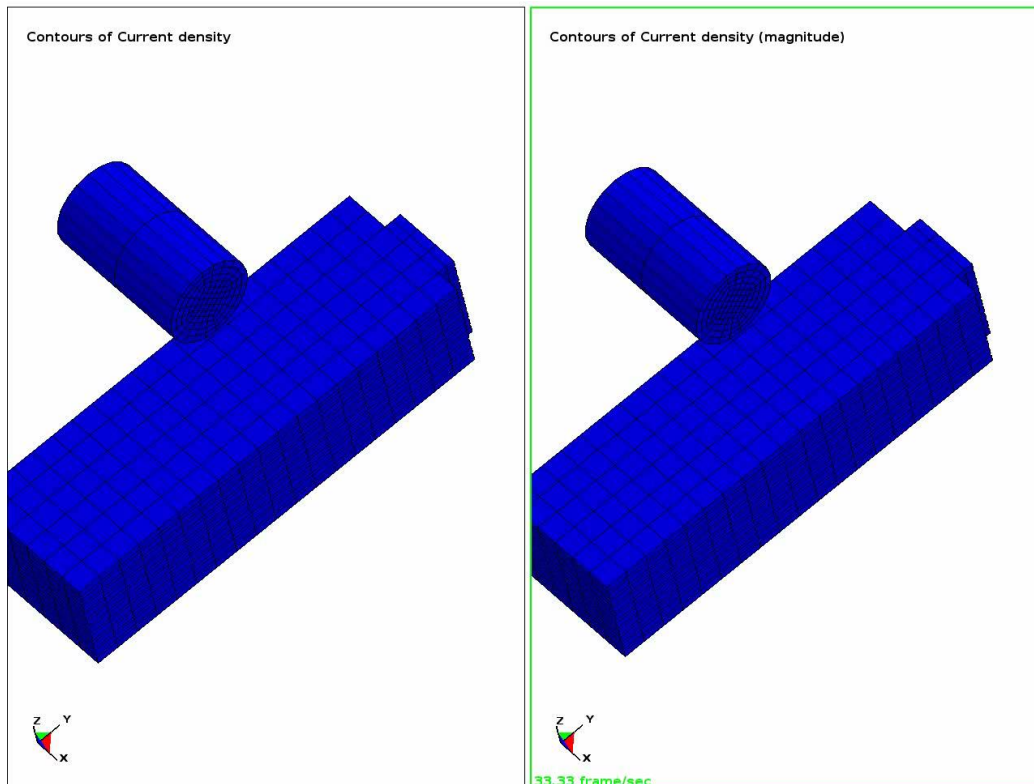
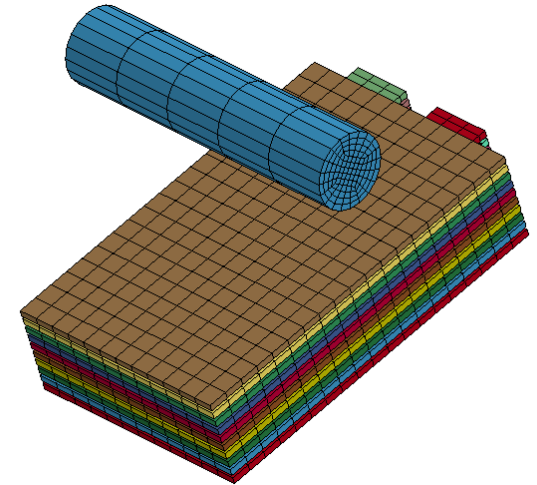
State Of Charge vs time

Composite Tshells: Internal short (2)

Same 10 cells module crushed
by a cylinder

Potential

Current density

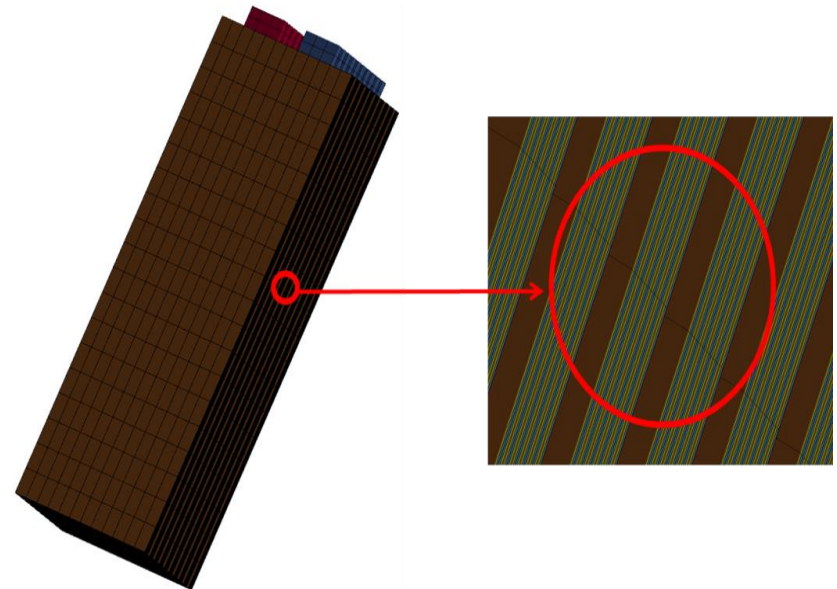
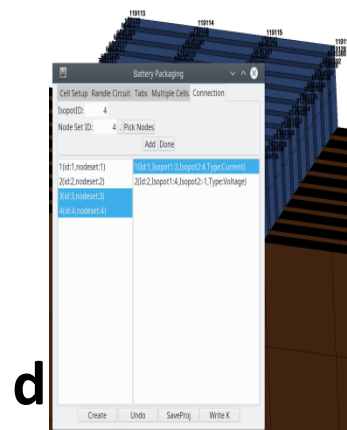
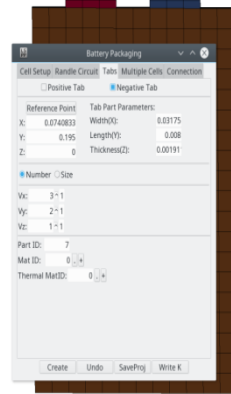
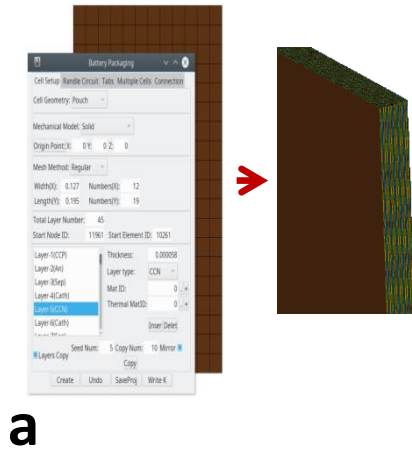


State Of Charge vs time

LS-PREPOST Battery Packaging

Application

- Easy design of the layers of a single cell
- Addition of connecting tabs
- Multiplication of cells to create modules
- Electrical connections



Battery – Plans for the future

- Collaborations with Ford Research and Innovation Center and Oak Ridge National Labs to improve:
 - Mechanical simulations of layered cells
 - Criteria for onset of internal short circuits
 - Setting of internal short resistance
- Development of more macroscopic models for modules and packs
- Addition of new features in LS-PREPOST battery packaging application

Electrophysiology modeling



LSTC
Livermore Software
Technology Corp.

Motivation

- Experimental studies involving the *in-vivo* human heart are possible and often available, but they are expensive and very limited.
- Well defined numerical modeling is emerging as a powerful tool that can help to interpret experimental data.
- Cardiac modeling is a complex problem. The maturity of the models of electrical propagation in the heart is still not comparable with the one achieved in other engineering fields mainly due to :
 - Non linear anisotropic inhomogenous material properties
 - Direct observation of electromechanical potential distribution is not trivial. Validation experimental results are difficult to obtain.
 - The problem not only involves multiphysics but is extremely multi-disciplinary.

Electrophysiological models

The bidomain model : well-established description of the electrical activity of the myocardium on a macroscopic scale, taking into account the ionic current, the membrane potential and the extracellular potential.

The monodomain model : The monodomain model is a simplification of the bidomain equations. It assumes that conductivities are proportional in the intracellular and extracellular spaces

I. Verification of cardiac tissue electrophysiology simulator using LS-DYNA

- **GOAL**
test the **ability** of LS-DYNA for cardiac tissue simulations

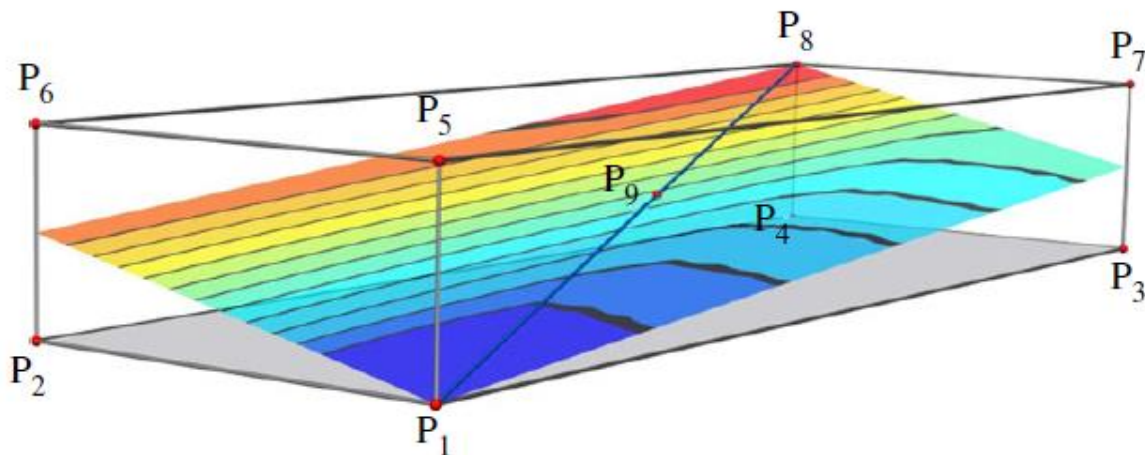
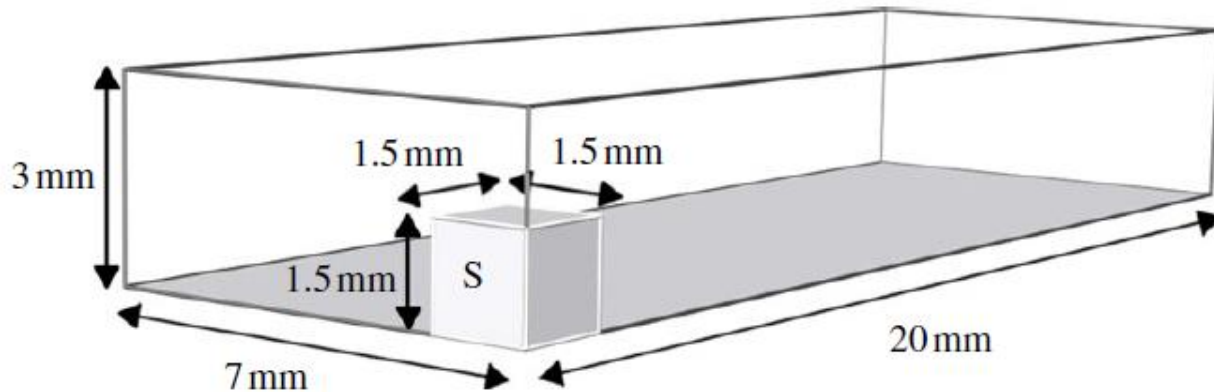
Benchmark:

Verification of cardiac tissue electrophysiology simulator using a N-version benchmark, Philosophical Transactions of the Royal Society A: Mathematical, Physical and Engineering Sciences, vol 369, issue 1954, pp 4331-4351, November 2011

I. Verification of cardiac tissue electrophysiology simulator using LS-DYNA

- **BENCHMARK GOAL**

Cuboid heart sample with stimulus on one corner. We observe the propagation of the potential inside the cell by determining the nodes' activation time.



Activation time
instant where the potential becomes positive

I. Verification of cardiac tissue electrophysiology simulator using LS-DYNA

- **MODEL DEFINITION**

Variable	Description
equations	monodomain
material	transversely isotropic
PDE solver	explicit
cell model	Ten Tusscher & Panfilov
variant	epicardium cell model
numerical integration scheme	Qu-Garfindel Operator Split
mesh type	hexahedral
solution method	finite element
basis function	linear Nedelec elements (FEMSTER)
pre-conditioners	none
matrix solver	hybrid-parallel, multifrontal, sparse direct solver (MF2)
system architecture	Serial or MPP

I. Verification of cardiac tissue electrophysiology simulator using LS-DYNA

• MODEL DEFINITION

$$1 \quad \begin{cases} \beta C_m \frac{\partial V}{\partial t} + \beta I_{ion}(u, V, t) - \nabla \cdot (\sigma \nabla V) = I_{stim}(\vec{x}, t) \\ \frac{\partial u}{\partial t} = f(u, V) \end{cases}$$

monodomain equation

cell model : ten Tusscher & Panfilov ionic equations

V : membrane potential
 t : time
 σ : conductivity tensor
 C_m : membrane capacitance
 β : surface area to volume ration
 I_{stim} : stimulus current, applied at the position \vec{x}
 I_{ion} : single cell ionic current
 u : set of cell-level variables \rightarrow 19 for ten Tusscher model

2

Projection onto the FEM basis functions

$$\beta C_m M \cdot \frac{dV}{dt} + \beta I_{ion} - S \cdot V = I_{stim}$$

$V, I_{stim}, I_{ion} \rightarrow$ nodal vectors
 M : mass matrix $M(i, j) = \int_{\Omega} \Phi_i \Phi_j d\Omega$
 S : stiffness matrix $S(i, j) = \int_{\Omega} \sigma \nabla \Phi_i \cdot \nabla \Phi_j d\Omega$

3

explicit Qu-Garfindel Operator Split

$$V = V_t \quad M \cdot V_{t+1/2} = M \cdot V_t - \frac{dt}{2\beta C_m} S \cdot V_t$$

Integrate diffusion operator for half timestep

$$V = V_{t+1/2} \quad V_{t+1/2}^* \begin{cases} C_m \dot{V} = I(u, V) \\ \frac{du}{dt} = f(u, V) \end{cases}$$

Integrate ionic operator for full timestep

$$V = V_{t+1/2}^* \quad M \cdot V_{t+1} = M \cdot V_{t+1/2}^* - \frac{dt}{2\beta C_m} S \cdot V_{t+1/2}^*$$

Integrate diffusion PDE for half timestep

I. Verification of cardiac tissue electrophysiology simulator using LS-DYNA

• 9 SIMULATIONS

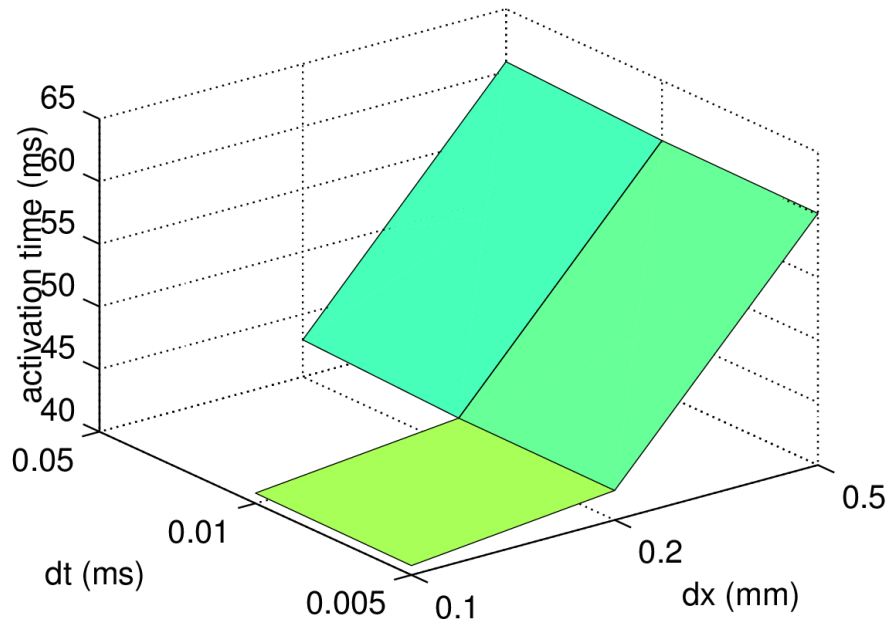
dx (mm)	number of elements	dt (ms)	number of time steps
0.5	3,360	0.05	1,600
0.2	52,500	0.01	8,000
0.1	420,000	0.005	16,000

• RESULTS

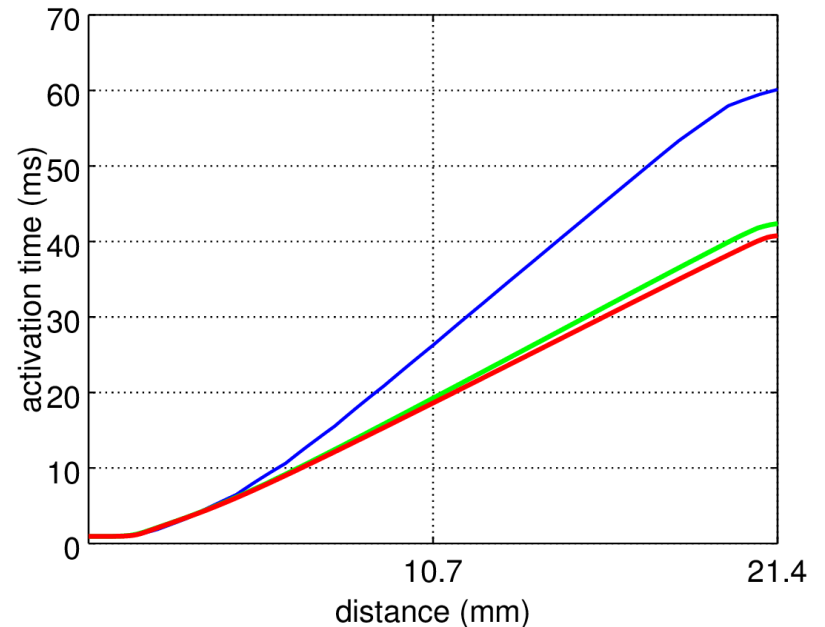
- 8 successful simulations
 - 1 failed simulation :
dx = 0.1 mm with dt = 0.05 ms
- ✗ CFL condition $dt \leq \frac{\beta C_m dx^2}{2\sigma_l \sigma_t} = 0.046$ ms

The results are very similar to the benchmark paper ones

Activation time at P8



Activation time along P1-P8 for dt = 0.05 ms and dx = 0.5 mm, dx = 0.2 mm and dx = 0.1 mm

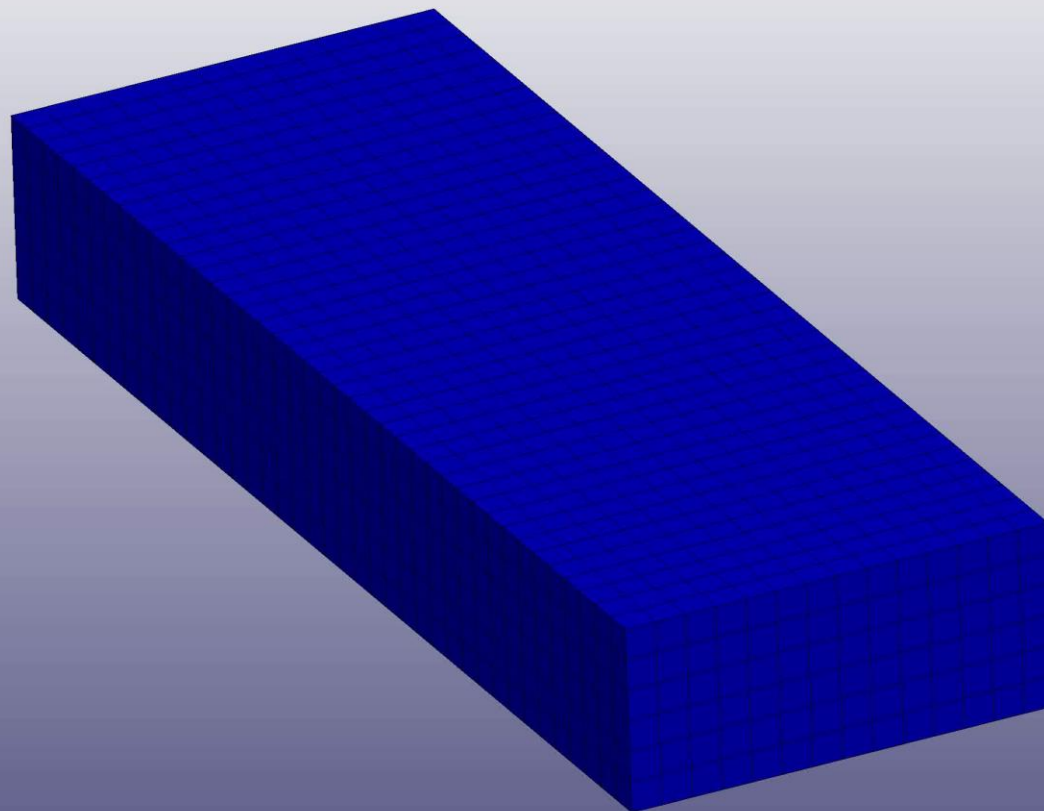


I. Verification of cardiac tissue electrophysiology simulator using LS-DYNA

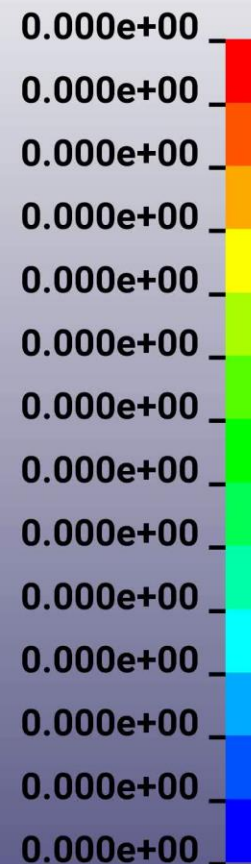
- **ELECTRICAL POTENTIAL PROPAGATION**

LS-DYNA keyword deck by LS-PrePost

Time = 0
Contours of Scalar potential
min=0, at elem# 1
max=0, at elem# 1



Scalar potential



II. Developments

- Introduction of different solvers for the monodomain equations
- Introduction of bidomain model
- Presentation of the cards in LS-DYNA

II. Developments

- TO FACE THE CFL CONDITION

PDE solver

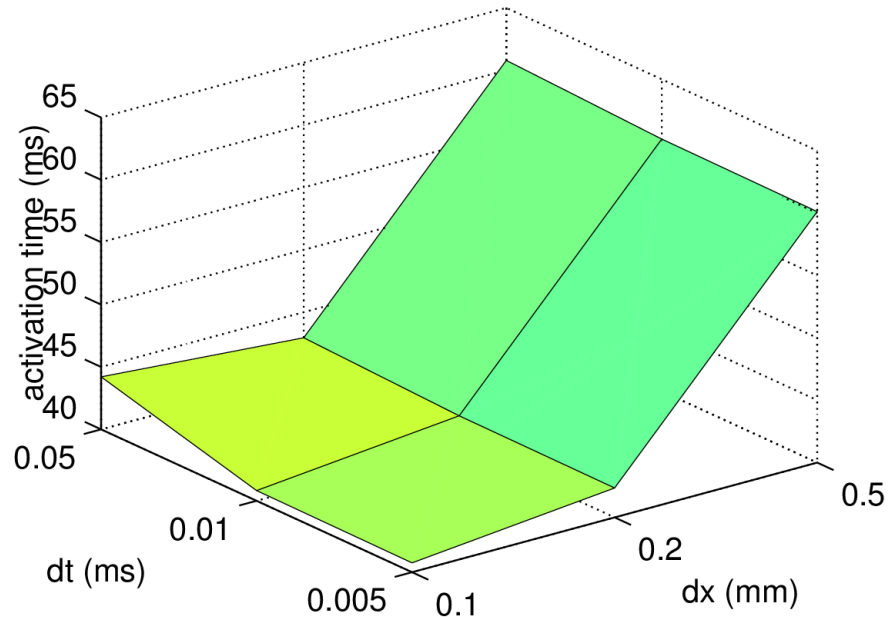
implicit

implicit Qu-Garfindel Operator Split

This term now in the lhs

$$\begin{aligned}
 V = V_t & \quad \left(M + \frac{dt}{2\beta C_m} S\right) \cdot V_{t+1/2} = M \cdot V_t && \text{Integrate diffusion operator for half timestep} \\
 V = V_{t+1/2} & \quad V^*_{t+1/2} \begin{cases} C_m \dot{V} = I(u, V) \\ \frac{du}{dt} = f(u, V) \end{cases} && \text{Integrate ionic operator for full timestep} \\
 V = V^*_{t+1/2} & \quad \left(M + \frac{dt}{2\beta C_m} S\right) \cdot V_{t+1} = M \cdot V^*_{t+1/2} && \text{Integrate diffusion PDE for half timestep}
 \end{aligned}$$

Activation time at P8



II. Developments

- TO GAIN TIME**

numerical integration scheme

Dave's Operator Split

explicit Dave's Operator Split

At even time step

Integrate diffusion operator for one timestep

$$V = V_t \quad M.V_{t+1} = M.V_t - \frac{dt}{2\beta C_m} S.V_t$$

Integrate ionic operator for full timestep

$$V = V_{t+1} \quad V^*_{t+1} \begin{cases} C_m \dot{V} = I(u, V) \\ \frac{du}{dt} = f(u, V) \end{cases}$$

$$\text{Set } V_{t+1} = V^*_{t+1}$$

At odd time step

Integrate ionic operator for full timestep

$$V = V_{t+1} \quad V^*_{t+1} \begin{cases} C_m \dot{V} = I(u, V) \\ \frac{du}{dt} = f(u, V) \end{cases}$$

$$\text{Set } V_{t+1} = V^*_{t+1}$$

Integrate diffusion operator for one timestep

$$V = V_t \quad M.V_{t+1} = M.V_t - \frac{dt}{2\beta C_m} S.V_t$$

Machine time – simulation time = 80 ms (all the runs were done in serial)

Numerical integration scheme	dt1=0.05ms - dx1=0.5mm	dt1=0.05ms - dx3=0.1mm	dt3=0.005ms - dx3=0.1mm
explicit Qu-Garfindel Operator Split	1min14s	X	33h15min30s
explicit Dave's Operator Split	59s	X	24h49min3s
implicit Qu-Garfindel Operator Split	1min12s	3h23min58s	34h40min16s
implicit Dave's Operator Split	58s	2h32min30s	24h53min12s

II. Developments

- TO INCREASE THE ACCURACY**

equations	bidomain
PDE solver	implicit
numerical integration scheme	Spiteri-Ziaratgahi Operator Split

1

$$\begin{cases} \beta C_m \frac{\partial V}{\partial t} + \beta I_{ion}(u, V, t) - \nabla \cdot (\sigma_i \nabla V) - \nabla \cdot (\sigma_i \nabla u_e) = I_{stim}(\vec{x}, t) \\ \nabla \cdot (\sigma_i \nabla V) + \nabla \cdot ((\sigma_i + \sigma_e) \nabla u_e) = 0 \\ \frac{\partial u}{\partial t} = f(u, V) \end{cases}$$

bidomain equations

u_e : extracellular potential
 σ_i : intracellular conductivity tensor
 σ_e : extracellular conductivity tensor

2

Projection onto the FEM basis functions

$$\begin{aligned} \beta C_m M \cdot \frac{dV}{dt} + \beta I_{ion} - S_i \cdot V - S_i \cdot U_e &= I_{stim} \\ S_i \cdot V + S_{ie} \cdot U_e &= 0 \end{aligned}$$

$V, U_e, I_{stim}, I_{ion} \rightarrow$ nodal vectors
 2 stiffness matrices $S_i(i, j) = \int_{\Omega} \sigma_i \overline{\nabla \Phi_i} \cdot \overline{\nabla \Phi_j} d\Omega$
 $S_{ie}(i, j) = \int_{\Omega} (\sigma_i + \sigma_{ie}) \overline{\nabla \Phi_i} \cdot \overline{\nabla \Phi_j} d\Omega$

3

implicit Spiteri-Ziaratgahi Operator Split

$$\begin{aligned} u_{t+1} &= u_t + dt f(u_t, V_t, t) \\ \begin{bmatrix} \frac{\beta C_m}{dt} M + S_i & S_i \\ S_i & S_{ie} \end{bmatrix} \cdot \begin{bmatrix} V_{t+1} \\ U_{e, t+1} \end{bmatrix} &= \begin{bmatrix} \frac{\beta C_m}{dt} M \cdot V_t - \beta M \cdot I_{ion}(u_{t+1}, V_t, t) \\ 0 \end{bmatrix} \end{aligned}$$

solved using a PCG method, where the preconditioner is the diagonal line of the matrix, or with the hybrid-parallel, multifrontal, sparse direct solver, MF2

cell model	Purkinje
------------	----------

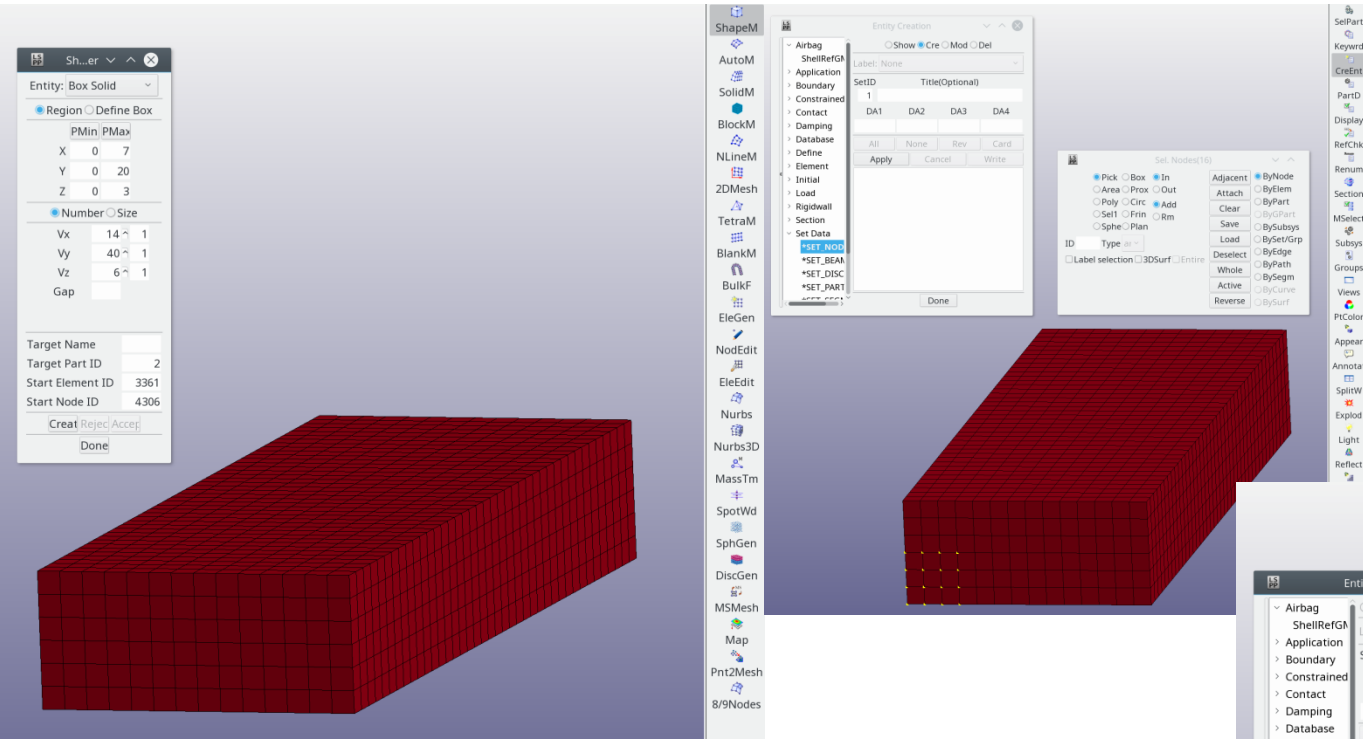
III. Creation of a model

III. Creation of a model

- LS-PREPOST**

1 Build a mesh

2 Select the nodes where the stimulus is applied

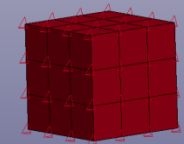
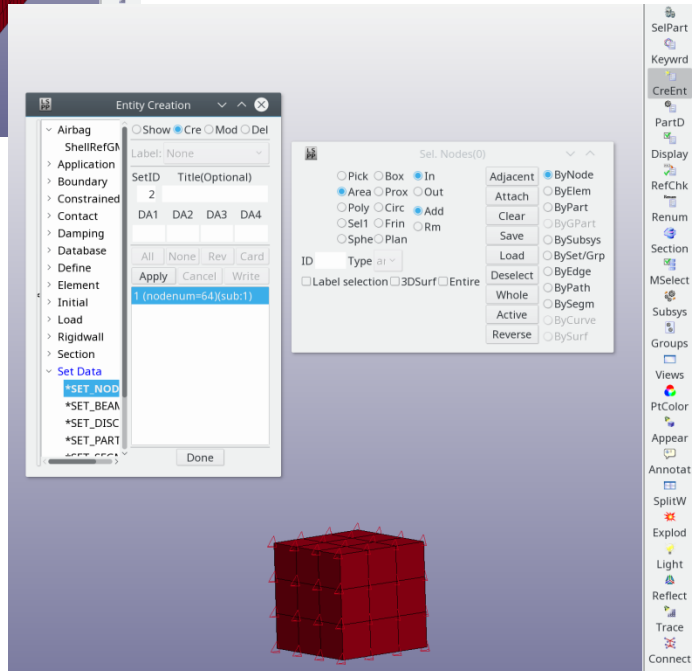


Mode → CreEntity → Set Data
→ Set Nodes → Create

Sel. Nodes window : Pick ByNode
Apply

To select nodes inside the solid

- Blank the unwished elements with EleTools → Blank → Element Sel. Elem. window : Pick or Area ByElem Apply
- Create the nodes set using Sel. Nodes window : Area ByNode



III. Creation of a model

- INPUT DECK – MECHANIC (for now, i.e. for pure EP model without mechanical coupling)

```
*KEYWORD
*INCLUDE
mesh.k
$ *****
$ MECHANIC
$ *****
*CONTROL_TERMINATION
$-----1-----2-----3-----4-----5-----6-----7-----8
$   endtim
$       80.
*CONTROL_TIMESTEP
$-----1-----2-----3-----4-----5-----6-----7-----8
$   dtinit                                lctm
$       0.05                                3
*DEFINE_CURVE
3
0.,0.05
10.,0.05
*DATABASE_BINARY_D3PLOT
$-----1-----2-----3-----4-----5-----6-----7-----8
$   dt
$       0.2
*PART
$-----1-----2-----3-----4-----5-----6-----7-----8
cellule
$   pid      secid      matid      eosid      hgid      grav      adpopt      tmid
$       1          1          1          eosid      hgid      grav      adpopt      tmid
*SECTION_SOLID
$-----1-----2-----3-----4-----5-----6-----7-----8
$   sid      elform
$       1          1
*MAT_ELASTIC
$-----1-----2-----3-----4-----5-----6-----7-----8
$   matid      ro      E      pr
$       1      8928.57  200.e+09  .3
```

III. Creation of a model

- INPUT DECK – ELECTROMAGNETISM for MONODOMAIN**

```

$ *****
$ ELECTROMAGNETIC
$ *****
*EM_CONTROL
$-----1-----2-----3-----4-----5-----6-----7-----8
$  emsol      numls  emdtinit  emdtmax  emtinit  emtend  ncyclFem  ncyclBem
$  11         1      0.05
*EM_SOLVER_FEM
$-----1-----2-----3-----4-----5-----6-----7-----8
$  relTol  maxIter  solveType  precondition  uselast
$  1.e-6   10000    1           2             1
*EM_MAT_003
$-----1-----2-----3-----4-----5-----6-----7-----8
$  matid    mtype  sigmaXX  sigmaYY  sigmaZZ  beta    Cm
$  1        2      1.7606e-51.33418e-4 1.7606e-5 0.14    0.01
$-----1-----2-----3-----4-----5-----6-----7-----8
$  sigmaXY  sigmaXZ  sigmaYX  sigmaYZ  sigmaZX  sigmaZY  AOPT
$                                     2.
$-----1-----2-----3-----4-----5-----6-----7-----8
$  XP      YP      ZP      A1      A2      A3      MACF
$                                     0      0      1
$-----1-----2-----3-----4-----5-----6-----7-----8
$  V1      V2      V3      D1      D2      D3
$                                     0      -1     0
    
```

emsol 11 → **monodomain** equations
 numerical integration scheme:
 numls 1 → explicit Qu-Garfindel
 2 → implicit Qu-Garfindel
 3 → explicit Dave
 4 → implicit Dave

emsol = 11 → ***EM_MAT_003** Definition of 1 conductivity tensor e.g. $\sigma = \begin{bmatrix} 0.017606 & 0 & 0 \\ 0 & 0.133418 & 0 \\ 0 & 0 & 0.017606 \end{bmatrix}$ in $S.m^{-1}$

The conductivity is more important along the direction Y, which represents the fiber length.

III. Creation of a model

- INPUT DECK – ELECTROMAGNETISM for BIDOMAIN**

```

$ *****
$ ELECTROMAGNETIC
$ *****
*EM_CONTROL
$-----1-----2-----3-----4-----5-----6-----7-----8
$  emsol      numts  emdtinit  emdtmax  emtinit  emtend  nyclFem  nyclBem
$   12        2      &dt                50000
*EM_SOLVER_FEM
$-----1-----2-----3-----4-----5-----6-----7-----8
$  relTol    maxIter solveType  precondition  uselast
$  1.e-6     10000    1          2            1
*EM_MAT_005
$-----1-----2-----3-----4-----5-----6-----7-----8
$  intramid  mtype  sigmaXX  sigmaYY  sigmaZZ  beta  Cm
$   1         2  0.019e-3  0.17e-3  0.019e-3  0.14  0.01
$-----1-----2-----3-----4-----5-----6-----7-----8
$  sigmaXY  sigmaXZ  sigmaYX  sigmaYZ  sigmaZX  sigmaZY
$-----1-----2-----3-----4-----5-----6-----7-----8
$  extramid  sigmaXXb  sigmaYYb  sigmaZZb
$   1         0.24e-3  0.62e-3  0.24e-3
$-----1-----2-----3-----4-----5-----6-----7-----8
$  sigmaXYb  sigmaXZb  sigmaYXb  sigmaYZb  sigmaZXb  sigmaZYb
$-----1-----2-----3-----4-----5-----6-----7-----8
$#  AOPT      XP      YP      ZP      A1      A2      A3      MACF
$      0      0      1
$-----1-----2-----3-----4-----5-----6-----7-----8
$#  V1      V2      V3      D1      D2      D3
$      0      -1      0

```

emsol 12 → bidomain equations

numerical integration scheme:

numls 1 → implicit Spiteri-Ziaratgahi

where the preconditioner is the diagonal line of the matrix

numls 2 → implicit Spiteri-Ziaratgahi

with the hybrid-parallel, multifrontal, sparse direct solver, MF2 (**faster**)

emsol = 12 →

***EM_MAT_005**

Definition of 2 conductivity tensors σ_i and σ_e

III. Creation of a model

- INPUT DECK –
CELL MODEL VARIABLES

*EM_EP_TENTUSSCHER

Variables linked to a material id

```

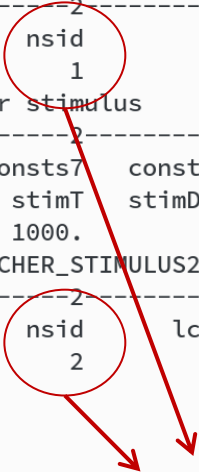
*EM_EP_TENTUSSCHER
$-----1-----2-----3-----4-----5-----6-----7-----8
$   matid
$   1
$ CONSTS
$-----1-----2-----3-----4-----5-----6-----7-----8
$ const1  const2  const3  const4  const5  const52  const53  const10
$   R      T      F      Cm      Vc      Vsr      Vss      p_KNa
$ 8314.472 31096485.3415 0.185 0.016404 0.0010940.00005468 0.03
$-----1-----2-----3-----4-----5-----6-----7-----8
$ const11 const12 const13
$   K_o    Na_o    Ca_o
$   5.4    140.    2.
$-----1-----2-----3-----4-----5-----6-----7-----8
$ const14 const15 const16 const17 const18 const19 const20 const21
$   g_K1   g_Kr   g_Ks   g_Na   g_bNa   g_CaL   g_bCa   g_to
$   5.405  0.153  0.392  14.838  0.0002  0.0000398 0.000592  0.294
$ const31 const33
$   g_pCa   g_pK
$   0.1238  0.0146
$-----1-----2-----3-----4-----5-----6-----7-----8
$ const22 const23 const24 const25 const26 const27 const28 const29
$   P_NaK   K_mK   K_mNa   k_NaCa  ksat   alpha   gamma   Km_Ca
$   2.724   1.     40.     1000.   0.1    2.5    0.35   1.38
$ const30 const32
$   Km_Nai   K_pCa
$   87.5     0.0005
$-----1-----2-----3-----4-----5-----6-----7-----8
$ const34 const35 const36 const37 const38 const39 const40
$   k1'     k2'     k3      k4      EC      max_sr  min_sr
$   0.15    0.045  0.06    0.005   1.5    2.5    1.
$ const41 const44 const42 const45 const43
$   V_rel   V_leak  V_xfer  Vmax_up K_up
$   0.102   0.00036 0.0038  0.006375 0.00025
$ const46 const47 const48 const49 const50 const51
$   Buf_c   K_buf_c  Buf_sr  K_buf_sr Buf_ss  K_buf_ss
$   0.2     0.001   10.     0.3     0.4    0.00025
$ INIT STATES
$-----1-----2-----3-----4-----5-----6-----7-----8
$ states1 states2 states3 states4 states5 states6 states7 states19
$   V      K_i    Na_i    Ca_i    Ca_ss   Ca_sr   R'
$  -85.23  136.89  8.604  0.000126 0.00036  3.64   0.9073
$-----1-----2-----3-----4-----5-----6-----7-----8
$ states5 states6 states7 states8 states9 states10 states12 states13
$   xr1    xr2    xs     m      h      j      d      f
$   0.00621 0.4712 0.0095 0.00172 0.7444  0.7045  3.373e-5 0.7888
$ states14 states15 states16 states17
$   f2     fCass  s      r
$   0.9755 0.9953 0.999998 2.42e-8

```

III. Creation of a model

- INPUT DECK - STIMULUS**

```
*EM_EP_TENTUSSCHER_STIMULUS
$-----1-----2-----3-----4-----5-----6-----7-----8
$ stimid      nsid
   1          1
$ constants for stimulus
$-----1-----2-----3-----4-----5-----6-----7-----8
$ const6      const7      const8      const9
$stimStart    stimT      stimDur      stimAmp
   0.         1000.       2.         50.
*EM_EP_TENTUSSCHER_STIMULUS2
$-----1-----2-----3-----4-----5-----6-----7-----8
$ stimid      nsid      lcid
   2          2         33
*DEFINE_CURVE
33
0.,50.
2.,50.
2.1,0.
10.,0.
10.1,50.
12.,50.
12.1,0.
20.,0.
```



Node set id where stimulus is applied

*EM_EP_TENTUSSCHER_STIMULUS

- Definition of :
- the starting time
 - the period
 - the duration
 - the amplitude

*EM_EP_TENTUSSCHER_STIMULUS2

Stimulus loaded by a load curve representing stimulus amplitude vs time

III. Creation of a model

- ELECTRICAL POTENTIAL PROPAGATION - 2 STIMULUS**

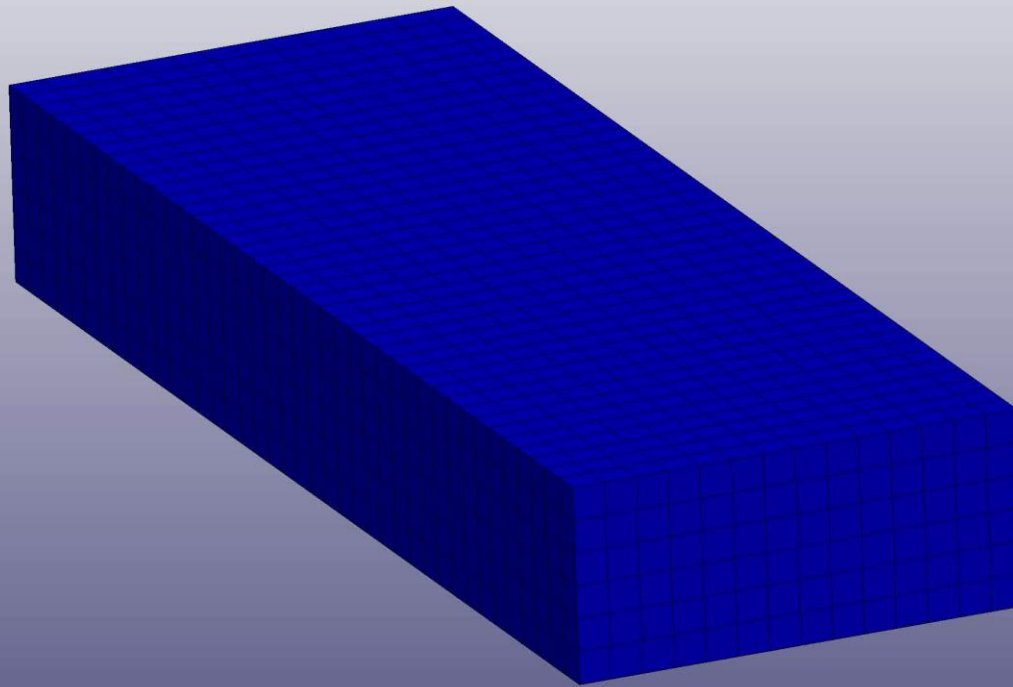
LS-DYNA keyword deck by LS-PrePost

Time = 0

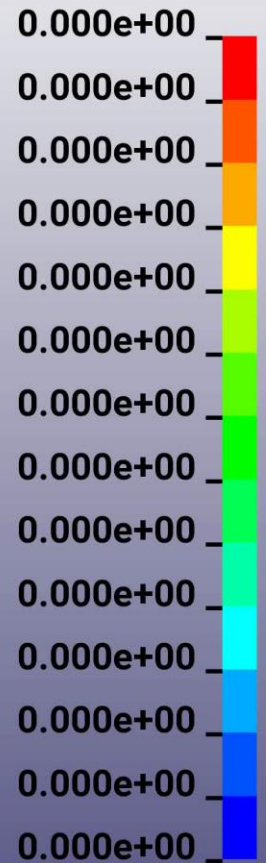
Contours of Scalar potential

min=0, at elem# 1

max=0, at elem# 1



Scalar potential



CONCLUSION

- Different EP models in LS-DYNA, for both monodomain and bidomain equations
- The ten-Tusscher cell model has been introduced
- They give good results on the first benchmark tests
- These models are available to the users through new cards
- More cell models will be added in the future

- What should be the priorities on pure EP?
 - Other cell models (Purkinje, ...) ?
 - Introduce fractal Purkinje network ?
 - Try runs with many elements ?
 - Try runs with models closer to full heart with different cell models ?

- We are interested in the APD restitution results and whether more developments are needed to simulate tachycardia and fibrillation

